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1 **Challenges and perspectives on functional interpretations of australopith**
2 **postcrania and the reconstruction of hominin locomotion**

3

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16

17 **Abstract**

18 In 1994, Hunt published the ‘postural feeding hypothesis’ — a seminal paper on the origins of
19 hominin bipedalism—founded on the detailed study of chimpanzee positional behavior and the
20 functional inferences derived from the upper and lower limb morphology of the *Australopithecus*
21 *afarensis* A.L. 288-1 partial skeleton. Hunt proposed a model for understanding the potential
22 selective pressures on hominins, made robust, testable predictions based on *Au. afarensis*
23 functional morphology, and presented a hypothesis that aimed to explain the dual functional
24 signals of the *Au. afarensis* and, more generally, early hominin postcranium. Here we synthesize
25 what we have learned about *Au. afarensis* functional morphology and the dual functional signals
26 of two new australopith discoveries with relatively complete skeletons (*Australopithecus sediba*

27 and StW 573 '*Australopithecus prometheus*'). We follow this with a discussion of three research
28 approaches that have been developed for the purpose of drawing behavioral inferences in early
29 hominins: 1) developments in the study of extant apes as models for understanding hominin
30 origins; 2) novel and continued developments to quantify bipedal gait and locomotor economy in
31 extant primates to infer the locomotor costs from the anatomy of fossil taxa; and 3) novel
32 developments in the study of internal bone structure to extract functional signals from fossil
33 remains. In conclusion of this review, we discuss some of the inherent challenges of the
34 approaches and methodologies adopted to reconstruct the locomotor modes and behavioral
35 repertoires in extinct primate taxa, and notably the assessment of habitual terrestrial bipedalism
36 in early hominins.

37

38 **Keywords:** *Australopithecus*; Bone functional adaptation; Trabecular bone; Cortical bone;
39 African apes

40 1. Introduction

41 Since the discovery of numerous *Australopithecus afarensis* postcranial remains at Hadar,
42 Ethiopia, in the early 1970s (Taieb et al., 1974; Johanson and Taieb, 1976; Bush et al., 1982;
43 Johanson et al., 1982), which built upon a collection of australopith fossils already uncovered in
44 South Africa (e.g., Dart, 1925; Broom and Schepers, 1946; Broom and Robinson, 1949; Straus,
45 1948; Robinson, 1972), paleoanthropologists have increasingly focused on the inferences of
46 posture and locomotion that can be drawn from fossil hominin (i.e., humans and their fossil
47 relatives) skeletons. This focus on functional morphology led to contentious debates but also the
48 development of new hypotheses, analytical approaches, and methods. Functional inferences have
49 typically centered on understanding the form of bipedalism in which australopiths engaged and
50 the relative importance of arboreality in their positional repertoire (e.g., Lovejoy, 1985; Stern
51 and Susman, 1983; Susman et al., 1984; Senut and Tardieu, 1985; Latimer, 1991).
52 Reconstructions of australopith locomotion and posture were made within the broader context of
53 two foundational and longstanding evolutionary aims of paleoanthropology, 1) the identification
54 of the primary locomotor behavior from which bipedalism evolved; and 2) understanding the
55 evolutionary or selective process(es) leading to the establishment of hominin bipedal
56 dependence. Multiple hypotheses about the primary locomotor behavior from which bipedalism
57 evolved (e.g., Keith, 1923; Tuttle, 1969; Richmond and Strait, 2000) and the selective drivers of
58 bipedalism have been proposed (e.g., Lovejoy, 1981; Darwin, 1987; Wheeler, 1991; Hunt, 1994),
59 which remain contentious due to a paucity of Late Miocene and Early Pliocene hominin fossils
60 and the virtual absence of an African ape fossil record (Crompton et al., 2008; Harcourt-Smith,
61 2010; Wood and Harrison, 2011; Andrews, 2020; Almécija et al., 2021; but see McBearty and
62 Jablonski, 2005; Pickford et al., 2008). In the absence of fossil evidence near the time of the

63 hominin-panin divergence, these hypotheses have traditionally relied heavily on functional
64 interpretation of australopith anatomy, observations of extant primate postural and locomotor
65 behaviors, and the influence of phylogeny. One such hypothesis is the ‘postural feeding
66 hypothesis’ proposed by Hunt (1994) in “The evolution of human bipedality: Ecology and
67 functional morphology” (see also Hunt, 1996). In this review, we use Hunt’s (1994) seminal
68 paper on the origins of hominin bipedalism as inspiration for how the australopith postcranium
69 has influenced our hypotheses about the selective pressures surrounding hominin bipedalism and
70 the value of living primate models and ecological context in our interpretation of hominin
71 functional morphology. We start, with a brief review of the historical context in which Hunt’s
72 (1994) ‘postural feeding hypothesis’ was developed. We then further review some of the new
73 australopith fossils discovered and new methods developed since 1994 that have helped
74 paleoanthropologists to gain a better understanding of australopith diversity and make more
75 informed functional inferences of the fossil morphology.

76

77 *1.1. Historical context of australopith locomotion and the emergence of hominin bipedalism*

78 Hypotheses about the locomotor or postural behavior from which bipedalism emerged range
79 from terrestrial knuckle-walking to arboreal vertical clinging or brachiation and from pronograde
80 to orthograde postures (see reviews in Richmond et al., 2001; Harcourt-Smith and Aiello, 2004;
81 Crompton et al., 2008; Senut et al., 2018). Keith (1903, 1923) was the first to explicitly propose
82 hominoid-like, orthograde ancestor based on morphological features of the upper limb that are
83 shared between humans and suspensory apes. Keith (1923) proposed three stages of hominoid
84 evolution: a hylobatid-like (‘hylobatian’) ancestor that evolved into a larger-bodied African ape-
85 like (‘troglodytian’) ancestor capable of orthograde climbing and terrestrial knuckle-walking,

86 which in turn evolved into a bipedal ('plantigrade') hominin (see also Morton, 1926). Tuttle
87 (1969, 1975, 1981; Tuttle et al., 1974) further developed Keith's 'brachiating' hypothesis
88 through the study of great ape hand postures and anatomy, highlighting the lack of anatomical
89 evidence for a knuckle-walking phase in hominin evolution. Tuttle (1969:p. 960) proposed "that
90 the ancestors of [hu]man probably engaged in some form of suspensory posturing and that they
91 assumed bipedal postures very soon after venturing to the ground." It is important to note that
92 neither Keith nor Tuttle at this time had a conception of hominoid phylogeny [although the
93 seminal research on hominid proteins by Goodman (1962, 1963) was published]. Tuttle (1969)
94 supported a closer evolutionary relationship between *Pan* and *Gorilla* (and, in fact, grouped
95 gorillas within in the *Pan* genus) to the exclusion of humans. Thus knuckle walking could be
96 considered a synapomorphic behavior of African apes in his hypothesis that human bipedalism
97 evolved from a suspensory ancestor.

98 With greater evidence and acceptance of the phylogenetic relationship between *Pan* and
99 humans (Goodman, 1963; Sarich and Wilson, 1967; Miyamoto et al., 1987), Washburn (1967:p.
100 23) proposed, albeit with little morphological evidence, that hominin bipedalism evolved from a
101 terrestrial knuckle-walking ancestor because it offers a logical 'intermediate condition' in which,
102 as bipedalism is positively selected, the long upper limb can be used less and less. The terrestrial
103 knuckle-walking hypothesis continued to gain support through comparative anatomy, notably
104 synapomorphic features of the upper limb, wrist, and hand shared between humans and African
105 apes (Marzke, 1971; Corruccini, 1978; Shea and Inouye, 1993; Gebo, 1992; 1996; Begun, 1993,
106 1994; Richmond and Strait, 2000; Richmond et al., 2001) and the identification of 'knuckle-
107 walking features' in australopiths (McHenry, 1983; Richmond and Strait, 2000). Parsimony also
108 played a key supporting role with the sentiment that knuckle-walking locomotion is too unusual

109 to have evolved independently in *Pan* and *Gorilla* (Gebo, 1992, 1996; Begun, 1994; Richmond
110 and Strait, 2000; Richmond et al., 2001). Although other hypotheses on the locomotor or postural
111 origin of hominin bipedalism emphasize arboreality, most notably a vertical climbing origin
112 supported by biomechanical similarities between primate vertical climbing and human
113 bipedalism (Prost, 1980; Fleagle et al., 1981; Stern and Susman, 1981; Ishida et al., 1985; Senut,
114 1988), the terrestrial knuckle-walking hypothesis envisions a locomotor repertoire that also
115 includes arboreal climbing and some suspension (Richmond et al., 2001).

116 The role of arboreality has been central in the debate over early hominin functional
117 morphology, and particularly that of australopiths, since the early 1980s, following the
118 publication of the *Au. afarensis* fossils from Hadar (Taieb et al., 1974; Johanson and Taieb,
119 1976; Bush et al., 1982; Johanson et al., 1982). This debate stems from the duality of the *Au.*
120 *afarensis*, and that of australopiths more generally, postcranium that can be broadly summarized
121 as possessing human-like lower limbs and ape-like upper limbs. The functional interpretation of
122 *Au. afarensis* morphology is typically divided into two camps that differ in the significance they
123 grant to the ape-like morphological features, as aptly summarized by Daegling (2022; see also
124 Ward, 2002). In the ‘efficiency camp’ researchers focused on human-like (i.e., derived)
125 morphological features and biomechanical data to support the hypothesis that *Au. afarensis* had a
126 bipedal gait similar to that of humans i.e., striding gait with extended hip and knee (Lovejoy et
127 al., 1973; Lovejoy, 1975, 1978, 1988; Day and Wickens, 1980; White, 1980; Latimer, 1983,
128 1991; Ohman, 1986; Latimer et al., 1987; Latimer and Lovejoy, 1989, 1990; Crompton et al.,
129 1998; Kramer, 1999). In this camp, *Au. afarensis* was reconstructed as fully committed to
130 bipedalism because energetically costly bipedalism would not be positively selected, thus

131 compromising any ability to climb competently. Arboreal behaviors were viewed as a trivial
132 component of australopith positional repertoire.

