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Bifurcation of critical points for continuous families of C^2 functionals of Fredholm type

Jacobo Pejsachowicz and Nils Waterstraat

Abstract

Given a continuous family of C^2 functionals of Fredholm type, we show that the non-vanishing of the spectral flow for the family of Hessians along a known (trivial) branch of critical points not only entails bifurcation of nontrivial critical points but also allows to estimate the number of bifurcation points along the branch. We use this result for several parameter bifurcation, estimating the number of connected components of the complement of the set of bifurcation points and apply our results to bifurcation of periodic orbits of Hamiltonian systems. By means of a comparison principle for the spectral flow, we obtain lower bounds for the number of bifurcation points of periodic orbits on a given interval in terms of the coefficients of the linearization.

1 Introduction

In this paper we deal with bifurcation of critical points of a continuous family of C^2 functionals $\{\psi_\lambda: U \rightarrow \mathbb{R}\}_{\lambda \in \Lambda}$, defined on an open neighborhood U of 0 in a separable Hilbert space H and parametrized by a topological space Λ . Such a family is given by a function $\psi: \Lambda \times U \rightarrow \mathbb{R}$ such that, for any $\lambda \in \Lambda$, the map $\psi_\lambda \equiv \psi(\lambda, \cdot): U \rightarrow \mathbb{R}$ is C^2 , and moreover for any k , $1 \leq k \leq 2$, the map sending the point (λ, x) to the k -th differential $d^k \psi_\lambda(x)$ is a continuous map from $\Lambda \times U$ into the normed space of symmetric k forms, $Sym^k(H, \mathbb{R})$. In what follows, we will always assume that the point 0 is a critical point of ψ_λ , for all $\lambda \in \Lambda$. Families of functionals of this type arise when the data of the problem are not smooth enough in order to ensure the differentiability with respect to the parameter.

Let $f_\lambda(x) = \nabla \psi_\lambda(x)$ be the gradient of ψ_λ at the point $x \in U$, and let $L_\lambda = Df_\lambda(0)$ be the Fréchet differential of f_λ at the critical point $0 \in H$. The operator L_λ is the Hessian of ψ_λ at the critical point 0. Each L_λ is a bounded self-adjoint operator and $\psi_\lambda(x) = \langle L_\lambda x, x \rangle + o(\|x\|^2)$. Since ψ is a continuous family of C^2 functionals, f is continuous in both variables and differentiable in x . Moreover, the map $L: \Lambda \rightarrow \mathcal{L}_S(H)$ defined by $L(\lambda) = L_\lambda$ is continuous with respect to the norm topology in the space $\mathcal{L}_S(H)$ of all bounded self-adjoint operators from H into itself. We assume in addition that each L_λ is Fredholm, namely, that it has a closed image and finite dimensional kernel. From the self-adjointness of L_λ , we have that $\text{ind } L_\lambda = \dim \ker L_\lambda - \text{codim im } L_\lambda = 0$.

The space of all self-adjoint Fredholm operators $\Phi_S(H)$ is an open subset of $\mathcal{L}_S(H)$. Therefore, by considering possibly a smaller neighborhood U of 0, we can suppose that $Df_\lambda(x)$ is Fredholm for every $x \in U$. Thus f is a continuous family of C^1 -Fredholm maps possessing a variational

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structure, with ψ as associated family of potential functions. A family ψ as above will be called a *continuous family of Fredholm C^2 functionals*. The set $\mathcal{T} \equiv \Lambda \times \{0\}$ is called the *trivial branch*.

Definition 1.1. A point $\lambda_* \in \Lambda$ is a point of bifurcation of critical points of the family ψ from the trivial branch if every neighborhood of $(\lambda_*, 0)$ in $\Lambda \times U$ contains some point (λ, x) , where $x \neq 0$ is a critical point of ψ_λ .

By the implicit function theorem, bifurcation can occur only at points $\lambda \in \Lambda$ where L_λ fails to be invertible. In this paper we will deal first with the case where $\Lambda = [a, b]$ is a compact interval and then we will use the obtained results in several-parameter bifurcation. We assume that both L_a and L_b are invertible and will look for sufficient conditions ensuring the existence of at least one bifurcation point for the family ψ in (a, b) .

When ψ is C^2 and H is finite dimensional it is a folklore result that bifurcation arises in (a, b) whenever the Morse index $\mu(\psi_a, 0)$ differs from $\mu(\psi_b, 0)$. This result extends to C^2 functionals $\psi: [a, b] \times U \rightarrow \mathbb{R}$ if the Hessians L_λ of ψ_λ at 0 are either essentially positive or essentially negative. Let us recall that a self-adjoint operator L_λ is essentially positive if it is a compact perturbation of a positive definite self-adjoint operator. If ψ_λ is as above and if 0 is a non-degenerate critical point of ψ_λ , its Morse index $\mu(\psi_\lambda, 0)$ is the dimension of the maximal negative space of its Hessian L_λ at 0. With this definition the corresponding bifurcation theorem holds in the form stated in finite dimensions. The same holds for functionals with essentially negative definite Hessian.

The above results are sufficient for many applications of bifurcation theory to nonlinear differential equations, but not for all of them. Indeed, in variational problems arising in the theory of Hamiltonian systems, e.g., geodesics on semi-Riemannian manifolds, and perturbations of self-adjoint systems of first order elliptic differential operators, one deals with strongly indefinite functionals ψ , where $\mu(\psi, x)$ and $\mu(-\psi, x)$ are both infinite. In this case the invariant that substitutes the difference between the Morse indices at the end points is the *spectral flow* of a path of self-adjoint Fredholm operators.

Roughly speaking, given a path $L: I \rightarrow \Phi_S(H)$ of self-adjoint Fredholm operators with invertible end-points, its spectral flow $\text{sf}(L, I) \in \mathbb{Z}$ is the number of negative eigenvalues of L_a that become positive as the parameter λ travels from a to b minus the number of positive eigenvalues of L_a that become negative. When the operators of the path are essentially positive, then the spectral flow of L is the difference of the Morse indices at the end-points. However, if the operators in the path are strongly indefinite, i.e. neither L nor $-L$ consists of essentially positive operators, then $\text{sf}(L, I)$ depends in general on the whole path and not only on its end-points.

The spectral flow was introduced for the first time for paths of elliptic self-adjoint operators in [APS76] and since then its definition was extended with various degrees of generality and used in linear and nonlinear functional analysis. Let us quote as references [BW85, Fl88, CLM94, RS95, Ph96, MPP05, W08, PW13].

The above heuristic description of the spectral flow can be made rigorous in many different ways. A neat geometric understanding of the spectral flow can be obtained by interpreting this invariant as an oriented intersection number of the path with the singular variety Σ of all non-invertible self-adjoint Fredholm operators. The set Σ is a one codimensional stratified subvariety of the open subset $\Phi_S(H) \subset \mathcal{L}_S(H)$ of all bounded self-adjoint Fredholm operators on H . For $k \geq 1$, the stratum $\Sigma_k = \{T \in \Phi_S(H) : \dim \ker T = k\}$ of the variety Σ is a submanifold (not closed in $\Phi_S(H)$). The top stratum Σ_1 is of codimension 1 in $\Phi_S(H)$, while the other strata are of codimension three or higher. Σ_1 possesses a nowhere vanishing normal vector field, i.e., is co-oriented. This allows us to define $\text{sf}(L, I)$ by approximating the path L with a smooth path having transversal intersections with Σ (hence, not intersecting the strata of higher order) and counting the intersection points of the approximating path with Σ_1 with signs ± 1 according to

whether the orientation of the tangent vector to the path coincides or not with that of a chosen normal field (cf. [FPR99]).

The graph of any self-adjoint operator is a Lagrangian subspace of the product $H \times H$ with its natural (cotangent) symplectic structure. In this picture Σ becomes the "train" (or "Maslov Cycle") of $H \times \{0\}$. Using this, the spectral flow can be interpreted as an infinite dimensional Maslov index for paths in the Fredholm Lagrangian Grassmannian. This approach leads to the definition of spectral flow for families of unbounded self-adjoint operators as well (cf. [Ni93]).

That the spectral flow is the right homotopy invariant of the path of linearizations for the study of bifurcation of critical points of families of strongly-indefinite functionals was found in [FPR99]. In the present paper we will improve the results of [FPR99] in several ways.

First of all, we extend the bifurcation theorem of [FPR99] to continuous families of C^2 functionals parametrized by an interval by showing that bifurcation of critical points arise whenever the path of Hessians along the trivial branch has a non-vanishing spectral flow. For this we will use the homotopy invariance of the Conley index of an isolated invariant set in the central part of the proof of the theorem, after having reduced the problem to finite dimensions. The Conley index needs less differentiability assumptions about the functional than the homology groups of a critical point used in [FPR99]. In addition we estimate the number of bifurcation points of the family ψ in terms of the spectral flow $\text{sf}(L, I)$ of the path of Hessians along the trivial branch and the highest stratum Σ_m crossed by L . Our conclusion in Theorem 2.1 is as follows: if the crossing points with Σ are isolated, then ψ must have at least $|\text{sf}(L, I)|/m$ bifurcation points.

When the parameter space is a general topological space Λ , upon appropriate assumptions, we will use the above result along paths in Λ in order to estimate the number of connected components of the complement of the set of bifurcation points. This is done in Theorem 2.2.

Bifurcation of periodic and homoclinic orbits of Hamiltonian systems is a natural place for applications of the above theory since the associated functionals are of strongly indefinite type. We apply our results to bifurcation of 2π -periodic orbits of time-dependent, periodic Hamiltonian systems whose Hamiltonian function has a time independent Hessian. In this case the linearized equation has constant coefficients and from this fact one easily obtains sufficient conditions for bifurcation and estimates for the number of components directly in terms of the coefficients.