133 In contrast, researchers in the ‘compromise camp’ incorporated both basal and derived
134 morphology as well as biomechanical data to support the hypothesis that *Au. afarensis* engaged
135 in a bipedal gait that was unlike that of modern humans and, instead, was compliant (i.e., bent
136 hip and bent knee) and energetically costly (Senut, 1980; Stern and Susman, 1981, 1983, 1991;
137 Feldesman, 1982; Jungers, 1982, 1991; Jungers and Stern, 1983; Schmid, 1983; Rose, 1984,
138 1991; Susman et al., 1984; Deloison, 1985, 1991, 1992; Tardieu 1986a, b; Susman and Stern,
139 1991; Duncan et al., 1994; Stern, 2000). This energetically costly bipedalism allowed *Au.*
140 *afarensis* to be arboreally competent because trees were essential to, for example, foraging and
141 avoiding predation (Susman et al., 1984; Preuschoft and Witte, 1991; Rak, 1991; Cartmill and
142 Schmitt, 1996; MacLatchy, 1996; Schmitt et al., 1996, 1999; Ruff, 1998; Stern, 1999; also see
143 below)

144 Numerous hypotheses have also been offered regarding the selective drivers underlying the
145 origin of bipedalism (Rose, 1991, and references therein). These hypotheses are dependent not
146 only on the functional interpretation of australopith morphology and on the form of positional
147 behavior from which bipedalism evolved, but also the paleoecological context in which early
148 hominins may have been living. Many of the initial hypotheses linked the origin of bipedalism to
149 a savanna landscape, either the traditional view of an open, grassland savanna or a savanna-
150 mosaic that includes areas of woodland (see review in Domínguez-Rodrigo, 2014). In an open
151 landscape, bipedalism may have been an effective means of long-distance travel (Sinclair et al.,
152 1986) or moving through patches of open terrain to reach woodland habitats (Rodman and
153 McHenry, 1980; Isbell and Young, 1996; Potts, 1998). Others focused on the use of bipedalism

154 for feeding in terrestrial, savanna-dwelling primates as a potential model for the selective driver
155 of hominin bipedalism, all of which were grouped under the umbrella of the ‘terrestrial feeding
156 hypothesis’ (Jolly, 1970; Rose, 1976, 1984; Wrangham, 1980). Jolly’s (1970) ‘seed-eater’ model
157 is particularly relevant to Hunt’s (1994) ‘postural feeding hypothesis’ as it was the first time
158 bipedal posture, rather than locomotion, was proposed as the selective target (see also Du Brul,
159 1962; Prost, 1980; Wrangham, 1980).

160

161 **2. Hunt (1994) and the ‘small-tree postural feeding’ hypothesis**

162 Within the historical context described above, Hunt (1994) recognized that feeding behavior
163 is a logical selective target for changes in hominin positional behavior, but none of the
164 previously proposed feeding hypotheses adequately accounted for the dual functional nature of
165 the *Au. afarensis* postcranium. Hunt, instead, proposed the ‘small-tree postural feeding
166 hypothesis’ based on extant chimpanzees as behavioral models to interpret the selective
167 pressures on the early hominin postcranium (see also Hunt, 1996). The foundation of his
168 hypothesis was the behavioral and ecological study of 26 habituated adult chimpanzees from the
169 Mahale Mountains and Gombe of western Tanzania. Similar to studies of baboons (Rose, 1976,
170 1984, 1991), Hunt (1994) found that bipedalism was rare in comparison to other locomotor and
171 postural behaviors, but when used, it was most often adopted as a posture during feeding (80% of
172 bipedal bouts) rather than as as locomotior behavior for traveling. Bipedalism was used both on
173 the ground and in trees, but when foraging for fruit from short trees while on the ground,
174 chimpanzees were able to reach higher fruits, use both hands for fruit gathering, and to eat the
175 fruits faster.

176 Hunt's (1994, 1996) postural feeding hypothesis aimed to reconcile the presumed
177 contradictory functional signals across the *Au. afarensis* skeleton: an ape-like upper body
178 advantageous for arboreal arm-hanging and more human-like lower body that he interpreted as
179 indicating habitual but 'less than optimal' bipedal locomotion (i.e., more energetically costly)
180 compared with humans. Although the modern human bipedal economy (i.e., a low energetic cost
181 during bipedalism) is not necessarily the appropriate benchmark (Daegling, 2022), Hunt (1994,
182 1996) highlighted the importance of considering the energetic economy (or what Hunt often
183 called 'energetic efficiency') of bipedalism, both postural and locomotor (see also Rodman and
184 McHenry, 1980; Steudel, 1996). The postural feeding hypothesis aimed to explain *Au. afarensis*
185 morphology holistically as 'fully-evolved' hominins adapted for a unique positional repertoire
186 rather than as intermediate, 'half-evolved' bipeds (Hunt, 1994:p. 199) (of course, these terms
187 used by Hunt (1994) were not meant as teleological or to imply evolution is goal-oriented). In
188 doing so, Hunt (1994, 1996) synthesized two of the arguably most plausible hypotheses at the
189 time for the origin of bipedalism: the hylobatid hypothesis and the terrestrial feeding hypothesis.

190 We find Hunt's (1994) paper to be inspiring because it 1) uses the careful study of extant ape
191 behavior as a model for understanding potential selective pressures on hominins, 2) makes robust
192 predictions based on functional morphology, biomechanics, and locomotor economy that can be
193 (and since have been) tested, and 3) presents a hypothesis that aims to explain the dual functional
194 signals of the *Au. afarensis* and, more generally, early hominin postcranium; all of which are just
195 as relevant, if not more so, today as they were nearly 30 years ago.

196 Here we review the key questions regarding functional interpretation of the australopith
197 postcranium, what we have learned about *Au. afarensis* functional morphology since Hunt's
198 paper was published, and the dual functional signals of two new australopith discoveries with

199 relatively complete skeletons (*Australopithecus sediba* and StW 573, referred to by some as
200 *Australopithecus prometheus*). We follow this with a discussion of the advances in three research
201 approaches used to draw inferences about early hominin behavior (and the past more generally):
202 1) the study of extant apes as models for understanding hominin origins; 2) measurement of
203 bipedal gait and locomotor economy in extant primates to infer the locomotor costs from the
204 anatomy of fossil taxa; and 3) the study of internal bone structure to extract functional signals
205 from fossils. We end with a summary of the current challenges in paleoanthropology for
206 reconstructing (locomotor) behaviors, including (but not only) the evolution of hominin
207 bipedalism.

208

209 **3. New fossil evidence: The early years**

210 Over 40 years of debate about the reconstructed positional behavior of *Au. afarensis* (i.e., the
211 ‘efficiency camp’ vs. ‘compromise camp’; see above) has been driven, at least in part, by
212 differences in the functional importance one attributes to ape-like vs. human-like features found
213 throughout the australopith postcranium (Stern, 2000; Ward, 2002, 2013; Daegling, 2022; Fig.
214 1). In a simplified scenario, derived, human-like features of the australopith lower limb offer
215 clear phylogenetic polarity and a direct biomechanical link to function (Lauder, 1996), which
216 reveals their biological role for bipedal movement (Bock and van Wahlert, 1965; Weishampel,
217 1995). These derived features, or their biological role—in this case, bipedal posture and
218 locomotion— can be inferred to have conferred fitness benefits to those individuals better able to
219 deal with the mechanical demands of terrestrial bipedality. On the contrary, primitive, ape-like
220 features can be considered 1) selectively neutral or stabilized retentions from an ape-like
221 ancestor that are not directly linked to function (e.g., retained via pleiotropy or other ontogenetic

222 mechanisms), 2) positively-selected retentions that are functionally significant and play a
223 biological role—in this case, arboreality; or 3) positively-selected exaptations that are
224 functionally significant for a new biological role, such as manipulation (Fig. 1). In the 1980s and
225 1990s, interpreting the functional significance of *Au. afarensis* morphology was done largely
226 within the comparative context of extant great apes, modern humans and, less frequently,
227 geologically younger fossil hominins (e.g., Jungers, 1982; Stern and Susman, 1983; Susman et
228 al., 1984; Latimer and Lovejoy, 1990), making phylogenetic polarity of features and their
229 functional interpretation more challenging. Older (putative) hominins with postcranial remains
230 prior to 4.0 Ma were not uncovered until mid-1990s or later (e.g., Leakey et al., 1995; Senut et
231 al., 2001; Lovejoy et al., 2009a; White et al., 2009; Macchiarelli et al., 2020; Daver et al., 2022;
232 but see Patterson and Howells, 1967), and thus debates about the functional significance of
233 certain aspects of australopith morphology were fueled by a ‘black box’ of hominin evidence
234 between 4–7 Ma. Below we briefly review (putative) fossil hominin evidence prior to the first
235 appearance of *Au. afarensis* that has been uncovered since 1994.