The case of general non-autonomous periodic Hamiltonian systems is more involved. However, for the one-parameter case, we obtain in Proposition 8.1 some estimates for the number of bifurcation points for 2π -periodic orbits in terms of the coefficients of its linearization along the stationary branch. The estimate is deduced from a general comparison principle for the spectral flow which is stated in Theorem 7.1 and might have other uses as well.

The paper is organized as follows: in Section 2 we state our main results. In Section 3 we recall some well known properties of the spectral flow and prove Proposition 2.5. The sections 4 and 5 are devoted to the proofs of the theorems 2.1 and 2.2, respectively. Applications to several parameter bifurcation of periodic orbits of Hamiltonian systems with time independent Hessians are given in Section 6. In Section 7 we establish the comparison principle which is used in Section 8 in order to obtain an estimate for the number of bifurcation points for non-trivial periodic orbits of a Hamiltonian system from the stationary branch.

2 The main theorems

Our main result reads as follows:

Theorem 2.1. *Let U be a neighborhood of 0 in a separable Hilbert space H and let $\psi: I \times U \rightarrow \mathbb{R}$ be a continuous family of C^2 functionals parametrized by $I = [a, b]$. Assume that 0 is a critical point of the functional $\psi_\lambda \equiv \psi(\lambda, \cdot)$ for each $\lambda \in I$. Moreover, assume that the Hessians L_λ of*

ψ_λ at 0 are Fredholm with L_a and L_b invertible.

i) If $\text{sf}(L, I) \neq 0$, then the interval (a, b) contains at least one point of bifurcation of critical points of ψ_λ from the trivial branch.

ii) If L intersects Σ only at a finite number of points $\lambda \in I$, then the family ψ possesses at least $|\text{sf}(L, I)|/m$ bifurcation points in (a, b) , where m is the highest order of the stratum crossed by L , i.e.,

$$m = \max\{\dim \ker L_\lambda : \lambda \in [a, b]\}.$$

There is a number of cases in which the hypothesis of ii) are verified:

- 1) The path L is real analytic. Indeed, in this case, the set $\Sigma(L) := L^{-1}(\Sigma)$ of all *singular points* of the path L has to be discrete, because on a small neighborhood of any point $\lambda \in I$ the set $\Sigma(L)$ coincides with the set of zeroes of the analytic function $\det(U^*LU|_{H_0})$, where U and H_0 are as in the proof of Lemma 4.5 below.
- 2) The path L is differentiable and has only regular crossing points in I . A regular crossing point is a point $\lambda \in \Sigma(L)$ at which the crossing form $\mathcal{Q}(\lambda)$, defined as the restriction of the quadratic form $\langle \dot{L}_\lambda h, h \rangle$ to $\ker L_\lambda$, is non-degenerate. The proof that regular crossing points are isolated can be found in [FPR99, Theorem 4.1]. It also follows from the above theorem that, for paths having only regular crossing points, one has

$$\text{sf}(L, I) = \sum_{\lambda \in \Sigma(L)} \text{sig } \mathcal{Q}(\lambda), \quad (1)$$

where sig stands for the signature of a quadratic form. It is easy to see that at regular crossing points $\text{sig } \mathcal{Q}(\lambda)$ coincides with the "crossing number" studied in [CL88, K04]. From this viewpoint the spectral flow arise in variational bifurcation theory as an improvement of this, earlier defined invariant at isolated points in $\Sigma(L)$.

- 3) A differentiable path is said to be positive if the quadratic form $\mathcal{Q}(\lambda)$ is positive definite at each crossing point. By the above discussion, positive paths have only regular crossings and moreover $\text{sig } \mathcal{Q}(\lambda) = \dim \ker L_\lambda$. Therefore positive paths verify the second hypothesis in Theorem 2.1. Moreover, in this case

$$\text{sf}(L, I) = \sum_{\lambda \in \Sigma(L)} \dim \ker L_\lambda.$$

A typical positive path on $(0, \infty)$ is $L_\lambda = \lambda \text{Id} - K$, where K is a compact operator. A well known theorem by Krasnoselskii states that if ϕ is a weakly continuous functional such that $\nabla \phi(0) = 0$, then every non-vanishing eigenvalue of the Hessian of ϕ at 0 is a bifurcation point for solutions of the variational equation $\lambda x - \nabla \phi(x) = 0$. Thus Krasnoselskii's theorem is a very special case of Theorem 2.1.

- 4) The positivity can be formulated for paths that are only continuous, by requiring that for each singular point λ_0 of L in I there is a neighborhood $I_\delta = (\lambda_0 - \delta, \lambda_0 + \delta)$ and an increasing function $\gamma: I_\delta \rightarrow \mathbb{R}$ with $\gamma(\lambda_0) = 0$, such that:

$$\begin{aligned} \langle L(\lambda) - L(\lambda_0)u, u \rangle &\leq \gamma(\lambda)\langle u, u \rangle \quad \forall \lambda \in (\lambda_0 - \delta, \lambda_0], \quad \forall u \in \ker L_{\lambda_0}, \\ \langle L(\lambda) - L(\lambda_0)u, u \rangle &\geq \gamma(\lambda)\langle u, u \rangle \quad \forall \lambda \in [\lambda_0, \lambda_0 + \delta), \quad \forall u \in \ker L_{\lambda_0}, \end{aligned}$$

and $\lim_{\lambda \rightarrow 0} \frac{\|L(\lambda) - L(\lambda_0)\|^2}{\gamma(\lambda)} = 0$. In this case (cf. [FPS]), one still has that the singular points are isolated and $\text{sf}(L, I) = \sum_{\lambda \in \Sigma(L)} \dim \ker L_\lambda$.

Using the above theorem, we will obtain estimates on the number of connected components of the complement of the set of bifurcation points of families of functionals parametrized by more general topological spaces. More precisely, we assume that Λ is a connected topological space and ψ a continuous family of Fredholm C^2 functionals such that $0 \in H$ is a critical point of all ψ_λ , $\lambda \in \Lambda$.

Let us denote the set of all bifurcation points in Λ by $B(\psi)$. In what follows, we call a path $\gamma : I \rightarrow \Lambda$ admissible if the operators $L_{\gamma(a)}$ and $L_{\gamma(b)}$ are isomorphisms. The spectral flow $\text{sf}(L \circ \gamma, I)$ of L along an admissible path is well defined and it is additive under concatenation. We will say that the family ψ satisfies the assumption (A) if for any admissible path γ the spectral flow $\text{sf}(L \circ \gamma, I)$ depends only on the end-points of the path, or equivalently, if $\text{sf}(L \circ \gamma, I) = 0$ for all closed admissible paths.

Theorem 2.2. *Let Λ be a connected topological space and $\psi : \Lambda \times H \rightarrow \mathbb{R}$ a continuous family of Fredholm C^2 functionals such that $0 \in H$ is a critical point of all ψ_λ , $\lambda \in \Lambda$, and such that (A) holds.*

- i) *If there exists an admissible path γ in Λ such that $\text{sf}(L \circ \gamma, I) \neq 0$, then $\Lambda \setminus B(\psi)$ is disconnected.*
- ii) *If there exists a sequence of admissible paths γ_n , $n \in \mathbb{N}$, such that $\lim_{n \rightarrow \infty} |\text{sf}(L \circ \gamma_n, I)| = \infty$, then $\Lambda \setminus B(\psi)$ has infinitely many path components.*
- iii) *If $\Sigma(L) = B(\psi)$, any admissible path γ such that $L \circ \gamma$ has only isolated singular points will cross at least $\frac{|\text{sf}(L \circ \gamma)|}{m} + 1$ components of $\Lambda \setminus B(\psi)$, where m is defined as in Theorem 2.1.*

Remark 2.3. Let us recall that the Lebesgue covering dimension $\dim \Lambda$ of a topological space Λ is the minimal value of $n \in \mathbb{N}$ such that every finite open cover of Λ has a finite open refinement in which no point belongs to more than $n + 1$ elements. By Corollary 1, Theorem IV 4 of [HW48], no subset of dimension strictly smaller than $n - 1$ can disconnect a topological n -manifold. Therefore, it follows from Theorem 2.1 that, if the parameter space Λ is a topological manifold of dimension n , then the covering dimension of $B(\psi)$ is at least $n - 1$.

Corollary 2.4. *If Λ is a smooth manifold verifying the assumptions of Theorem 2.2 and if $\Sigma(L) \subset \mathcal{S}$, where \mathcal{S} is a stratified submanifold of Λ of positive codimension, e.g., if L is smooth and transversal to the variety Σ , then iii) holds irrespective of the assumption $\Sigma(L) = B(\psi)$. The same is true if Λ is a topological n -manifold and $\dim \Sigma(L) \setminus B(\psi) \leq n - 2$.*

The condition (A) is satisfied if the Hessians L_λ are either essentially positive or negative definite. However, we will use (A) in the case of a family of Hamiltonian systems, in which none of the Morse indices is finite. In this framework (A) still holds by (2) below. The following proposition shows the relevance of the topology of the parameter space for the validity of (A).

Proposition 2.5. *Let Λ be a connected space of finite type, i.e., all homology groups $H_k(\Lambda)$, $k \in \mathbb{N}$, are finitely generated. If $H_1(\Lambda; \mathbb{Q}) = 0$, then (A) holds for any continuous family of Fredholm C^2 functionals parametrized by Λ .*

Finally, let us mention that Theorem 2.2 and Proposition 2.5 improve the main results of the recent work [PW13]. Moreover, the proof of the second assertion in Theorem 2.2 simplifies the argument used in [Wa13].

3 The spectral flow

The proof of Theorem 2.1 is based on a reduction process to families of functionals of a particular form and some properties of the spectral flow which we are going to review in this section. Among the several constructions of this invariant in the literature, we will follow the approach taken in [FPR99] because it leads almost immediately to the reduction process mentioned above.

Let us recall that the open set $\Phi_S(H)$ is not connected and that the position with respect to 0 of the essential spectrum of an operator determines to which connected component the operator belongs. The three connected components of $\Phi_S(H)$ are: the set of *essentially positive operators* $\Phi_S^+(H)$ consisting of all operators in $\Phi_S(H)$ whose negative spectrum has only isolated eigenvalues of finite multiplicity; the set of *essentially negative operators* $\Phi_S^-(H)$ defined in a corresponding way and the set of *strongly indefinite operators* $\Phi_S^i(H)$ whose elements have infinite dimensional negative and positive spectral subspaces.

Let us briefly recall from [FPR99] the definition of the spectral flow of a path $L : I \rightarrow \Phi_S(H)$. In accordance with the notation in Theorem 2.2, L will be called *admissible* if its end-points are invertible. At first, if such an admissible path L is a compact perturbation of a fixed self-adjoint Fredholm operator $T \in \Phi_S(H)$, i.e., $L_\lambda = T + K_\lambda$ where K_λ is compact, then the spectral flow is defined as the relative Morse index of the end-points of the path; namely:

$$\begin{aligned} \text{sf}(L, [a, b]) &= \mu_{\text{rel}}(L_a, L_b) \\ &= \dim[E^-(L_a) \cap E^+(L_b)] - \dim[E^-(L_b) \cap E^+(L_a)], \end{aligned} \quad (2)$$

where E^\pm denote the maximal positive (resp. negative) space of a self-adjoint operator. In order to explain how (2) can be extended to general admissible paths in $\Phi_S(H)$, we firstly assume that $L : I \rightarrow \Phi_S^i(H)$ is a path of strongly indefinite operators. We split H into a product $H^+ \times H^-$ with both H^\pm isomorphic to H and, writing $h = (x, y)$, we define $J(x, y) = x - y$. Clearly, $J^2 = Id$ and the spectrum of J is $\{\pm 1\}$, both with infinite dimensional spectral subspace. Such a J is called polarization in [We76]. Once a polarization is chosen, we say that a path $M : I \rightarrow GL(H)$ is a cogredient parametrix for a path $L : I \rightarrow \Phi_S^i(H)$ with respect to J , if

$$M_\lambda^* L_\lambda M_\lambda = J + K_\lambda, \quad (3)$$

with K_λ compact and (necessarily) self-adjoint. It is shown in [FPR99] that every path in $\Phi_S^i(H)$ has a cogredient parametrix M and that the definition

$$\text{sf}(L, [a, b]) = \mu_{\text{rel}}(J + K_a, J + K_b) \quad (4)$$

does not depend on the choice of the cogredient parametrix M .

The case of paths $L : I \rightarrow \Phi_S^\pm(H)$ of essentially positive or essentially negative operators reduces to the one in $\Phi_S^i(H \oplus H)$ by taking direct sum $\mp Id$ on the second factor. Consequently, (4) extends to all admissible paths in $\Phi_S(H)$. It follows easily from (4) that for paths in $\Phi_S^\pm(H)$ the spectral flow coincides with the difference of the Morse indices of $\pm L$ at the end points.

The spectral flow is uniquely characterized by the following four properties (cf. [CFP00]):

- i) *Normalization*: If L is a path of isomorphisms, then $\text{sf}(L, I) = 0$.
- ii) *Morse Index*: If H is finite dimensional, then $\text{sf}(L, I) = \mu(L_a) - \mu(L_b)$.

iii) *Direct Sum Property*: If L_1 and L_2 are admissible paths on Hilbert spaces H_1 and H_2 respectively, then $\text{sf}(L_1 \oplus L_2, I) = \text{sf}(L_1, I) + \text{sf}(L_2, I)$.

iv) *Homotopy Invariance Property*: Let $H: [0, 1] \times I \rightarrow \Phi_S(H)$ be a family such that for each $s \in [0, 1]$, the path $H_s \equiv H(s, \cdot)$ is admissible. Then $\text{sf}(H_s, I)$ is independent of s .

From the above four properties it follows also that the spectral flow is additive under the concatenation of intervals, and invariant under free homotopies of closed paths. Namely (cf.[FPR99]):

v) *Concatenation*: If the path $L: I \rightarrow \Phi_S(H)$ is admissible both on $[a, c]$ and on $[c, b]$, then $\text{sf}(L, [a, b]) = \text{sf}(L, [a, c]) + \text{sf}(L, [c, b])$.

vi) *Homotopy of Closed Paths*: Let the family $H: [0, 1] \times I \rightarrow \Phi_S(H)$ be such that $H(\cdot, a) = H(\cdot, b)$ and $H(0, a), H(1, a)$ are invertible. Then, irrespective of the invertibility of the operators $H(\cdot, a)$,

$$\text{sf}(H_0, I) = \text{sf}(H_1, I).$$

We will now use the last two properties of the spectral flow in order to prove Proposition 2.5. Let $\pi_1(\Lambda, \lambda)$ be the fundamental group of Λ with base point λ . Since the spectral flow is homotopy invariant and additive under concatenation of paths, it induces a homomorphism $\bar{\text{sf}}: \pi_1(\Lambda, \lambda) \rightarrow \mathbb{Z}$ which necessarily sends the commutator subgroup $[\pi_1, \pi_1]$ to 0. Therefore $\bar{\text{sf}}$ factors through the quotient $q: \pi_1(\Lambda, \lambda) \rightarrow \pi_1(\Lambda, \lambda)/[\pi_1, \pi_1]$. Under the identification $\pi_1(\Lambda, \lambda)/[\pi_1, \pi_1] \simeq H_1(\Lambda; \mathbb{Z})$, we obtain a homomorphism $h: H_1(\Lambda; \mathbb{Z}) \rightarrow \mathbb{Z}$ such that, denoting with $[\gamma]$ the homotopy class of a closed path γ based at λ , we have that $\text{sf}(L \circ \gamma) = h \circ q([\gamma])$.

Since Λ is of finite type, there exists $d \in \mathbb{N} \cup \{0\}$ and prime numbers p_1, \dots, p_N such that $H_1(\Lambda; \mathbb{Z}) \cong \mathbb{Z}^d \oplus \mathbb{Z}_{p_1} \oplus \dots \oplus \mathbb{Z}_{p_N}$. It follows from the universal coefficient theorem that $d = 0$, because $H_1(\Lambda; \mathbb{Q}) = 0$ by assumption. We conclude that every element of $H_1(\Lambda; \mathbb{Z})$ is of finite order which, on its turn, implies that $h \equiv 0$. Thus $\text{sf}(L \circ \gamma) = 0$, for any closed path based at λ and hence, by vi), for any closed admissible path. This yields the desired conclusion.

4 Proof of Theorem 2.1

First of all, let us notice that it is enough to prove the theorem in the strongly indefinite case. Indeed, given any family of functionals $\psi: I \times U \rightarrow \mathbb{R}$ of Fredholm type, one can consider the auxiliary family $\hat{\psi}: I \times U \times U \times U \rightarrow \mathbb{R}$ defined by

$$\hat{\psi}(\lambda, w, u, v) \equiv \psi(\lambda, u) + \frac{1}{2}\|w\|^2 - \frac{1}{2}\|v\|^2.$$

Clearly, the bifurcation points of ψ are the same as those of $\hat{\psi}$. Moreover, by the direct sum property, the spectral flows of the Hessians along the trivial branch of critical points of ψ and $\hat{\psi}$ are the same. But the Hessians of $\hat{\psi}$ are strongly indefinite. Henceforth we assume that ψ is strongly indefinite and do a further reduction of the problem.

We choose a cogredient parametrix M for the path L of Hessians of ψ and set

$$\tilde{\psi}(\lambda, h) \equiv \psi(\lambda, M_\lambda(h)), \quad \tilde{f}(\lambda, h) = M_\lambda^* f(\lambda, M_\lambda(h)), \quad \tilde{L}_\lambda = M_\lambda^* L_\lambda M_\lambda.$$

Then we have for all $(\lambda, h) \in I \times H$

$$\nabla_h \tilde{\psi}(\lambda, h) = \tilde{f}(\lambda, h) \quad \text{and} \quad D_h \tilde{f}(\lambda, h) = \tilde{L}_\lambda h. \quad (5)$$

Since $\{M_\lambda\}_{\lambda \in I}$ and $\{M_\lambda^*\}_{\lambda \in I}$ are paths of invertible operators, it is clear that nontrivial solutions of the equation $f(\lambda, h) = 0$ correspond via M_λ with nontrivial solutions of $\tilde{f}(\lambda, h) = 0$. Therefore, the bifurcations of critical points of ψ and $\tilde{\psi}$ arise at the same values of the parameter λ . Also the crossing points of L and \tilde{L} with each stratum Σ_k are the same. Moreover, it follows from the homotopy invariance property iv) that the spectral flows of L and $\tilde{L} = M^*LM$ coincide. Indeed, the homotopy $H(\lambda, t) = M_{t\lambda}^* L_\lambda M_{t\lambda}$ shows that $\text{sf}(\tilde{L}, I) = \text{sf}(M_a^* L M_a)$. Since $GL(H)$ is connected, there exists a path of invertible operators from M_a to Id and we obtain that

$$\text{sf}(\tilde{L}, I) = \text{sf}(M_a^* L M_a) = \text{sf}(L, I).$$

Consequently, by possibly replacing $\psi: I \times U \rightarrow \mathbb{R}$ with $\tilde{\psi}: I \times U \rightarrow \mathbb{R}$, we may assume that for each parameter $\lambda \in I$, $L_\lambda = J + K_\lambda$ with K_λ compact and symmetric, which we will do from now on.