236 The earliest species of australopith, *Australopithecus anamensis* (4.2–3.8 Ma), was announced
237 in 1995 based on fossils from Kanapoi, Kenya (Leakey et al., 1995) with additional specimens
238 also from Allia Bay, Kenya (Leakey et al., 1998, Ward et al., 1999, 2001, 2013) and Asa Issie,
239 Ethiopia (White et al., 2006). Although there are few postcranial remains, all can be generally
240 described as being similar in morphology to *Au. afarensis*, but larger in absolute size (Ward et
241 al., 1999, 2001; White et al., 2006). The proximal and distal tibia show several features
242 distinctive to bipedal locomotion, including an expanded proximal end with concave condyles
243 and a vertical tibial shaft that is orthogonal to the talar joint (Leakey et al., 1995; Ward et al.,
244 1999). The femoral shaft lacks a linea aspera, similar to the morphology found in *Au. afarensis*

245 A.L. 288-1, and has remarkably thick cortical bone (White et al., 2006). The distal humerus lacks
246 morphology specific to African apes and although some have noted distinctive *Homo*-like
247 features (Senut and Tardieu, 1985; Baker et al., 1998; Senut, 1999), more detailed studies show
248 the most morphological similarities to *Au. afarensis* (Feldesman, 1982; Lague and Jungers,
249 1996). Like the femur, the humerus also has notably thick cortical bone (Ward et al., 2001). The
250 radius is long, suggesting elongated forelimb proportions similar to those of *Au. afarensis*
251 (Heinrich, 1993; Ward et al, 2001). A dorsal ridge on the distal radius has been interpreted as
252 limiting radiocarpal joint extension, implying evidence of a knuckle-walking origin for hominin
253 bipedalism (Richmond and Strait, 2000; but see Ward et al., 2001). The capitate has a
254 radioulnarly broad proximal head with a large lunate articulation, similar to some other
255 australopiths, but the radially-facing second metacarpal facet is similar to that of extant African
256 apes and unlike that of other hominins (McHenry, 1983; Leakey et al., 1998, Ward et al., 2001;
257 Lovejoy et al., 2009b, Macho et al., 2011). *Australopithecus anamensis* manual phalanges are
258 curved to a similar degree as *Au. afarensis* (Ward et al., 1999), but the intermediate phalanx from
259 Asa Issie is described as being longer for its breadth than those from Hadar (White et al., 2006).

260 Insert Figure 1 here

261
262 *Ardipithecus* (5.8–4.4 Ma) is currently the best known (putative) hominin prior to *Au.*
263 *afarensis* (White et al., 1994, 1995, 2009; Haile-Selassie, 2001; Haile-Selassie and
264 WoldeGabriel, 2009; Lovejoy et al., 2009a, b, c; Simpson et al., 2019). There are two species:
265 the older *Ardipithecus kadaba* (5.8-5.2 Ma; Haile-Selassie, 2001; Haile-Selassie and
266 WoldeGabriel, 2009) and *Ardipithecus ramidus* (4.4 Ma; White et al., 2004; 2009), of which the
267 ARA-VP-6/500 partial skeleton provides the most informative postcranial evidence. ARA-VP-

268 6/500 is remarkably complete but unfortunately does not preserve the articular ends of most long
269 bones and the pelvic bones are highly fragmented. The lower body morphology shows several
270 features associated with bipedalism, including shorter and medially-rotated iliac blades, a well-
271 developed anterior inferior iliac spine, a shortened greater trochanter, thinner cortex on the
272 superior margin of the femoral neck, lateral midfoot rigidity, and evidence of regular
273 dorsiflexion at the metatarsal-phalangeal joints (White et al., 2009; Lovejoy et al., 2009c). This
274 morphology is combined with several features considered advantageous for arboreality: a
275 grasping hallux with no dorsal doming, a long ischium, long, curved manual and pedal
276 phalanges, as well as several features described as distinct from extant apes and more like Early
277 Miocene apes, including short metacarpals but relatively long pollex, a simple ‘carpometacarpal
278 complex’, and long tarsus (Lovejoy et al., 2009b; Selby et al., 2016; Simpson et al., 2019).
279 Collectively, this suite of postcranial features is interpreted as indicating facultative, terrestrial
280 bipedalism combined with the primitive retention of arboreal capabilities including palmigrade
281 above-branch quadrupedalism and ‘careful climbing’ (White et al., 2009; Lovejoy et al., 2009b,
282 c). Critically, the initial interpretations highlighted a distinct absence of any great ape-like
283 morphology related to orthograde, suspension, vertical climbing, and knuckle-walking, implying
284 that shared morphologies among extant great apes must be homoplasies (White et al., 2009;
285 2015; Lovejoy et al., 2009a).

286 Recent studies, however, have questioned the original functional interpretations of the *Ar.*
287 *ramidus* morphology and the subsequent evolutionary implications. For example, Prang et al.
288 (2021) demonstrated that the *Ar. ramidus* hand is most similar to chimpanzees and bonobos with
289 morphology advantageous for suspensory locomotion. Similarly, Prang (2019) interpreted the
290 *Ar. ramidus* foot as most similar to chimpanzees and gorillas, and suggested that the elongated

291 tarsus could have increased propulsion during bipedalism. A morphological and cladistic
292 analysis of foot morphology by DeSilva et al. (2019) further highlighted distinct morphs within
293 the *Ardipithecus* sample (see also Simpson et al., 2019) as well as the Burtele foot (Haile-
294 Selassie et al., 2012) and StW 573 (Kidd and Oxnard, 2005; Crompton et al., 2021; see below),
295 which they interpreted as evidence of different hominin taxa engaging in different forms of
296 bipedal walking or arboreality. This conclusion is further supported by morphometric and
297 kinematic modeling of the hominin pelvis showing that *Ar. ramidus* had human-like hip
298 extension for bipedal walking but also powerful, ape-like hip extension for vertical climbing,
299 while *Au. afarensis* and *Au. africanus* had a reduced mechanical advantage for climbing (Kozma
300 et al., 2018). Multiple forms of bipedality (and climbing) in early hominins further complicate
301 interpretations of trait polarity and functional significance in reconstructions of australopith
302 bipedalism.

303 *Orrorin tugenensis* (6 Ma) from Lukeino Formation, Kenya preserves three femora, a distal
304 humerus and manual phalanges (Senut et al., 2001; Gommery and Senut, 2006). The two most
305 preserved femora show features interpreted as indicators of habitual bipedality, including a
306 femoral neck that is elongated and anteroposteriorly compressed, and has thicker cortex
307 inferiorly than superiorly, the presence of an obturator externus groove, and a well-developed
308 gluteal tuberosity (Senut et al., 2001; Pickford et al., 2002; Galik et al., 2004). These
309 morphological features were originally inferred to suggest *Orrorin* was a habitual, and perhaps
310 obligate biped, but with upper limb morphology that indicated effective climbing abilities (Senut
311 et al., 2001). The preserved external shape of the *Orrorin* proximal femur has been described as
312 more hominin-like rather than ape-like but the asymmetric cortical bone distribution in the
313 femoral neck has received particular attention as arguably one of the key traits indicative of

314 bipedality in *Orrorin* (Pickford et al. 2002, Galik et al. 2004; Richmond and Jungers, 2008).
315 Some have questioned the methodology employed and the quality of the CT scans used to
316 demonstrate the inferiorly thicker femoral neck cortex of *Orrorin* (Ohman et al. 2005, White
317 2006), while others have criticized the usefulness of the trait in general, regardless of its presence
318 in *Orrorin*, as an indicator of habitual or obligate bipedality (Andrews and Harrison, 2005). A
319 more recent study of the cortical thickness topographic distribution of the *Orrorin* femoral shaft
320 confirms a human-like cortical distribution consistent with habitual terrestrial bipedalism
321 (Puymeraill et al., 2017).

322 Arguably the most controversial of the early putative hominins, *Sahelanthropus tchadensis*
323 (~7 Ma) from Toros-Menalla, Chad, was inferred to be bipedal based initially on basicranial
324 morphology (Brunet, 2002, Brunet et al., 2005; Zollikofer et al., 2005) and only recently on
325 postcranial evidence (Daver et al., 2022). In their analyses of the external and internal
326 morphology of the *Sahelanthropus* femoral shaft, Daver et al. (2022) show an anteroposteriorly
327 compressed femoral neck, the presence of a linea aspera and calcar femorale, and human-like
328 cross-sectional geometry of the diaphysis. The ulnae, however, show a suite of morphological
329 features reflecting arboreality, including high degree of shaft curvature and orangutan-like cross-
330 sectional geometry (Daver et al., 2022). Taken together, Daver et al. (2022) concluded that
331 *Sahelanthropus* engaged in habitual bipedalism, likely on the ground, and arboreal ‘cautious
332 climbing’ behaviors. However, others have questioned the association of the postcrania with the
333 *Sahelanthropus* cranium (Beauvilain, 2008). Independent analyses of the external morphology
334 and cross-sectional shape reveal greater similarities with *Pan* and features that are distinct from
335 the femoral shaft morphology of *Orrorin* or later hominins (Macchiarelli et al., 2020). Moreover,
336 a calcar femorale can be present in extant great apes and absent in some bipedal hominins,

337 indicating that this feature is not necessarily indicative of bipedal locomotion (Cazenave et al.,
338 2022). At ~7 Ma, so close to the panin-hominin divergence, a full suite of bipedal features in
339 *Sahelanthropus* is an unrealistic expectation, creating an unclear threshold of ‘how many bipedal
340 features does one need to be considered a fully terrestrial biped or a hominin’? This fundamental
341 problem is further confounded by the challenge of identifying bipedalism in a potential hominin
342 with a different body plan, which would elicit distinct, site-specific biomechanics and therefore
343 distinct internal bone structure response. As Macchiarelli et al. (2020) highlight, even if
344 *Sahelanthropus* is not bipedal, it does not diminish its importance in our understanding of
345 hominid evolution.