We choose Hilbert bases $\{e_k^+\}_{k=1 \dots \infty}$ and $\{e_k^-\}_{k=1 \dots \infty}$ for H^+ and H^- , respectively. Let H_n be the subspace of H spanned by $\{e_k^\pm \mid 1 \leq k \leq n\}$. Then J commutes with the orthogonal projection P_n of H onto H_n and hence $J(H_n) = H_n$, $J(H_n^\perp) = H_n^\perp$. Namely, the pair H_n, H_n^\perp reduces J . Notice also that the signature of the restriction of J to H_n is zero.

It is shown in [CFP00, Lemma 4] that there exists $n \in \mathbb{N}$ such that, for all $\lambda \in I$,

$$(\text{Id} - P_n)L_\lambda: H_n^\perp \rightarrow H_n^\perp$$

is invertible, and for $0 \leq t \leq 1$ and $\lambda \in \{a, b\}$,

$$tL_\lambda + (1-t)[(\text{Id} - P_n)L_\lambda(\text{Id} - P_n) + P_n L_\lambda P_n]$$

is invertible, too. Hence, if we denote

$$L_\lambda^n = P_n L_\lambda |_{H_n}: H_n \rightarrow H_n \quad \text{and} \quad \tilde{L}_\lambda^n = (\text{Id} - P_n)L_\lambda |_{H_n^\perp}: H_n^\perp \rightarrow H_n^\perp,$$

we get from iv), iii) and i)

$$\text{sf}(L, I) = \text{sf}(L^n \oplus \tilde{L}^n, I) = \text{sf}(L^n, I) + \text{sf}(\tilde{L}^n, I) = \text{sf}(L^n, I).$$

Finally, by using ii), we obtain:

Proposition 4.1. *If $L: I \rightarrow \mathcal{L}(H)$ and $L^n: I \rightarrow \mathcal{L}(H_n)$ are as above, then there exists n_0 such that*

$$\text{sf}(L, I) = \text{sf}(L^n, I) = \mu(L_a^n) - \mu(L_b^n), \quad \text{for all } n \geq n_0.$$

Before turning to the proof of Theorem 2.1 let us prove a version of the Lyapunov-Schmidt Reduction for critical points that we will use below. This later is a modification of the reduction proved in [FPR99] adapted to the class of functionals we are working with.

Lemma 4.2. *Let $\psi: I \times U \rightarrow \mathbb{R}$ be a continuous one-parameter family of C^2 functionals. Let $f(\lambda, h) \equiv \nabla_h \psi(\lambda, h)$. Assume that $f(\lambda, 0) = 0$ for all $\lambda \in I$. Suppose that there is an orthogonal splitting $H = X \times Y$, where $\dim X < \infty$ and such that, writing $h = (x, y)$ and $f(\lambda, h) = (f_1(\lambda, x, y), f_2(\lambda, x, y))$, we have that $D_y f_2(\lambda, 0, 0): Y \rightarrow Y$ is invertible for all $\lambda \in I$. Then:*

i) There is an open ball $B = B(0, \delta) \subset X$ and a continuous family of C^1 maps $g: I \times B \rightarrow Y$, such that $g(\lambda, 0) = 0$ for all $\lambda \in I$, and

$$f_2(\lambda, x, g(\lambda, x)) = 0 \quad \text{for all } (\lambda, x) \in I \times B. \quad (6)$$

ii) If the mapping $\bar{f}: I \times B \rightarrow X$ and the functional $\bar{\psi}: I \times B \rightarrow \mathbb{R}$ are defined by

$$\bar{f}(\lambda, x) \equiv f_1(\lambda, x, g(\lambda, x)) \quad \text{and} \quad \bar{\psi}(\lambda, x) \equiv \psi(\lambda, x, g(\lambda, x)) \quad \text{respectively,}$$

then $\bar{\psi}$ is a continuous family of C^2 functionals on B and

$$\nabla_x \bar{\psi}(\lambda, x) = \bar{f}(\lambda, x) \quad \text{for all } (\lambda, x) \in I \times B. \quad (7)$$

Proof. Composing f_2 on the right with $D_y^{-1}f_2(\lambda, 0, 0)$, we obtain a map $\bar{f}_2: I \times X \times Y \rightarrow Y$ such that $D_y \bar{f}_2(\lambda, 0, 0) = \text{Id}$ for all $\lambda \in I$. Clearly, there exists a g verifying (6) for f_2 if and only if the same holds for \bar{f}_2 . Therefore, we can assume that $D_y f_2(\lambda, 0, 0) = \text{Id}$. Assuming this, the derivative in the y direction of the map $k(\lambda, x, y) = y - f_2(\lambda, x, y)$ vanishes at $(\lambda, 0, 0)$ for all λ . Being $D_y k(\lambda, x, y)$ continuous, using compactness of I , we can find a product ball $(B' = B(0, \epsilon)) \times (B'' = B(0, \epsilon)) \subset X \times Y$ such that $\|D_y k(\lambda, x, y)\| \leq \frac{1}{2}$ on $I \times B' \times B''$. From this, we obtain that

$$\|k(\lambda, x, y) - k(\lambda, x, y')\| \leq \frac{1}{2}\|y - y'\|, \quad (8)$$

for any $(\lambda, x) \in I \times B'$ and any $y, y' \in B''$. Taking a $\delta < \epsilon$ such that $\|k(\lambda, x, 0)\| = \|f_2(\lambda, x, 0)\| \leq \frac{\epsilon}{2}$ on $B = B(0, \delta)$ and using (8) together with $k(\lambda, 0, 0) = 0$, we obtain that $\|k(\lambda, x, y)\| < \epsilon$, on $I \times B \times B''$.

Therefore, for any $(\lambda, x) \in I \times B$, the map $k_{(\lambda, x)}(y) := k(\lambda, x, y)$ is a strict contraction of B'' into itself. Defining $g(\lambda, x)$ to be the unique fixed point of $k_{(\lambda, x)}: B'' \rightarrow B''$, the equation (6) holds true. The continuity of g follows from the fact that fixed points of continuous families of contractions depend continuously on the parameter. By the implicit function theorem for C^1 maps, each $g_\lambda \equiv g(\lambda, \cdot)$ is differentiable. That the map $(\lambda, x) \rightarrow Dg_\lambda(x)$ is continuous is a simple consequence of the formula for the derivative of an implicit function. Finally, a straightforward application of the chain rule gives (7), from which it also follows that $\bar{\psi}$ is a continuous family of C^2 functionals. \square

Let us take as X, Y in Lemma 4.2 the pair H_n, H_n^\perp . Then we have a splitting $f = (f_1^n, f_2^n)$, where

$$f_1^n(\lambda, x, y) = P_n f(\lambda, x, y) \quad \text{and} \quad f_2^n(\lambda, x, y) = (\text{Id} - P_n)f(\lambda, x, y).$$

Moreover, we have that $D_y f_2^n(0, 0) = \tilde{L}^n$ is an isomorphism for n large enough. Thus, by the previous lemma we obtain a finite dimensional reduction $\bar{\psi}^n: I \times B \rightarrow \mathbb{R}$, $\bar{f}^n = \nabla_x \bar{\psi}^n: I \times B \rightarrow H_n$ for some ball $B \subset H_n$ centered at 0.

Proposition 4.3. *Let $l_\lambda^n = D_x \bar{f}^n(\lambda, 0)$ be the Hessian of $\bar{\psi}_\lambda^n$ at 0. For $i = a, b$ and n big enough, we have that 0 is a non-degenerate critical point of $\bar{\psi}_i^n$ and*

$$\mu(\bar{\psi}_i^n, 0) := \mu(l_i^n) = \mu(L_i^n).$$

Proof. For $i = a, b$, let $C_i^n = Dg_i(0)$. From equation (6) we obtain by implicit differentiation

$$C_i^n = [D_y f_2^n(i, 0, 0)]^{-1} D_x f_2^n(i, 0, 0) = (\tilde{L}_i^n)^{-1} (\text{Id} - P_n) L_i|_{H_n}. \quad (9)$$

For n big enough, \tilde{L}_i^n becomes as close as we wish to the isomorphism L_i which make the norms of its inverses uniformly bounded. If we now use that $L_i = J + K_i$ and that J commutes with P_n , we infer

$$C_i^n = (\tilde{L}_i^n)^{-1} (\text{Id} - P_n) (J + K_i)|_{H_n} = (\tilde{L}_i^n)^{-1} (\text{Id} - P_n) K_i|_{H_n}.$$

Now, since $(\text{Id} - P_n) K_i$ converges to 0 in norm, we obtain that $\|C_i^n\| \rightarrow 0$, $n \rightarrow \infty$. Observing that

$$l_i^n = P_n L_i (\text{Id} + C_i^n) = L_i^n + P_n L_i C_i^n,$$

we see that $l_i^n - L_i^n \rightarrow 0$ in norm which implies that the Morse index of l_i^n is defined and coincides with that of L_i^n for sufficiently large n . \square

By construction, the family $\bar{\psi}$ and the family ψ have the same bifurcation points. Now, part *i*) of Theorem 2.1 follows from the propositions 4.1, 4.3 and:

Proposition 4.4. *Let $U \subset \mathbb{R}^N$ be a neighborhood of 0 and let $\psi: I \times U \rightarrow \mathbb{R}$ be a continuous family of C^2 functionals such that 0 is a critical point of $\psi_\lambda \equiv \psi(\lambda, \cdot)$ for each $\lambda \in I$. If the Hessians l_a of ψ_a and l_b of ψ_b are invertible and $\mu(l_a) \neq \mu(l_b)$, then the interval (a, b) contains at least one point of bifurcation of critical points of the family ψ_λ from the trivial branch.*

Proof. In order to show that $\mu(l_a) \neq \mu(l_b)$ entails bifurcation, we will use the continuation property of the Conley index of an isolated invariant set of a flow. We will shortly recall below some basic facts about the Conley index. Here we follow essentially the presentation of the Conley index in [Ba93] and [Ba92]).

A *flow* on a locally compact metric space X is a continuous map $\Phi: \mathbb{R} \times X \rightarrow X$ such that $\Phi(0, x) = x$ and $\Phi(t + s, x) = \Phi(t, \Phi(s, x))$. As usual we will use subindices in order to denote the partial maps. We will denote by $\gamma(x) = \Phi_x(\mathbb{R})$ the orbit of a point x and by $\alpha(x)$, $\omega(x)$ the alpha and omega limit respectively of the orbit passing through x . Given a subset A of X we will denote by $I(A)$ the maximal invariant subset of A , i.e., the union of all orbits contained in A . A compact subset N of X is an *isolating neighborhood* if any orbit $\gamma(x)$ contained in N does not intersect ∂N . If N is an isolating neighborhood, the maximal invariant subset $I(N)$ of N is a compact subset of the interior of N . An invariant subset S of X of the form $S = I(N)$ with N an isolating neighborhood is called an *isolated invariant set*. An *index pair* for an isolated invariant set S is a pair (N, E) of compact subsets of X such that the closure of $N \setminus E$ is an isolating neighborhood of S . The set $E \subset N$, called the *exit set*, is positively invariant in N and such that any orbit exiting N in forward time must pass through E . Every isolating neighborhood of the set S contains an index pair (N, E) for S .

By definition, the Conley index $h(S)$ of an isolated invariant set S is the homotopy type of the pointed space N/E obtained from N by identifying all points in E to a base point. That the (pointed) homotopy type of N/E is independent of the choice of the index pair is one of the main results of Conley's theory. The invariance of the Conley index under conjugation of flows by homeomorphisms allows to compute the index of an isolated hyperbolic equilibrium point x_0 of a complete C^1 - vector field f considered as an isolated invariant set of the associated flow. It turns out that $h(\{x_0\})$ is the homotopy type of a pointed sphere S^m , where m equals the dimension of the unstable manifold of x_0 or, what is the same, the number of characteristic exponents of x_0 with positive real part (see [C78] Chapter I, Section 4.3). In particular, if x_0 is a non-degenerate equilibrium point of a C^2 functional ψ , then the Conley index of x_0 considered

as an isolated critical point of the flow associated to $-\nabla\psi$ is the homotopy type of the sphere S^μ , where $\mu = \mu(\psi, x_0)$ is the Morse index of the critical point. We will use a particular case of the continuation principle for the Conley index in the form presented in [Ba92] (cf. also [Ba93]). A continuous map $\Phi: I \times \mathbb{R} \times X \rightarrow X$ such that each Φ_λ is a flow induces a flow $\bar{\Phi}$ on $I \times X$ defined by $\bar{\Phi}(t, \lambda, x) = (\lambda, \Phi(t, \lambda, x))$. That $\bar{\Phi}$ is a flow is clear from the definition. Moreover, the fibers of the projection $\pi: I \times X \rightarrow I$ are invariant under $\bar{\Phi}$, which acts on the fiber $\{\lambda\} \times X$ as Φ_λ . The continuation principle for the Conley index, in the formulation of [Ba92, Theorem 3.3], asserts that if S is an isolated invariant set for $\bar{\Phi}$, then the section $S_\lambda = \{x \in X \mid (\lambda, x) \in S\}$ is an isolated invariant set for Φ_λ and $h(S) = h(S_\lambda)$ for all $\lambda \in I$. In particular, $h(S_\lambda)$ is independent of λ .

With this said we continue with the proof of the proposition. Assume that for ϵ small enough there are no nontrivial vertical critical points of the family ψ on $\bar{B}(0, \epsilon)$. Set $f_\lambda(h) = -\nabla\psi_\lambda(h)$. Possibly after multiplication by a smooth bump function equal to one on $\bar{B}(0, \epsilon)$, we can assume without loss of generality that each vector field f_λ is complete. Consider the homotopy $\Phi: I \times \mathbb{R} \times X \rightarrow X$ defined by the family of flows induced by the differential equation $\dot{h} = f(\lambda, h)$ and take the flow $\bar{\Phi}$ constructed above. Then the set $S = I \times \{0\}$ is an isolated invariant set with isolating neighborhood $N = I \times \bar{B}(0, \epsilon)$. Indeed, if there is an orbit of $\bar{\Phi}$ passing through a point (λ, h) with $h \neq 0$ and contained in N , then by the above discussion the orbit is of the form $\{\lambda\} \times \gamma(h)$ where $\gamma(h)$ is the orbit of Φ_λ through h . Since Φ_λ is of gradient type, the α and the ω limit of $\gamma(h)$ should be two different critical points of ψ_λ in $\bar{B}(0, \epsilon)$, which is impossible. But then, by the continuation principle and the computation of the Conley index of a non-degenerate equilibrium point, we get

$$\mu(l_a) = \mu(\psi_a, 0) = \mu(\psi_b, 0) = \mu(l_b)$$

contradicting the hypothesis. \square

We now prove the second part of Theorem 2.1. Since the singular set $\Sigma(L)$ is finite, for each $\lambda_0 \in \Sigma(L)$ we can define the spectral flow of L across λ_0 by

$$\text{sf}(L, \lambda_0) = \lim_{\epsilon \rightarrow 0} \text{sf}(L, [\lambda_0 - \epsilon, \lambda_0 + \epsilon]).$$

That this limit exists is a consequence of the additivity and normalization properties of the spectral flow. By the first assertion of Theorem 2.1, λ_0 is a bifurcation point if $\text{sf}(L, \lambda_0) \neq 0$.

Lemma 4.5. *Let $L: I \rightarrow \Phi_S(H)$ be a path such that L_λ fails to be invertible only at $\lambda_0 \in (a, b)$. Then $|\text{sf}(L, \lambda_0)| \leq \dim \ker L_{\lambda_0}$.*

Proof. Since L_{λ_0} is a self-adjoint Fredholm operator, there exists $\epsilon > 0$ such that 0 is the only point in the spectrum of L_{λ_0} in the interval $[-\epsilon, \epsilon]$.

Let us take $I = [\lambda_0 - \delta, \lambda_0 + \delta]$, where $\delta > 0$ is such that $\pm\epsilon$ is not in the spectrum of L_λ for all $\lambda \in I$. Let P_λ , $\lambda \in I$, denote the orthogonal projection onto the spectral subspace of L_λ corresponding to the spectrum inside $[-\epsilon, \epsilon]$. Then $P: I \rightarrow \mathcal{L}(H)$ is continuous, for each $\lambda \in I$, the projection P_λ reduces L_λ and the restriction of L_λ to the kernel of P_λ is an isomorphism. By possibly using a smaller $\delta > 0$, we can assume that $\|P_\lambda - P_{\lambda_0}\| < 1$, and by following the construction in [Ka76, Remark 4.4, Chap II], there is a path $U: I \rightarrow \mathcal{L}(H)$ of orthogonal isomorphisms such that

$$P_\lambda = U_\lambda P_{\lambda_0} U_\lambda^*, \quad \lambda \in I, \quad \text{and} \quad U_{\lambda_0} = \text{Id}.$$

From the homotopy invariance property iv) of the spectral flow, it is readily seen as in the proof of the first part of Theorem 2.1 that

$$\text{sf}(L, I) = \text{sf}(U^*LU, I).$$

Moreover, each $U_\lambda^*L_\lambda U_\lambda$ commutes with P_{λ_0} and so is reduced by this projection. Setting $H_0 = \ker L_{\lambda_0}$ and $H_1 = H_0^\perp$, we obtain

$$U_\lambda^*L_\lambda U_\lambda = (U_\lambda^*L_\lambda U_\lambda |_{H_0}) \oplus (U_\lambda^*L_\lambda U_\lambda |_{H_1})$$

and we conclude from the property iii) of the spectral flow that

$$\text{sf}(U^*LU, I) = \text{sf}(U^*LU |_{H_0}, I) + \text{sf}(U^*LU |_{H_1}, I).$$

Since L_λ is invertible for all $\lambda \neq \lambda_0$ and $U_{\lambda_0} = \text{Id}$, we have $\ker U_\lambda^*L_\lambda U_\lambda \subset H_0$ for all $\lambda \in I$ and consequently $U^*LU |_{H_1}$ is a path of invertible operators. Using i) and ii) we get:

$$\begin{aligned} |\text{sf}(L, \lambda_0)| &= |\text{sf}(U^*LU, I)| = |\text{sf}(U^*LU |_{H_0}, I)| = \\ &= |\mu(U_{\lambda_0-\delta}^*L_{\lambda_0-\delta}U_{\lambda_0-\delta} |_{H_0}) - \mu(U_{\lambda_0+\delta}^*L_{\lambda_0+\delta}U_{\lambda_0+\delta} |_{H_0})| \leq \\ &\leq \dim H_0 = \dim \ker L_{\lambda_0}. \end{aligned}$$

□

Since the set $B(\psi)$ of bifurcation points of ψ is a subset of $\Sigma(L)$, its cardinality is a finite number N . Using again the additivity and the normalization properties of the spectral flow, we obtain

$$|\text{sf}(L, I)| = \left| \sum_{\lambda \in \Sigma(L)} \text{sf}(L, \lambda) \right| \leq \sum_{\lambda \in \Sigma(L)} |\text{sf}(L, \lambda)|. \quad (10)$$

On the other hand, since the points of $\Sigma(L) \setminus B(\psi)$ do not give any positive contribution to the right hand side of (10), we have

$$|\text{sf}(L, I)| \leq \sum_{\lambda \in B(\psi)} |\text{sf}(L, \lambda)| \leq Nm,$$

by the previous lemma. Consequently the number of bifurcation points N is bounded from below by the quotient $|\text{sf}(L, I)|/m$.