346 Although a minority of researchers view some of the above hominin taxa as ‘chronospecies’
347 leading to *Au. afarensis* (White, 2003; White et al., 2006, 2009), most paleoanthropologists
348 recognize a far bushier and perhaps reticulated hominin evolutionary tree (e.g., Holliday, 2003;
349 Harrison, 2010; Wood and Harrison, 2011; Strait et al., 2015; Wood and Boyle, 2016; Slon et al.,
350 2018). Importantly, paleoanthropologists must acknowledge that some or all of these early,
351 putative hominins could instead fall within the panin clade or any number of extinct clades, and
352 that homoplasy will undoubtedly be rampant and confounding (Wood and Harrison, 2011;
353 Daegling, 2022). Thus, although there are now many more fossils within the 7–4 Ma ‘black box’
354 than there were at the time of Hunt’s (1994) functional interpretation of *Au. afarensis*
355 postcranium, any potential clarity on the polarity or functional significance of australopith
356 morphology is overshadowed by new and complex questions about early hominin evolution and
357 phylogenetic relationships. As Wood and Harrison (2011:p. 348) aptly question: “Should the
358 discovery of a purported fossil hominin overturn predictions about an ancestral morphotype
359 based on a wealth of comparative data from extant taxa, or should one defer to the hypothetical

360 morphotypes that best fit the comparative evidence and critically reassess the phylogenetic
361 placement of fossil taxa that contradicts such an hypothesis?”

362

363 **4. New fossil evidence: Australopiths in a complex taxonomic context**

364 As highlighted by Hunt (1994), inferences about positional behaviors and their energetic costs
365 in fossil taxa are only possible for species represented by sufficient postcranial remains.
366 However, the rarity of unambiguously associated craniodental and postcranial remains
367 complicates the already difficult task of drawing functional inferences from fragmentary and/or
368 incomplete axial or appendicular skeletal remains (e.g., Susman et al., 2001; Wood and
369 Constantino, 2007; Domínguez-Rodrigo et al., 2013; Hlusko et al., 2015; Lague, 2015; Wood
370 and Boyle, 2016). This is especially true in the Plio-Pleistocene in which hominin taxic diversity
371 has increased and become more complex with recent fossil discoveries (e.g., Berger et al., 2010;
372 Wood and Boyle, 2016; Clarke and Kuman, 2019; Zipfel et al., 2021), and which possibly may
373 be underestimated (e.g., Cofran and Thackeray, 2010; Zanolli et al., 2019; Pickering et al., 2021;
374 Zipfel et al., 2021). Nonetheless, intense fieldwork has unveiled relatively complete hominin
375 skeletons or sufficient associated remains to satisfactorily reconstruct a body plan and to provide
376 more robust functional inferences (e.g., Brown et al., 2004; Alemseged et al., 2006; Berger et al.,
377 2010, 2015; Haile-Selassie et al., 2010; Clarke and Kuman, 2019; see sections 4.2 and 4.3).

378 These relatively complete hominin skeletons each reflect committed bipedalism, but also
379 differing mosaics of anatomical features that suggest biomechanical variation in bipedal gait, and
380 that arborealism or climbing continued to be a significant component of behavior for some
381 hominins, including into the Pleistocene (e.g., Stern, 2000; Ward, 2002, 2013; Larson et al.,
382 2009; Lovejoy et al., 2009a,b,c; Haile-Selassie et al., 2012; Barak et al., 2013; Berger et al.,

383 2015; Kivell et al., 2015; Harcourt-Smith, 2016; Ruff et al., 2016, 2018; Zeininger et al., 2016;
384 McNutt et al., 2021). This new evidence departs from Hunt's (1994) vision of a single, unique,
385 adaptive morphotype for both terrestrial and arboreal bipedal foraging in hominins that may have
386 remained relatively unchanged even in *Homo habilis*. However, Hunt's (1994) hypothesis
387 accommodated the arboreal features of the *Au. afarensis* upper body because he considered them
388 functionally significant (i.e., via stabilizing selection), with the underlying assumption of
389 correspondence between the presence of a morphology and the use of that morphology in a
390 biological role. New fossil discoveries and new analyses of old fossils have revealed that Hunt's
391 (1994) functional interpretation remains valid. We outline this evidence below.

392

393 *4.1. What we have learned about Australopithecus afarensis since Hunt (1994)*

394

395 The *Au. afarensis* hypodigm currently includes more than 400 specimens collected from
396 multiple sites in eastern Africa, which are thoroughly reviewed by Kimbel and Deleuzene (2009;
397 see also Drapeau et al., 2005 and Ward et al., 2012). Therefore, here we do not aim to reproduce
398 their work and instead focus on functional inferences derived from more recent morphological
399 studies of the partial skeleton A.L. 288-1 'Lucy' and *Au. afarensis* more generally (Fig. 2a).

400 One of the anatomical features highlighted by Hunt (1994) was the presence of six lumbar
401 vertebrae in *Au. afarensis*, indicating a longer, more flexible lower back than that of humans and
402 African apes, and that australopiths were likely not adapted to vertical climbing or leaping.
403 However, a recent re-analysis of the A.L. 288-1 lumbar vertebrae found that one vertebra (A.L.
404 288-1am) exhibited morphology that is absent in extant hominoids but common in large-bodied
405 extant papionins, indicating that this vertebra is not hominin (Meyer et al., 2015). Moreover, a

406 reassessment of the A.L. 288-1 sacral vertebrae suggests that ‘Lucy’ possessed five sacral
407 vertebrae as in modern humans (Russo and Williams, 2015), rather than four as previously
408 interpreted (Lovejoy et al., 2009d; McCollum et al., 2010). The juvenile *Au. afarensis* partial
409 skeleton (DIK-1-1) from Dikika, Ethiopia provides further insights into the full vertebral column,
410 preserving the only known complete early hominin cervical and thoracic vertebral column
411 (Alemseged et al., 2006; Ward et al., 2017). DIK-1-1, at 3.3 Ma, preserves the earliest evidence
412 of 12 thoracic vertebrae, rather than 13 in African apes, but a thoracolumbar transition at the 11th
413 thoracic segment, a distinctive transitional pattern found in other early hominins but that is
414 higher than in modern humans and extant apes (Ward et al., 2017). Collectively, this new
415 evidence has important implications for reconstructing the trunk and lower back morphology in
416 early hominin evolution (see reviews in Williams et al., 2016; Williams and Pilbeam, 2021).

417 Hunt (1994) focused on differing functional signals derived from the upper vs. lower body in
418 *Au. afarensis*. Researchers agree that the derived traits of the australopith lower limb (and
419 postcranial skeleton overall) are the result of selection for bipedality (reviewed in Ward, 2002,
420 2013). However, there has been enduring debate over australopith bipedal gait and kinematics, in
421 particular whether they used a human-like, extended-limb striding bipedalism or a compliant,
422 bent-hip/bent-knee gait (reviewed in Schmitt, 2003; Carey and Crompton, 2005). The recently
423 discovered *Au. afarensis* partial skeleton (KSD-VP-1/1) from Woranso-Mille, Ethiopia (3.58
424 Ma) confirms key bipedal features, including a long tibia, an elliptical lateral femoral condyle,
425 and a well-developed patellar lip that together is coherent with human-like bipedalism with a
426 valgus knee (Haile-Selassie et al., 2010). In addition, a complete *Au. afarensis* fourth metatarsal
427 (A.L. 333-160) recently recovered from Hadar, Ethiopia, was also interpreted as having
428 morphology consistent with a human-like bipedal gait (Ward et al., 2011). This morphology

429 includes torsion of the metatarsal shaft, a feature thought only to be observed in modern humans,
430 and suggesting *Au. afarensis* possessed modern human-like transverse and longitudinal arches,
431 which are critical to committed, terrestrial bipedalism (Ward et al., 2011). Morphological
432 comparisons of A.L. 333-160 with a larger comparative sample show similarities between
433 hominins and cercopithecids in torsion of the fourth metatarsal, reflecting the presence of
434 transverse arches in terrestrial cercopithecids as well (Drapeau et al., 2013; Mitchell et al., 2012).
435 Furthermore, other aspects of metatarsal morphology highlighted by Ward et al. (2011) are also
436 similar to other great apes and/or highly variable, bringing into question the significance of these
437 features for inferring midfoot stiffness and the interpretation that *Au. afarensis* was a habitual
438 terrestrial biped, at least from its fourth metatarsal morphology alone (Mitchell et al., 2012).

439 Nonetheless, there are several other features of the *Au. afarensis* foot that are surprisingly
440 human-like, especially in light of new australopith discoveries (see below; Zipfel et al., 2011;
441 McNutt et al., 2018; DeSilva et al., 2019). These features include a robust calcaneal tuberosity
442 and an expanded, plantarly-positioned lateral plantar process, both of which are found in the
443 modern human heel and suggest the *Au. afarensis* foot was well adapted for incurring high forces
444 during heel-strike (Prang, 2015a; McNutt et al., 2018). *Au. afarensis* tali have a human-like,
445 plantarly-oriented talar head (Prang, 2016a) and more human-like overall shape relative to other
446 australopiths (Sorrentino et al., 2020). An associated *Au. afarensis* forefoot (A.L. 333-115)
447 demonstrates human-like dorsal doming of the lateral metatarsal heads, but the kinematics of toe
448 push-off during the bipedal gait are interpreted as differing from that of humans based on a more
449 mediolaterally narrow first metatarsal head compared to modern humans (Latimer et al., 1982;
450 Latimer and Lovejoy, 1990; Fernandez et al., 2016). Moreover, the nearly completely juvenile
451 foot from Dikika, Ethiopia (DIK-1-1f) offers a rare opportunity to assess how function and

452 behavior may have changed throughout ontogeny in *Au. afarensis* (Alemseged et al., 2006;
453 DeSilva et al., 2018). Compared to adult *Au. afarensis* specimens, the hallux was more mobile
454 and the calcaneus more gracile, indicating selection for foot grasping abilities in juveniles
455 combined with habitual bipedality (DeSilva et al., 2018).

456 For *Au. afarensis*, functional information from postcranial morphology can be combined with
457 biomechanical inferences derived from the Laetoli footprints (3.66 Ma; Leakey, 1978; Leakey
458 and Hay, 1979; White and Suwa, 1987). Novel analyses of the ‘G’ and ‘S’ tracks using extant
459 human bipedal biomechanics as a model suggest *Au. afarensis* walked with an extended hip and
460 knee (Raichlen et al., 2010) but potentially with a slightly more flexed limb at foot strike than
461 that of modern humans (Hatala et al., 2016; but see McNutt et al, 2021). Comparisons of the
462 Laetoli footprints to younger (1.5 Ma) hominin footprints from Ileret, Kenya, imply that the
463 Laetoli hominins had a shallower and wider instep and potentially different foot proportions
464 relative to later hominins (Bennett et al., 2009).

465 Regarding the *Au. afarensis* upper limb, recent analyses of the scapula support Hunt’s (1994)
466 functional interpretation of the importance of arboreality in australopiths. The Dikika partial
467 juvenile skeleton preserves both scapulae showing cranially-oriented glenoid fossae and
468 obliquely-oriented scapular spines, similar to that of great apes, and suggesting an African ape-
469 like ontogenetic trajectory (Green and Alemseged, 2012; Young et al., 2015). Shared
470 morphology between juvenile and adult *Au. afarensis* scapulae indicates that arboreal locomotion
471 was an important behavior throughout adulthood as well (Green and Almesege, 2012). In
472 contrast, others have suggested that the KSD-VP-1/1 adult partial scapula is more human-like
473 (Haile-Selassie et al., 2010) and potentially reflects use of the upper limbs for tool-use while
474 engaging in committed terrestrially (Melillo, 2016).

475 Several studies have focused on the functional inferences that can be drawn from *Au.*
476 *afarensis* hand morphology, particularly in relation to the estimated intrinsic hand proportions,
477 but these studies have typically focused on potential manipulative abilities rather than locomotor
478 behaviors. The composite hand of *Au. afarensis* includes second to fifth metacarpals (Mc 2–5)
479 that most likely belong to a single individual, combined with a first metacarpal and phalanges
480 from different A.L. 333 localities (Marzke, 1983; Alba et al., 2003). The estimated intrinsic hand
481 proportions (i.e., relative length of the thumb to the finger[s]) range from *Gorilla*-like (Rolian
482 and Gordon, 2013) to human-like (Alba et al., 2003). Experimental evidence of human
483 participants using simulated stone tools instrumented with force sensors highlights the high joint
484 forces acting on the thumb, which has implications for early hominin tool use (Rolian et al.,
485 2011; also see Williams et al., 2012; Key and Dunmore, 2015; Williams-Hatala et al., 2018). As
486 such, some researchers suggest that *Au. afarensis* lacked the ability to produce precision grips
487 with the same proficiency as modern humans (Rolian and Gordon, 2013) and that the gracile first
488 metacarpal morphology could not effectively dissipate the high stress that occurs during stone
489 tool behaviors (Rolian et al., 2011). In contrast, others have inferred a human-like pad-to-pad
490 precision grip ability in response to or as an exaptation for a variety of manipulative behaviors,
491 not just lithic or non-lithic tool-use (Alba et al., 2003; Almécija and Alba, 2014; Feix et al.,
492 2015; Prang et al., 2021). These functional interpretations, however, took on new relevance with
493 the discovery of cut marks and percussion marks in the Dikika assemblage at 3.4 Ma (McPherron
494 et al., 2010) and the Lomekwi tool technology in Kenya at 3.3 Ma (Harmand et al., 2015) that
495 are, at least potentially, associated with *Au. afarensis* (but see Sahlea et al., 2017; Domínguez-
496 Rodrigo and Alcalá, 2019).

497 Hunt's (1994) hypothesis aimed to accommodate the contrasting functional signals within the
498 *Au. afarensis* upper and lower limbs. The new discoveries and analyses since this time continue
499 to confirm the dual nature of the functional signals reflected in its postcranial morphology. New
500 evidence suggests that the bipedal gait of *Au. afarensis* may have been more human-like and
501 energetically economical than some researchers previously posited (e.g., Crompton et al., 1998;
502 Wang et al., 2003; Carey and Crompton, 2005; Lovejoy and McCollum, 2010; Raichlen et al.,
503 2010), and, interestingly, more human-like than other roughly contemporary or more recent
504 australopiths (Harcourt-Smith and Aiello, 2004; Zipfel et al., 2011, DeSilva et al., 2018; see
505 below). Although some debate still remains over the significance of arboreality in *Au. afarensis*,
506 evidence of perimortem fractures throughout the A.L. 288-1 skeleton is interpreted as consistent
507 with a vertical fall from a tree, unusual evidence of arborealism in *Au. afarensis* (Kappelman et
508 al., 2016). Moreover, in contrast to previous assumptions (e.g., Marzke, 1983, 1988; Latimer,
509 1991; Marzke et al., 1992; Alba et al., 2003; Tocheri et al., 2008), recent hominin discoveries
510 suggesting the possibility that *Au. afarensis* was a lithic stone tool user and/or capable of forceful
511 precision dexterity are not incompatible with a significant reliance on arboreal locomotion
512 (Kivell et al., 2015; Feuerriegel, 2016). We highlight some of this new comparative context
513 below.

514

515 *4.2. Recently-discovered australopiths and anatomical evidence of locomotor behaviors*

516

517 Since 1994, several new australopith discoveries have expanded australopith taxic diversity
518 (e.g., Asfaw et al., 1999; Berger et al., 2010; Haile-Selassie et al., 2012; 2015; Clarke and
519 Kuman, 2019; reviewed in Wood and Boyle, 2016). Here we synthesize the functional

520 morphology of partial skeletons from two *Australopithecus* species recently found in South
521 Africa, focusing on the locomotor signals within the lower and upper limb: StW 573 from
522 Sterkfontein caves, dated to as old as 3.67 Ma (Granger et al., 2015; Bruxelles et al., 2019) and
523 referred to as *Australopithecus prometheus* (Clarke and Kuman, 2019), and *Australopithecus*
524 *sediba* Malapa Hominin 1 (MH1) and Malapa Hominin 2 (MH2) from Malapa (Berger et al.,
525 2010), dated to 1.977 Ma (Pickering et al., 2011).

526 The StW 573 partial skeleton is remarkably well preserved, including relatively complete
527 upper and lower limbs from both sides with a complete, semi-articulated hand, as well as a
528 thorax and partial pelvis (Stratford and Crompton, 2021; Fig. 2b). Many features of the lower
529 limb bones, including developmentally plastic features that only form during repeated use of
530 bipedal gaits (Frost, 1990; Duren, 1999; Hamrick, 1999; Tardieu, 2010), suggest clear evidence
531 of habitual terrestrial bipedality (Heaton et al., 2019; Crompton et al., 2021). For example, the
532 StW 573 femur has a relatively large head, an intertrochanteric crest reflecting a strong
533 iliofemoral ligament, a well-developed patellar lip, flattened and asymmetrical femoral condyles,
534 and a high bicondylar angle indicating stabilized hip and knee joints during bipedal walking
535 (Heaton et al., 2019; Crompton et al., 2021). These features are found in combination with a
536 more ape-like tibia morphology and fibulotalar articulation indicating greater ankle mobility than
537 that of extant humans (Heaton et al., 2019; Crompton et al., 2021). The StW 573 foot bones were
538 originally described as having a mosaic of features, including a human-like talus and a medially-
539 oriented medial cuneiform-first metatarsal joint implying a more abducted hallux compared to
540 extant humans, which would have facilitated arboreality (Clarke and Tobias, 1995). In contrast,
541 more recent morphological studies suggest an ape-like talus and lack of hallux opposability in
542 StW 573 (Harcourt-Smith, 2002; Crompton et al., 2021).

543 Morphology of the StW 573 upper limb indicates that climbing and/or suspension continued
544 to be a part of its locomotor repertoire (Heaton et al., 2019; Carlson et al., 2021; Crompton et al.,
545 2021). The long clavicles, the African ape-like shape of the scapulae, including a cranially-
546 oriented glenoid fossa, as well as low humeral torsion, suggest a high, dorsally-positioned
547 scapula that would have facilitated above-head upper limb use and body weight support (Heaton
548 et al., 2019; Carlson et al., 2021), as well as hand-assisted bipedalism (Hunt, 1994; Thorpe et al.,
549 2007). The humeri have widely-flaring lateral supracondylar ridges and large epicondyles that, in
550 apes, reflect a well-developed brachioradialis muscle and long wrist and digital flexor muscles,
551 facilitating climbing (Heaton et al., 2019; Crompton et al., 2021). StW 573 also preserves a
552 complete (apart from one missing phalanx), articulated left hand. It has been described as having
553 modern human-like intrinsic hand proportions (Clarke, 1998, 2002; Crompton et al., 2021) and
554 having a *Gorilla*-like ridge on the first metacarpal facet that would help to stabilize the thumb in
555 abducted pinch grips (Crompton et al., 2021). However, to date no quantitative analyses or
556 detailed descriptions of any of the StW 573 hand anatomy have been published. Although the
557 hand remains articulated within the breccia, making morphological analyses more challenging,
558 our own study of the fossils based on caliper linear measurements (taken by T.L.K.) estimates
559 thumb length (including the metacarpal and proximal phalanx) at 68 mm and third digit length
560 (including the metacarpal and proximal and intermediate phalanges) as 128 mm, indicating a
561 thumb length that is approximately 53% the length of the third digit. Thus, StW 573 indeed does
562 have similar intrinsic hand proportions to those of modern humans (mean 54%), but shorter than
563 *Homo naledi* (Hand 1, 58%) and, especially, *Au. sediba* (MH2, 61%; Kivell et al., 2011, 2015).
564 The first metacarpal facet of the trapezium shows strong dorsopalmar convex curvature like that
565 of African apes and unlike humans, but no ridge is present (T.L.K., pers. observ.).