5 Proof of Theorem 2.2 and Corollary 2.4

In order to simplify notations, we will henceforth drop the domain I of the path from the notation and use $\text{sf}(L)$ to denote $\text{sf}(L, I)$.

We will show at first the assertion i). Assume that $\gamma : I \rightarrow \Lambda$ is an admissible path such that $\text{sf}(L \circ \gamma) \neq 0$. Suppose that $\Lambda \setminus B(\psi)$ is connected. Join $\gamma(1)$ with $\gamma(0)$ by a path $\tilde{\gamma} : I \rightarrow \Lambda$ such that $\tilde{\gamma}(I) \cap B(\psi) = \emptyset$. We must have $\text{sf}(L \circ \tilde{\gamma}) = 0$. Otherwise, by Theorem 2.1, the family of functionals $\phi : I \times U \rightarrow \mathbb{R}$ defined by $\phi(t, u) = \psi(\gamma(t), u)$ would have a bifurcation point t_* . But then, $\gamma(t_*)$ would be a point of intersection of $\tilde{\gamma}(I)$ with $B(\psi)$.

From the additivity of the spectral flow, we see that

$$\text{sf}(L \circ \gamma) = \text{sf}(L \circ \gamma) + \text{sf}(L \circ \tilde{\gamma}) = \text{sf}(L \circ (\gamma * \tilde{\gamma})),$$

where $\gamma * \tilde{\gamma}$ denotes the concatenation of γ and $\tilde{\gamma}$. Since $\gamma * \tilde{\gamma}$ is a closed path, by assumption (A), $\text{sf}(L \circ \gamma) = \text{sf}(L \circ (\gamma * \tilde{\gamma})) = 0$, a contradiction.

Let us now prove ii). By choosing a point $\lambda_0 \in \Lambda \setminus \Sigma(L)$, we can associate an index $i(C)$ to each component of $\Lambda \setminus B(\psi)$ which contains elements of $\Lambda \setminus \Sigma(L)$ by defining $i(C) = \text{sf}(L \circ \gamma)$ where γ is any admissible path joining λ_0 with a point of C . Much as in i), $\text{sf}(L \circ \gamma)$ is independent from the choice of a point in $C \cap (\Lambda \setminus \Sigma(L))$, and hence the index is well defined. But then, for any admissible path γ we have that

$$\text{sf}(L \circ \gamma) = i(C_{\gamma(0)}) - i(C_{\gamma(1)}).$$

Therefore if the number of components were finite, the function $\gamma \rightarrow \text{sf}(L \circ \gamma)$ would take only a finite number of values, contradicting the assumption.

In order to prove iii), we observe at first that, given any admissible path γ such that $L \circ \gamma$ has only isolated singular points, we can find another path $\tilde{\gamma}$ with the same property but which never returns to the same component. For this, let $\mu_1 < \mu_2 < \dots < \mu_k$ be the singular points of $L \circ \gamma$ and set $\mu_0 = 0$, $\mu_{k+1} = 1$. We enumerate the components of $\Lambda \setminus B(\psi)$ traversed by γ in an increasing order according to the ordering of μ_i . We obtain in this way a list of components (C_0, C_1, \dots, C_k) with $\gamma(0) \in C_0$ and $\gamma(1) \in C_k$. If there is an index pair $i < j$ such that $C_i = C_j = C$, we can obtain a shorter path γ' by connecting $\gamma(\mu_i)$ with $\gamma(\mu_{j+1})$ by a path δ such that $\delta(0, 1) \subset C$. The path γ' has the same properties as γ , but C will appear in its list one time less. Iterating this procedure we obtain a path $\tilde{\gamma}$ which never traverses twice the same component. Now the assertion follows from *ii)* of Theorem 2.1 applied to the path $L \circ \tilde{\gamma}$.

In order to prove Corollary 2.4 in the case when Λ is a smooth manifold, it is enough to observe that, by density of transversality, in the above reduction procedure we can approximate the path δ with a differentiable path contained in the component C that is transversal to \mathcal{S} obtaining in this way a new path joining $\gamma(\mu_i)$ with $\gamma(\mu_{j+1})$, which composed with L will still have a finite number of singular points. On topological manifolds, using the dimension assumption, we can find inside C a path δ which avoids $\Sigma(L)$ because sets of dimension $n - 2$ or less cannot separate C . \square

6 Bifurcation of periodic orbits for perturbations of autonomous Hamiltonian systems

We assume that Λ is a connected topological space and $\mathcal{H} : \Lambda \times \mathbb{R} \times \mathbb{R}^{2n} \rightarrow \mathbb{R}$ is a continuous function such that each \mathcal{H}_λ is C^2 and its first and second partial derivatives depend continuously on $\lambda \in \Lambda$. Moreover, we require that $\mathcal{H}(\lambda, t, u)$ is 2π -periodic with respect to t , and that $\mathcal{H}(\lambda, t, 0) = 0$ for all $(\lambda, t) \in \Lambda \times \mathbb{R}$. Let us consider Hamiltonian systems

$$\begin{cases} \sigma u'(t) + \nabla_u \mathcal{H}(\lambda, t, u(t)) = 0, & t \in [0, 2\pi] \\ u(0) = u(2\pi), \end{cases} \quad (11)$$

where σ denotes the standard symplectic matrix. Note that $u \equiv 0$ is a solution of (11) for all $\lambda \in \Lambda$. In what follows we shall also assume the two following conditions:

(H1) There are constant $a, b \geq 0$ and $r > 1$ such that

$$\begin{aligned} |\nabla_u \mathcal{H}(\lambda, t, u)| &\leq a + b|u|^r, \\ |D_u \nabla_u \mathcal{H}(\lambda, t, u)| &\leq a + b|u|^r, \quad (\lambda, t, u) \in \Lambda \times \mathbb{R} \times \mathbb{R}^{2n}. \end{aligned}$$

(H2) There exists a continuous family A_λ of real time-independent symmetric $2n \times 2n$ matrices such that

$$\mathcal{H}(\lambda, t, u) = \frac{1}{2} \langle A_\lambda u, u \rangle + R(\lambda, t, u), \quad (\lambda, t, u) \in \Lambda \times \mathbb{R} \times \mathbb{R}^{2n},$$

where $\nabla_u R(\lambda, t, u) = o(\|u\|)$ as $\|u\| \rightarrow 0$, uniformly in (λ, t) .

Let us recall that the Hilbert space $H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$ consists of all functions $u : [0, 2\pi] \rightarrow \mathbb{R}^{2n}$ such that

$$u(t) = c_0 + \sum_{k=1}^{\infty} a_k \sin kt + b_k \cos kt,$$

where $c_0, a_k, b_k \in \mathbb{R}^{2n}$, $k \in \mathbb{N}$, and $\sum_{k=1}^{\infty} k(|a_k|^2 + |b_k|^2) < \infty$. The scalar product on $H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$ is defined by

$$\langle u, v \rangle_{H^{\frac{1}{2}}} = \langle c_0, \tilde{c}_0 \rangle + \sum_{k=1}^{\infty} k(\langle a_k, \tilde{a}_k \rangle + \langle b_k, \tilde{b}_k \rangle),$$

where \tilde{c}_0 and \tilde{a}_k, \tilde{b}_k denote the Fourier coefficients of $v \in H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$. Let

$$\Gamma : H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n}) \times H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n}) \rightarrow \mathbb{R}$$

be the unique continuous extension of the bounded bilinear form

$$\tilde{\Gamma}(u, v) = \int_0^{2\pi} \langle \sigma u'(t), v(t) \rangle dt$$

defined on the dense subspace $H^1(S^1, \mathbb{R}^{2n})$ of $H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$, which consists of all absolutely continuous functions $u : S^1 \rightarrow \mathbb{R}^{2n}$ having a square integrable derivative. We consider the map

$$\psi : \Lambda \times H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n}) \rightarrow \mathbb{R}, \quad \psi_\lambda(u) = \frac{1}{2} \Gamma(u, u) + \int_0^{2\pi} \mathcal{H}(\lambda, t, u(t)) dt.$$

It is a standard result that each ψ_λ is C^2 under the growth conditions (H1). Moreover,

$$\langle \nabla_u \psi_\lambda u, v \rangle_{H^{\frac{1}{2}}} = \Gamma(u, v) + \int_0^{2\pi} \langle \nabla_u \mathcal{H}(\lambda, t, u(t)), v(t) \rangle dt, \quad v \in H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n}),$$

and consequently, the critical points of ψ_λ are precisely the weak solutions of the Hamiltonian system (11). In particular, $u \equiv 0 \in H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$ is a critical point of ψ_λ , whose Hessian is defined by

$$\langle L_\lambda u, v \rangle_{H^{\frac{1}{2}}} = \Gamma(u, v) + \int_0^{2\pi} \langle A_\lambda u(t), v(t) \rangle dt.$$