566 The remarkable preservation of StW 573 offers a rare opportunity to reliably assess limb
567 proportions in an early hominin, and like other early hominins for which these can be assessed,
568 the StW 573 limb indices are intermediate and roughly equidistant from those of African apes
569 and modern humans (Heaton et al., 2019). As reported by Heaton et al. (2019), the StW 573
570 intermembral index (85.5) is almost identical to that of A.L. 288-1 (85.6), indicating that
571 variation in upper and lower proportions is less influenced by allometry than previously thought
572 (Holliday and Franciscus, 2012). The humerofemoral index (86.6) in StW 573 is also similar to
573 A.L. 288-1, as well as *Ardipithecus* (both 84.3), indicating a relatively shorter femur than that of
574 modern humans (Heaton et al., 2019). The StW 573 brachial index shows a surprising degree of
575 bilateral asymmetry (82.8 and 86.2) and is similar to that of *Gorilla* (mean 80.6) and *Au. sediba*
576 (~84) but lower than A.L. 288-1 (88.6; Heaton et al., 2019).

577 Crompton et al. (2021) concluded that StW 573 morphology reflects active selection for both
578 arboreal and terrestrial locomotion. They argued that relatively short upper limb length compared
579 with African apes would have reduced its energetic economy for arboreal locomotion but would
580 have been more economical than humans (Crompton et al., 2021). The ape-like aspects of the
581 pectoral girdle have also been interpreted as reflecting greater selection for suspensory activities
582 rather than enhanced manipulation (Carlson et al., 2021). The human-like bipedal morphology of
583 the lower limb combined with relatively shorter length compared to modern humans suggest
584 selection for walking short-to-medium distances and that bipedalism would have been used
585 within an arboreal context as well (Crompton et al., 2021). This behavioral interpretation is also
586 consistent with the morphology of the vestibular apparatus suggesting that StW 573 was adapted
587 to utilizing environments requiring maintenance of head/visual stability in a variety of postures
588 such as three-dimensionally (3D) complex arboreal environments (Beaudet et al., 2019).

589 The two associated partial skeletons of *Au. sediba*, one likely representing a subadult male
590 (MH1) and the other an adult female (MH2), show a mosaic of ape-like and human-like
591 morphology as well, but a different mosaic relative to that of StW 573 and *Au. afarensis* (Fig. 2c;
592 Kibii et al., 2011; Kivell et al., 2011; Williams, 2011, 2012; Zipfel et al., 2011; Berger, 2013;
593 Churchill et al., 2013; 2018; de Ruiter et al., 2013, 2017; DeSilva et al., 2013; Schmid et al.,
594 2013; Williams et al., 2013, 2018, 2021; Prang, 2015a, b, 2016a, b; Meyer et al., 2017; Rein et
595 al., 2017; Dunmore et al., 2020a). Partial pelvic and sacral remains from both MH1 and MH2
596 share several features with other australopiths, including a long pubis, relatively small sacral and
597 acetabular joints, and a wide bi-acetabular diameter (Kibii et al., 2011; Churchill et al., 2018).
598 However, the overall architecture of the pelvis is more similar to modern humans, including
599 more sagittally-oriented iliac blades (i.e., less flared) with a sigmoid curvature, robust iliac pillar
600 (acetabulo-cristal buttress, at least in MH1) and short ischium (Kibii et al., 2011; Churchill et al.,
601 2018). Importantly, *Au. sediba* demonstrates that the derived pelvic features of *Homo* can evolve
602 in the absence of brain encephalization (Kibii et al., 2011; Churchill et al., 2018). Newly
603 recovered lumbar vertebrae of MH2 demonstrate morphology consistent with lumbar lordosis
604 and other adaptations to bipedalism, although features of the vertebrae themselves show a mix of
605 human-like and more ape-like aspects (Williams et al., 2021).

606 The *Au. sediba* lower limb shows a unique combination of morphologies unlike any other
607 known australopith. As in other australopiths (Ward et al., 2015), the femoral neck is long and
608 anteroposteriorly compressed (DeSilva et al., 2013, 2018) and, when combined with the pelvic
609 morphology, would likely increase both the contractile force of the abductors and the hip joint
610 reaction force that would, in turn, increase the mediolateral bending moments around the
611 proximal femoral shaft (Ruff, 1995). The MH2 distal femur possesses australopith-like condyles,

612 an unusually well-developed lateral patellar lip that is *Homo*-like, but lacks the anterior
613 projection of the patellar surface (DeSilva et al., 2013, 2018). The distal tibia of MH2 (and MH4)
614 has an ape-like mediolaterally thick medial malleolus that is thicker than other australopiths but
615 has a human-like articulation with the talus (Zipfel et al., 2011; Desilva et al., 2018).

616 The *Au. sediba* foot bones, some of which were found in articulation, each reveal their own
617 mix of human-like and ape-like features not observed in other fossil hominins. For example, the
618 MH2 talus is human-like in having a flat trochlea, but ape-like in having a talar head and subtalar
619 joint morphology that suggests high mobility (Prang, 2015b; 2016a; Zipfel et al., 2011). In both
620 MH1 and MH2, the calcaneal tuberosity is gracile with an ape-like dorsally-positioned lateral
621 plantar process, a morphology that is more basal than that characterizing *Au. afarensis* (Latimer
622 and Lovejoy, 1989; Zipfel et al., 2011; Prang, 2015b; DeSilva et al., 2018).

623 Taken together, the unusual morphology of the *Au. sediba* lower limb indicates that it was
624 clearly adapted to habitual bipedalism, but with distinct biomechanics compared with other
625 hominins (DeSilva et al., 2013). DeSilva et al. (2013) suggest a hyperpronating bipedal gait, in
626 which heel strike occurs on the lateral edge of an inverted foot (e.g., reflecting a gracile calcaneal
627 tuberosity), followed by extreme pronation that would internally-rotate the tibia and femur (e.g.,
628 reflecting a well-developed patellar lip). Moreover, pronation is also an important motion during
629 ape climbing (Stern and Susman, 1983) and thus the particular mosaic of features and gait
630 mechanics in the *Au. sediba* lower limb may also have been advantageous for arboreal
631 locomotion (DeSilva et al., 2013).

632 The overall morphology of the *Au. sediba* upper limb bones (both MH1 and MH2) is similar
633 to other australopiths (Churchill et al., 2013, 2018). The short length and joint orientations of the
634 clavicle, low humeral torsion, and a cranially-oriented glenoid fossa of the scapula, suggest the

635 scapula was positioned laterally and high on the thorax and that the upper limb was habitually
636 used in overhead arm postures (Churchill et al., 2013). The morphology of the elbow is also
637 similar to other australopiths, with well-developed epicondyles and an elongated brachioradialis
638 crest at the distal humerus, a well-developed insertion for the biceps brachii on the radius, and
639 ape-like morphology of the ulnar trochlea that generally reflect powerful arm, wrist, and digital
640 flexion that is advantageous for climbing (Churchill et al., 2013; Rein et al., 2017).

641 The relatively complete MH2 hand shows mosaic carpal morphology, including a
642 radioulnarly narrow lunate, that suggests a greater range of abduction at the radiocarpal joint and
643 perhaps less central-axis loading of the radiocarpal and midcarpal joints than is interpreted for
644 other fossil hominins (Kivell et al., 2011, 2018a). The metacarpals are relatively gracile,
645 including the first metacarpal, that in combination with the radial carpometacarpal region,
646 suggests limited force production by the thumb. However, intrinsic hand proportions reveal a
647 thumb that is surprisingly long relative to the fingers, and longer than that found in modern
648 humans, which would have facilitated opposition of the thumb to the fingers and pad-to-pad
649 precision gripping that is typical of later *Homo* (Kivell et al., 2011, 2018a). The MH2 proximal
650 phalanges show moderate curvature and, unusually, both the proximal and intermediate
651 phalanges have well-developed flexor sheath ridges that, in combination with a palmarly-
652 projecting hamate hamulus, suggest powerful flexion and that some degree of arboreality may
653 have been a functionally important part of the *Au. sediba* locomotor repertoire (Kivell et al.,
654 2011, 2018a; Syeda et al., 2021).

655 Finally, we can assess some limb proportions in *Au. sediba*. The complete right upper limb of
656 MH2 has a brachial index similar to A.L. 228-1, with a forearm relatively shorter than
657 *Ardipithecus* but longer than modern humans (Churchill et al., 2013). Interlimb comparisons

658 show that the upper limb articular size is smaller than those of the lower limb, which is typical of
659 bipedal hominins, but the intermembral index remains intermediate between that of African apes
660 and modern humans (Holliday et al., 2018). Relative to other hominins, *Au. sediba* joint
661 proportions are most similar to *Au. africanus*, as well as *H. habilis* and *Homo floresiensis*, and
662 are more ape-like than *Au. afarensis* (Prabhat et al., 2021).

663 Taken together, the *Au. sediba* postcrania indicate active selection for habitual, terrestrial
664 bipedalism, albeit with a unique bipedal gait relative to other hominins, and for short to medium
665 distances given that the lower limb is not as elongated as in early *Homo* (Kibii et al., 2011;
666 DeSilva et al., 2013; Holliday et al., 2018). However, there likely remained stabilizing selection
667 for arboreal competency, as indicated by the upper limb and hand morphology associated with
668 over-head arm support that includes developmentally plastic features associated with climbing
669 and suspension (i.e., keeled ulnar trochlear facet and curved phalanges) and mobile foot joints
670 that are advantageous for climbing (Holliday et al., 2018; Churchill et al., 2013; DeSilva et al.,
671 2013; Rein et al., 2017; Williams et al., 2021). We can also combine these locomotor inferences
672 with a remarkably long thumb that would increase dexterity in *Au. sediba*, but would also
673 enhance arboreal grasping in a hominin with relatively short fingers (Kivell et al., 2011, 2018a).

674 Hunt (1994) reiterated the dual-behavioral signal of A.L. 288-1 upper and lower limbs
675 highlighted by previous analyses (e.g., Senut, 1980; Tuttle, 1981; Jungers, 1982; Jungers and
676 Stern, 1983; Stern and Susman, 1983) and current fossil evidence still supports this functional
677 interpretation, not only for *Au. afarensis*, but also for StW 573 and *Au. sediba*. However, the
678 suite of anatomical features in each of these species is different, suggesting subtly or, in some
679 cases, dramatically different locomotor biomechanics for each taxon. Although the retention of
680 arboreal features in these early hominins, as well as other Middle to Late Pleistocene hominins

681 (Larson et al., 2009; Berger et al. 2015), lends strong evidence to active selection for forelimb-
682 dominated locomotion, questions remain over how frequent and significant these behaviors were
683 in the day-to-day life of a given hominin. How do we better understand how these hominins were
684 interacting with different paleoenvironments and how can we better infer behavior during a
685 hominin lifetime?

686

687 **5. Advances in methodological approaches for extracting functional information from** 688 **hominin fossils**

689

690 *5.1. Behavioral studies of wild, habituated great apes*

691

692 The foundation of Hunt's (1994) small-tree postural feeding hypothesis is rooted in his
693 observations of when, where, and for which purpose Mahale and Gombe chimpanzees used
694 bipedalism and the functional link between bipedalism and arm-hanging. Although additional
695 comprehensive locomotor studies of great apes since then are limited (Remis, 1994, 1998;
696 Doran, 1997; Thorpe and Crompton, 2006; Manduell et al., 2011; Sarringhaus et al., 2014), we
697 have gained a greater appreciation of behavioral variation within and between great ape species,
698 populations, and different ecological settings. Moreover, we have recognized the relevance of the
699 variation in African ape behavior, locomotor and otherwise, to our understanding of hominin
700 evolution (e.g., Pruetz et al., 2015; Luncz et al., 2018; Thompson et al., 2018; Wessling et al.,
701 2018).

702 Since Hunt's (1994) study, more recent positional behavioral investigations of chimpanzees at
703 other sites confirm their infrequent use of bipedalism (Doran, 1997; Stanford, 2006; Sarringhaus

704 et al., 2014; Drummond-Clarke et al., 2022). For example, in adult chimpanzees of Ngogo,
705 Uganda, bipedalism represents less than 2% of all locomotor time and they most frequently use
706 hand-assisted, flexed-hindlimb, bipedal walking (Sarringhaus et al., 2014). However, the
707 behavioral context of chimpanzee bipedalism (e.g., feeding, vigilance) has only been further
708 studied in the chimpanzees of Bwindi Impenetrable National Park, Uganda (Stanford, 2006).
709 Bipedalism in Bwindi chimpanzees was almost always postural and arboreal, and was most
710 commonly used during foraging, similar to Hunt's (1994, 1996) results. However, Stanford
711 (2006) highlighted bipedal use in an arboreal, rather than a terrestrial, context for the potential
712 emergence of bipedalism in hominins.

713 Based on subtle anatomical differences between chimpanzees and bonobos (e.g., more curved
714 phalanges, longer and narrower scapula), bonobos were hypothesized to engage in more
715 suspensory locomotion and bipedalism (Zihlman et al., 1978, 1996). Initial studies of bonobo
716 positional behavior confirmed this hypothesis, highlighting a greater frequency of arboreality in
717 bonobos compared with chimpanzees, including higher frequencies of leaping, arboreal
718 bipedalism (Susman et al., 1980; Susman, 1984), and suspension (Doran, 1992, 1993). However,
719 these initial studies focused largely on comparisons of arboreal behaviors only (i.e., without
720 terrestrial data) and were conducted on bonobo populations (Lomako and Wamba, Democratic
721 Republic of the Congo, DRC) that the researchers acknowledged were less habituated than their
722 chimpanzee comparators, potentially inflating the frequency of arboreality (Susman et al., 1980;
723 Susman, 1984; Doran, 1993). A more recent study of a habituated population (Lui Kotole, DRC),
724 however, suggests that bonobos (when sexes are pooled) are no more arboreal than chimpanzees
725 (56% of locomotor time on the ground and 44% in the trees) and suspensory locomotion is
726 extremely rare (<0.1% of locomotor time; Ramos, 2014).

727 Bonobo bipedalism varies by population: at Lomako, bipedal locomotion ranged between 1–
728 2% (Doran and Hunt, 1994) and 6–8% (Susman et al., 1980; Susman, 1984) of their arboreal
729 locomotor time, whereas at Wamba bonobos rarely used bipedal postures, even during feeding
730 (Kano and Malavwa, 1984; Hunt, 1991). At Lui Kotole, bipedalism, primarily postural, was used
731 6% of time spent in the trees but represented only 0.2% of total positional behavior (Ramos,
732 2014). Bipedal standing with arm-hanging—the foundation of Hunt’s (1994) hypothesis—was
733 rare in Lui Kotole bonobos (<0.01% of all postural time) and was used in the trees, rather than on
734 the ground, for feeding (Ramos, 2014).

735 Compared with chimpanzees, investigation of orangutan (*Pongo pygmaeus*) positional
736 behavior has also highlighted their slightly more common use of bipedal postures (7% of
737 arboreal time vs. 0.3% in Mahale/Gombe chimpanzees) and bipedal walking (7% of arboreal
738 locomotion vs. 7% in Mahale/Gombe chimpanzees and 3% in Tai chimpanzees; Thorpe and
739 Crompton, 2006). However, unlike the flexed hindlimbs of chimpanzees, orangutans typically
740 use extended hindlimbs during bipedalism, making them a potentially better model for the
741 ecological context in which bipedalism evolved in the panin-hominin ancestor (Thorpe and
742 Crompton, 2006; Thorpe et al., 2007; but see Begun et al., 2007).

743 The value of studying extant chimpanzees is also derived from the diverse landscapes they
744 inhabit, ranging from dense, closed forest, to open, dry woodland savanna, allowing researchers
745 to observe how locomotor (and other) behaviors may change in response to the habitat
746 (Lindshield et al., 2021). In particular, behavioral changes as a result of a more open and dry
747 environment are thought to have played a key role in hominin evolution and speciation
748 (Behrensmeyer, 2006). Previous comparisons of positional behavior in bonobos and
749 chimpanzees from different habitats, ranging from woodland/deciduous forest (Gombe,

750 Tanzania) to evergreen rainforest (Taï, Ivory Coast) showed that there was far less variation in
751 positional behavior between chimpanzee habitats (and subspecies) than between chimpanzees
752 and bonobos (Doran and Hunt, 1994; see also Doran, 1996). However, as highlighted by van
753 Leeuwen et al. (2020), the chimpanzee populations used in this comparative study all lived in
754 forested habitats. Chimpanzees living in dry, open savanna landscapes¹ like Fongoli, Senegal
755 (Pruetz and Bertolani, 2009; Wessling et al., 2018), Mt. Asserik, Senegal (McGrew et al., 1981),
756 and Issa Valley, Tanzania (Fig. 3; Piel et al., 2017; Drummond-Clarke et al., 2022) represent
757 particularly informative models for interpreting the evolutionary pressures that potentially
758 affected hominins.

759 Although the anatomy and ‘Bauplan’ of hominins differed from those of extant apes,
760 chimpanzees (and other primates) offer the opportunity to test hypotheses about how a large-
761 bodied, semi-arboreal ape may adapt its physiology or behavior to ecological constraints
762 similarly faced by hominins. For example, Fongoli chimpanzees experienced more physiological
763 stress due to heat and dehydration compared with fluctuating seasonal availability in food,
764 suggesting the importance of thermoregulatory selective pressures on hominins living in similar
765 environments (Wessling et al., 2018). A preliminary study of postural and locomotor bipedalism
766 at Fongoli found that bipedalism is still rare in Fongoli chimpanzees but they do it more often
767 (2.3% of all positional behavior time) than chimpanzees at Taï (1.2%, Doran, 1993), as well as
768 Mahale, Gombe and Bwindi, and used bipedalism most often during feeding, both in arboreal
769 and terrestrial contexts (Tourkakis, 2009). Issa chimpanzees living in a mosaic environment of
770 savanna woodland and riparian forest also change the frequencies of their locomotor behaviors
771 and substrate use in their different habitats (Drummond-Clarke et al., 2022). Interestingly,

¹ These include trees with a mostly open canopy, as defined by Lindshield et al. (2021) and van Leeuwen et al. (2020).

772 however, Issa chimpanzees do not increase their frequency of bipedalism in the open savanna
773 woodland, and in fact use just as much arboreal locomotion in the savanna woodland as
774 chimpanzees living in densely-forested habitats, contrary to expectations based on hominin
775 evolutionary models (Drummond-Clarke et al., 2022). Variation in habitat has also been shown
776 to influence orangutan locomotor behavior, including higher frequencies of bipedalism in dry,
777 lowland forests (Ketambe, Sumatra) compared with peat swamp forests (Suaq Balimbing,
778 Sumatra and Sabangau, Borneo; Manduell et al., 2012). These studies highlight how a large-
779 bodied semi- (or highly) arboreal ape may change the frequency of different positional behaviors
780 and context in which they are used (e.g., feeding, vigilance) based on. variation in habitat, both
781 across seasons and sites, which can help make more refined inferences of behavior in hominins.