By the compactness of the embedding $H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n}) \hookrightarrow L^2(S^1, \mathbb{R}^{2n})$, the self-adjoint operators L_λ are Fredholm. Moreover, L_λ is invertible if and only if the matrix A_λ is non-resonant, i.e., the spectrum of σA_λ does not contain integral multiples of the imaginary unit i . We now define for any $2n \times 2n$ matrix A , a sequence of $4n \times 4n$ matrices by

$$L^0(A) = \begin{pmatrix} A & 0 \\ 0 & A \end{pmatrix}, \quad L^k(A) = \begin{pmatrix} \frac{1}{k}A & \sigma \\ -\sigma & \frac{1}{k}A \end{pmatrix}, \quad k \in \mathbb{N}.$$

Note that for k sufficiently large, the matrices $L^k(A)$ become arbitrarily close to an invertible symmetric matrix of vanishing signature. Hence $\text{sgn } L^k(A) = 0$ for sufficiently large k . This fact allows us to define the *index* $i(A)$ of the matrix A by

$$i(A) = \frac{1}{2} \sum_{k=1}^{\infty} \text{sgn } L^k(A).$$

It was shown in [FPR00, §1] that, if $\Lambda = [a, b]$ is a compact interval and the matrices A_b and A_a are non-resonant, so that L has invertible ends, then

$$\text{sf}(L) = i(A_b) - i(A_a). \quad (12)$$

As an immediate consequence of Theorem 2.2 we obtain:

Proposition 6.1. *Let Λ be a connected topological space. Assume that (H1) and (H2) hold for \mathcal{H} .*

- i) If there exist $\lambda, \mu \in \Lambda$ such that the matrices A_λ, A_μ are non-resonant and $i(A_\lambda) \neq i(A_\mu)$, then $\Lambda \setminus B(\psi)$ is disconnected.*
- ii) If there exists a sequence $\{\lambda_n\}_{n \in \mathbb{N}} \subset \Lambda$ such that A_{λ_n} is non-resonant for all $n \in \mathbb{N}$ and $\lim_{n \rightarrow \infty} |i(A_{\lambda_n})| = \infty$, then $\Lambda \setminus B(\psi)$ has infinitely many path components.*
- iii) If $B(\psi) = \{\lambda : A_\lambda \text{ is resonant}\}$, then any path γ joining two non-resonant parameters λ and μ such that $A \circ \gamma$ has only isolated resonant points must cross at least $\frac{|i(A_\lambda) - i(A_\mu)|}{2n} + 1$ components of $\Lambda \setminus B(\psi)$.*

From Corollary 2.4 we obtain:

Corollary 6.2. *Let Λ, \mathcal{H} be as in the previous proposition. Assume moreover that Λ is a smooth n -manifold and that the map A is smooth and transversal to the variety \mathcal{R} of all resonant matrices. Assume moreover that there exists a path $\gamma: (-\infty, \infty) \rightarrow \Lambda$ such that $A \circ \gamma$ is a positive path of symmetric matrices. Then, irrelevant of the choice of the higher order perturbation R , the number of connected components of $\Lambda \setminus B(\psi)$ is not less than $\frac{k}{2n} + 1$, where k is the number of intersections of the spectrum of $\sigma A \circ \gamma$ with $i\mathbb{Z}$.*

For example: let \mathcal{A} be the space of all symmetric $2n \times 2n$ matrices and consider the problem of bifurcation of periodic solutions for the parametrized system of Hamiltonian equations (11) with Hamiltonian function $\mathcal{H}(A, t, u) = \langle Au, u \rangle + R(A, t, u)$, where $A \in \mathcal{A}$ and R is any family of C^2 periodic functions continuously parametrized by \mathcal{A} , such that $\nabla_u R(A, t, u) = o(\|u\|)$ uniformly in (A, t) . The positive path $\gamma(\lambda) = \lambda \text{Id}$, is resonant for all $\lambda \in \mathbb{Z}$. Therefore, the set $\mathcal{A} \setminus B(\psi)$ must have infinitely many path components. Note however that $\Sigma(L) = B(\psi) = \mathcal{R}$ in this case.

7 Extended spectral flow and comparison theorems

For what follows it will be convenient for us to extend the definition of the spectral flow to general paths in $\Phi_S(H)$ with not necessarily invertible end-points. For a non-invertible operator $T \in \Phi_S(H)$, 0 is always an isolated eigenvalue of finite multiplicity. Hence there exists a $\delta > 0$ such that $T + \lambda \text{Id}$ is invertible for $0 < \lambda \leq \delta$. We define the spectral flow of a general path $L: I \rightarrow \Phi_S(H)$ as the spectral flow of the translated path

$$\text{sf}(L) = \text{sf}(L + \delta \text{Id}), \quad (13)$$

where $\delta > 0$ is as above. Clearly, the right hand side does not depend on the choice of δ . The resulting function is additive under concatenation and direct sum. It is homotopy invariant under homotopies keeping the end-points fixed. As a matter of fact, it is invariant under homotopies which keep the end points in a fixed stratum of Σ , but we will not make use of this property here.

The cone of positive operators defines an order in $\mathcal{L}(H)$ compatible with its topology. Given two bounded self-adjoint operators $T, S \in \mathcal{L}_S(H)$ we say that $T \geq S$ whenever $T - S$ is positive, and that $T > S$ whenever $T - S$ is positive definite, i.e., if there exists $c > 0$ such that $\langle (T - S)h, h \rangle \geq c \|h\|^2$ for all $h \in H$. A path $L: I \rightarrow \mathcal{L}_S(H)$ of self-adjoint operators is *non-decreasing* if $L_\lambda \geq L_\mu$ whenever $\lambda \geq \mu$ and it is *strictly increasing* if $L_\lambda > L_\mu$ whenever $\lambda > \mu$.

Theorem 7.1. *Let $H: [0, 1] \times [a, b] \rightarrow \Phi_S(H)$ be a homotopy such that $H(\cdot, a)$ is non-increasing and $H(\cdot, b)$ is non-decreasing, then*

$$\text{sf } H(0, \cdot) \leq \text{sf } H(1, \cdot).$$

If two paths L and M are such that $L - M$ is a path of compact operators, then the family $H(t, \lambda) = M + t(L - M)$ is a homotopy in $\Phi_S(H)$ between them. It verifies the hypothesis of the previous theorem whenever $L_a \leq M_a$ and $M_b \leq L_b$. Therefore we have:

Corollary 7.2. *Let $L, M: [a, b] \rightarrow \Phi_S(H)$ be paths such that $L_\lambda - M_\lambda$ is compact for each $\lambda \in I$. If $L_a \leq M_a$ and $M_b \leq L_b$, then*

$$\text{sf } M \leq \text{sf } L.$$

Theorem 7.1 is an easy consequence of the following proposition:

Proposition 7.3. *If $L: [a, b] \rightarrow \Phi_S(H)$ is non-decreasing, then $\text{sf}(L) \geq 0$.*

Proof. Let us choose, for each $\lambda \in I = [a, b]$, a ball $B_\lambda = B(L_\lambda, \varepsilon_\lambda) \subset \Phi_S(H)$ and take a partition π of I of mesh less than the Lebesgue number of the covering $\mathcal{U} = \{L^{-1}(B_\lambda) : \lambda \in I\}$. Then the image $L(I')$ of any interval I' of the partition is contained in some ball $B_{I'} \subset \Phi_S(H)$.

Select an interval $J = [c, d]$ of the partition π , and the straight line segment

$$N_\lambda = (d - c)^{-1}[(\lambda - c)L_d + (d - \lambda)L_c]$$

joining L_c with L_d . Consider the affine homotopy $H(t, \lambda) = (1 - t)L_\lambda + tN_\lambda$ between the path $M = L|_J$ and N . Each $H(t, \lambda)$ is an element of $\Phi_S(H)$ because $L|_J(J)$ is contained in B_J . Since H is a homotopy in $\Phi_S(H)$ with fixed end-points, we have $\text{sf } M = \text{sf } N = \text{sf}(N + \delta \text{Id})$, where δ is as in (13) and small enough in order to have $(N + \delta \text{Id})(J) \subset B_J$.

Now, if we take a sufficiently small $\mu > 0$, we have that the segment R , given by

$$R_\lambda = (d - c)^{-1}[(\lambda - c)(L_d + \mu \text{Id}) + (d - \lambda)(L_c + \mu \text{Id})],$$

is homotopic in $\Phi_S(H)$ to N by an affine homotopy keeping end-points invertible. Therefore, $\text{sf } M = \text{sf } R$. But now R is a differentiable path and by direct calculation we see that, whenever $\ker R_\lambda \neq 0$, the crossing form $\mathcal{Q}(R, \lambda)$ is positive definite and hence non-degenerate. The spectral flow in this case is simply the sum of the dimensions of the corresponding kernels. Hence

$$\text{sf}(L|_J) = \text{sf}(R) = \sum_{\lambda \in J} \dim \ker R_\lambda \geq 0.$$

The proposition is obtained by summing over all intervals of the chosen partition. \square

In order to conclude the proof of the comparison theorem from the above proposition, it is enough to recall that the spectral flow along a closed path is invariant by free homotopies. For a proof of this fact see [FPR99, Proposition 3.7]. In particular, since the rectangle $D = [0, 1] \times [a, b]$ is contractible, the spectral flow of the restriction of H to its boundary ∂D must be zero. From this it follows that $\text{sf}(H(0, \cdot)) \leq \text{sf}(H(1, \cdot))$, since $\text{sf}(H(1 - \cdot, a)) = -\text{sf}(H(\cdot, a)) \geq 0$ and $\text{sf}(H(\cdot, b)) \geq 0$ by Proposition 7.3.

8 Estimates for the number of bifurcation points for general systems

In this section we estimate from below the number of bifurcation points for periodic orbits bifurcating from a given branch of a family of non-autonomous Hamiltonian systems. Our aim is to obtain the estimates directly in terms of the coefficients of the linearization along the trivial branch.

Here the parameter space Λ will be the interval $[0, 1]$. Moreover we assume that $\mathcal{H} : [0, 1] \times \mathbb{R} \times \mathbb{R}^{2n} \rightarrow \mathbb{R}$ is a continuous function, which is 2π -periodic with respect to t , and such that each \mathcal{H}_λ is C^2 and its first and second partial derivatives depend continuously on (λ, t, u) . We also assume $\mathcal{H}(\lambda, t, 0) = 0$ for all $(\lambda, t) \in I \times \mathbb{R}$ and take as the trivial branch of periodic solutions the stationary branch $u(t) \equiv 0$. It is shown in [FPR99] that bifurcation from a general branch of periodic solutions can be easily reduced to the above case.

Much as before, we are looking for points of bifurcation of nontrivial 2π -periodic solutions of (11) from the stationary branch, but here we do not assume that the system (11) is a higher order perturbation of an autonomous system. Namely, while keeping the assumption (H1) we drop (H2). We still have that critical points of

$$\psi_\lambda(u) = \frac{1}{2} \Gamma(u, u) + \int_0^{2\pi} \mathcal{H}(\lambda, t, u(t)) dt,$$

are weak solutions of (11). Moreover the Hessian L_λ of ψ_λ at $u \equiv 0$ is given by

$$\langle L_\lambda u, v \rangle_{H^{\frac{1}{2}}} = \Gamma(u, v) + \int_0^{2\pi} \langle A_\lambda(t)u(t), v(t) \rangle dt, \quad (14)$$

where $A_\lambda(t) = D_u \nabla_u \mathcal{H}_\lambda(t, 0)$.

In the general case of a time depending system $\sigma u'(t) + A_\lambda(t)u(t)$ we do not have an index defined directly in terms of the coefficients as before. However, the spectral flow $\text{sf}(L, I)$ can still be computed from the relative Conley-Zehnder index of the path $\{P_\lambda\}_{\lambda \in I}$ of Poincaré maps (cf. [FPR00]). On its turn, the relative Conley-Zehnder index of the path P can be explicitly computed from the eigenvalues of P_0 and P_1 . Nevertheless the Poincaré map can be only obtained by integrating the linearization and cannot be considered as computable from the coefficients.

When $A_i(t) \equiv A_i, i = 0, 1$, are constant, then one can use (12) in order to estimate from below by $\frac{|i(A_1) - i(A_0)|}{2n}$ the number of bifurcation points for paths verifying the hypothesis of ii) in Theorem 2.1. Using the Floquet reduction one can always deform the linearized equation to one with constant coefficients. However, this procedure involves the monodromy operator too. In view of this, the estimate provided below, while rough, appears to be reasonable. It is based on the numerical range of the matrices $A_i(t), i = 0, 1$. Let $\{\mu_1^i(t) \leq \mu_2^i(t) \leq \dots \leq \mu_{2n}^i(t)\}$ be the eigenvalues of $A_i(t), i = 0, 1$. Set $\alpha_i = \inf\{\mu_1^i(t) : t \in I\}$ and $\beta_i = \sup\{\mu_{2n}^i(t) : t \in I\}$. Then we have

$$\alpha_i \text{Id} \leq A_i(t) \leq \beta_i \text{Id}, \quad i = 0, 1. \quad (15)$$

Consider the path $B_\lambda = (\beta_0 + \lambda(\alpha_1 - \beta_0)) \text{Id}$ and let M be the path of operators on $H^{\frac{1}{2}}$ defined by

$$\langle M_\lambda u, v \rangle_{H^{\frac{1}{2}}} = \Gamma(u, v) + \int_0^{2\pi} \langle B_\lambda u(t), v(t) \rangle dt. \quad (16)$$

Then L and M are Calkin equivalent, since both are compact perturbations of the operator \mathcal{D} representing the quadratic form Γ against the scalar product in $H^{\frac{1}{2}}$. Moreover,

$$\langle (L_\lambda - M_\lambda)u, v \rangle_{H^{\frac{1}{2}}} = \int_0^{2\pi} \langle (A_\lambda(t) - B_\lambda)u(t), v(t) \rangle dt.$$

Taking $\lambda = 0, 1$ and using (15) we see that the paths L and M verify the hypothesis of Corollary 7.2. Therefore,

$$\text{sf } M \leq \text{sf } L. \quad (17)$$

In the same way taking $C_\lambda = \alpha_0 + \lambda(\beta_1 - \alpha_0) \text{Id}$ and applying Corollary 7.2 to the operator path N induced on $H^{\frac{1}{2}}$ by $\sigma u'(t) + C_\lambda u(t)$, we obtain

$$\text{sf } L \leq \text{sf } N. \quad (18)$$

On the other hand, it follows from the definition of the extended spectral flow in (13) that the formula (2), relating the spectral flow of a path of compact perturbations of a fixed operator with the relative Morse index of its end-points holds even when the end-points are non-invertible, provided that we consider as $E^+(T)$ the spectral subspace corresponding the spectrum of T in $(0, +\infty)$ and $E^-(T)$ the spectral subspace of the spectrum in $(-\infty, 0]$. With the above setting we have:

$$\begin{aligned} \text{sf}(M) &= \mu_{\text{rel}}(M_0, M_1) \\ &= \dim(E^-(M_0) \cap E^+(M_1)) - \dim(E^-(M_1) \cap E^+(M_0)), \end{aligned} \quad (19)$$

an similarly for N .

Let us introduce two unbounded self-adjoint operators $\mathcal{M}_0, \mathcal{M}_1$ with domain

$$\mathcal{D} = H^1(S^1; \mathbb{R}^{2n}) \subset L^2(S^1; \mathbb{R}^{2n}).$$

Namely, $\mathcal{M}_0 = \sigma u'(t) + \beta_0 u(t)$ and $\mathcal{M}_1 = \sigma u'(t) + \alpha_1 u(t)$. Since $H^{\frac{1}{2}}(S^1, \mathbb{R}^{2n})$ is the form space of the operator $\sigma u'(t)$, it follows that M_i are the form extensions of \mathcal{M}_i . While the spectra of M_i and \mathcal{M}_i are necessarily different, it follows from the regularity of solutions of (16) that they

have the same "positive" and "negative" eigenvectors. Hence we can compute the right hand side of (19), in terms of $E^\pm(\mathcal{M}_i)$ as well. For this, let us identify \mathbb{R}^{2n} with $\mathbb{C}^n \equiv \mathbb{R}^n + i\mathbb{R}^n$ via

$$u = (x, y) \equiv z = x + iy.$$

Under the above identification, the action of σ coincides with the multiplication by i and $\mathcal{M}_i, i = 0, 1$, become:

$$\begin{cases} iz'(t) + \beta_0 z(t) = 0 \\ z(0) = z(2\pi) \end{cases} \quad \text{and} \quad \begin{cases} iz'(t) + \alpha_1 z(t) = 0 \\ z(0) = z(2\pi). \end{cases} \quad (20)$$

Their eigenvalues are of the form $m + \beta_0$ and $m + \alpha_1$, with $m \in \mathbb{Z}$ respectively, with (complex) multiplicity n .

Given real numbers μ and ν , define

$$\Delta(\mu, \nu) = \begin{cases} \#\{i \in \mathbb{Z} : \mu \leq i < \nu\} & \text{if } \mu \leq \nu \\ -\#\{i \in \mathbb{Z} : \nu \leq i < \mu\} & \text{if } \nu \leq \mu. \end{cases} \quad (21)$$

Then clearly

$$\mu_{rel}(M_0, M_1) = \mu_{rel}(\mathcal{M}_0, \mathcal{M}_1) = 2n \Delta(\beta_0, \alpha_1).$$

A similar computation shows that

$$\mu_{rel}(N_0, N_1) = \mu_{rel}(\mathcal{N}_0, \mathcal{N}_1) = 2n \Delta(\alpha_0, \beta_1).$$

By (17), (18) and (19) we have

$$2n \Delta(\beta_0, \alpha_1) = \mu_{rel}(M_0, M_1) \leq \text{sf } L \leq \mu_{rel}(N_0, N_1) = 2n \Delta(\alpha_0, \beta_1).$$

From this and Theorem 2.1 ii) we can conclude that

Proposition 8.1. *Assume that the linearization of the problem (11) along the stationary branch*

$$\begin{cases} \sigma u'(t) + A_\lambda(t)u(t) = 0 \\ u(0) = u(2\pi), \end{cases} \quad (22)$$

admits only trivial solutions for all but a finite number of values of λ .

Then

- i) If $\beta_0 < \alpha_1$, the family (11) has at least $\Delta(\beta_0, \alpha_1)$ points of bifurcation of periodic solutions from the stationary branch.*
- ii) If $\beta_1 < \alpha_0$, the family (11) has at least $-\Delta(\alpha_0, \beta_1)$ bifurcation points.*

Remark 8.2. Notice that we do not have to assume that the path is admissible. Indeed, it is enough to apply Theorem 2.1 ii) on $[\delta, 1 - \delta]$ for δ small enough.

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