782

783 *5.2. Australopith locomotor economy*

784

785 Given that *Au. afarensis* pelvic and lower limb morphology differs from that of later *Homo*,
786 Hunt (1994) suggested that early hominin bipedal locomotion was less efficient (i.e., consumed
787 more energy and caused greater muscle fatigue) relative to both modern human bipedalism and
788 ape quadrupedalism. Over nearly the past five decades, the locomotor economy of australopith
789 morphology has been inferred through experimental and comparative work in locomotor
790 energetics involving humans and chimpanzees (Rodman and McHenry, 1980; Pontzer and
791 Wrangham, 2004; Sockol et al., 2007; Pontzer et al., 2009, 2014; Pontzer, 2017). Mechanical
792 studies have demonstrated that the long hind limbs and straight-legged walking gait of humans
793 have greatly reduced the cost of transport during walking compared to chimpanzee
794 quadrupedalism and bipedalism (Sockol et al., 2007; Pontzer et al., 2014). In fact, human

795 walking is nearly twice as economical compared to that of chimpanzees (Pontzer, 2017).
796 Researchers have further expanded this experimental research to assess the energetic cost of
797 humans walking with bent hips and bent knees (Carey and Crompton, 2005) and crouched
798 postures (Johnson et al., 2022) to provide more informed inferences of early hominin bipedal
799 economy.

800 How does this recent experimental evidence fit with Hunt's (1994) hypothesis? Hunt (1994)
801 focused on *Au. afarensis* lower body anatomy reflecting less efficient bipedal locomotion (i.e.,
802 consumed more energy) compared with that of modern humans, which is not surprising given
803 that modern human bipedal functional morphology has had an additional three million years to
804 be positively selected and refined for energetic economy. Given the similarities in chimpanzee
805 bipedal gait kinematics compared to other nonhuman primates (D'Aout et al., 2004; Vereecke et
806 al., 2006; Demes, 2011), it is reasonable and parsimonious to assume that the locomotor costs of
807 the panin-hominin last common ancestor would have been similar to those of chimpanzees
808 (Pontzer et al., 2014). Based on knowledge at the time (Ishida, 1991), Hunt (1994) suggested that
809 early hominin bipedal locomotion would have been less economical than ape quadrupedalism.
810 However, energetically costly does not mean a particular gait or behavior was not possible, or
811 that it doomed a species to extinction; as Daegling (2022:p. 125) highlighted, since all bipedal
812 traits did not appear simultaneously, "[t]here must have been a phase of hominin evolution that
813 involved a highly inefficient manner of bipedal progression." Susman et al. (1984:p. 113)
814 creatively articulated the same view: "Must not there have been a period of time when both the
815 trees and the ground served as important areas for life's activities, as they do today for living
816 great apes? Must not there have been a period of time when the human ancestor was neither as
817 good at moving on two legs as it could become, nor as good at scrambling in the trees as it once

818 had been? We expect that such a period of time did exist”. In addition, given the similarity in
819 locomotor costs between chimpanzee quadrupedal and bipedal walking (Sockol et al., 2007;
820 Pontzer et al., 2009, 2014), increasing the frequency of bipedal locomotion in early hominins
821 would not necessarily have increased the costs of bipedalism (Pontzer et al., 2009, 2014) and,
822 indeed, early hominin bipedalism could have been less costly than non-bipedal behaviors
823 (Sockol et al., 2007).

824 The mechanics of early hominin bipedalism, as highlighted by Hunt (1994), are key to
825 inferring locomotor costs. Recent studies of *Au. afarensis* bipedal gait from preserved
826 morphology using a variety of modeling methods and parameters, generally agree that the
827 energetic costs of bipedal locomotion in *Au. afarensis* were more economical than chimpanzee
828 locomotion (Thompson et al., 2015) and potentially similar to those of modern humans
829 (Crompton et al., 1998; Nagano et al., 2005; Sellers et al., 2005). Indeed, a slightly longer
830 (relative to African apes) and extended hind limb paired with a stiff, non-grasping foot, and,
831 although mediolaterally broad, a more human-like pelvis in *Au. afarensis* (Stern, 2000; Jungers,
832 2009), are all consistent with human-like locomotor economy (Nagano et al., 2005; Sellers et al.,
833 2005).

834 Furthermore, even though Hunt’s (1994) hypothesis is still consistent with recent studies of
835 great apes using (hand-assisted) bipedal postures and locomotion within small, terminal branches
836 for feeding (Stanford and Nkurunungi, 2003; Thorpe et al., 2007; Crompton et al., 2008), recent
837 research suggests that the retention of arboreal adaptations within the *Au. afarensis* forelimb may
838 not have been more energetically economical compared to habitual bipedalism, as Hunt (1994)
839 hypothesized. The energetics of rock climbing in modern humans showed that variation in
840 human limb proportions or body mass have minimal effects on the climbing costs of transport

841 (Kozma and Pontzer, 2021) and that human costs of climbing are similar to those of other
842 primates (Hanna et al., 2008; Hanna and Schmitt, 2011). Experimental research on humans and
843 nonhuman primates suggests that arboreal postcranial adaptations, such as longer forelimbs or
844 curved digits, do not substantially decrease climbing costs (Hanna et al., 2008; Kozma and
845 Pontzer, 2021). Thus, although the potential energetic costs and savings of the *Au. afarensis*
846 upper and lower body may not be what Hunt (1994) originally predicted, the dual functional
847 signals of the australopith postcranium are consistent with Sylvester’s (2006) ‘decoupling
848 hypothesis’ positing that early hominins should require efficient forms of both terrestrial and
849 suspensory locomotion. That being said, energy expenditure is only one possible performance
850 attribute among others that selection can act upon (Pontzer and Wrangham, 2004).

851

852 *5.3. The study of internal bony structure*

853

854 Hunt’s (1994) functional interpretation of the *Au. afarensis* postcranium also included
855 inferences about the associated bone stresses, particularly those incurred at the hip joint, during
856 locomotion. Since that time, a considerable amount of research has been dedicated to developing
857 analytical tools, many of which are virtual (Pandolfi et al., 2020), to improve our inferences of
858 behavior in hominin taxa from skeletal morphology (e.g., Sellers et al., 2005; Gross et al., 2014;
859 Dunmore et al., 2018; Karakostis et al., 2018; Ruff, 2018; DeMars et al., 2021; Profico et al.,
860 2021). Here we discuss advancements in one of these virtual tools, namely, the analysis of
861 internal bone structure based on the concept of bone functional adaptation, within a comparative
862 extant primate context (Cowin, 2001; Currey, 2006; Ruff et al., 2006). Both cortical and
863 trabecular bone model and remodel throughout life to adjust structurally to the local loading

864 environment (Martin et al., 1998; Lieberman et al., 2003; Ruimerman et al., 2005; Currey, 2006;
865 Ruff et al., 2006; Bonewald and Johnson, 2008; Gosman et al., 2011; Allen et al., 2014; Barak,
866 2020). Because trabecular bone is more metabolically active (Huiskes, 2000; Jacobs, 2000;
867 Currey, 2006) and (re)models faster (~25% annual bone turnover) than cortical bone (~2–3%) in
868 adults (Eriksen, 1986, 2010), it can be more responsive to changes in load magnitude, direction,
869 or frequency (reviewed in Kivell, 2016; but see Lovejoy et al., 2003).

870 While many questions remain concerning the functional relationship between the ‘container’
871 (the cortical shell) and the ‘contents’ (the inner structural organization), both bone structures
872 have been experimentally shown to provide functional information about site-specific loading
873 conditions during one’s life (van der Meulen et al., 1993, 1996; Ruff et al., 1994, 2006; van der
874 Meulen and Carter, 1995; Biewener et al., 1996; Guldborg et al., 1997; Robling et al., 2002;
875 Mitra et al., 2005; Pontzer et al., 2006; Carlson and Judex, 2007; Polk et al., 2008; Barak et al.,
876 2011; Harrison et al., 2011; Carlson and Marchi, 2014; Christen et al., 2014). For example,
877 experimental research on the human female tibia showed that diaphyseal cortical bone geometry
878 in young adults retained signals of childhood/adolescent loading regardless of adult activity
879 (Murray and Erlandson, 2021). By contrast, distal tibial trabecular bone density was found to
880 reflect post-menarcheal loading, regardless of pre-menarcheal loading patterns (Murray and
881 Erlandson, 2021). The last two decades have seen several technological advances in high-
882 resolution 3D imaging (as well as access to this technology) and methods for quantifying and
883 statistically comparing variation in internal bone structure (e.g., Pahr and Zysset, 2009; Bondioli
884 et al., 2010; DeMars et al., 2021; Profico et al., 2021; Veneziano et al., 2021; Bachmann et al.,
885 2022), while limiting risk to fossil specimens (e.g., Macchiarelli and Weniger, 2011; Weber,
886 2015; but see Le Cabec and Toussaint, 2017). This has led to a substantial increase in the number

887 of studies investigating the potential functional signals within internal bone structure, and
888 particularly trabeculae, in fossil hominin remains and extant hominid taxa, that can help
889 paleontologists better distinguish ecophenotypic features from basal retentions (e.g., Puymeraill
890 et al., 2012a, b, 2013; Cazenave et al., 2017, 2019, 2021; Tsegai et al., 2013, 2018; Dunmore et
891 al., 2019; 2020a, b; Bird et al., 2021; Su and Carlson, 2017; Georgiou et al., 2018, 2019, 2020;
892 Sukhdeo et al., 2020; Bird et al., 2022; see Kivell, 2016 and references therein).

893 Analysis of internal bone structure in different associated elements of the skeleton, especially
894 concurrently from the upper and lower limbs, can reveal complementary evidence essential to
895 reconstructing actual habitual behavior of early fossil hominins characterized by a mosaic
896 postcranium. However, such analyses are rare for several reasons, including: 1) the paucity of
897 associated, relatively complete skeletons in the early hominin fossil record, 2) the inherent
898 methodological challenges of accessing imaging technology, especially high-resolution imaging,
899 and the time-consuming nature of some analyses (e.g., segmentation of bone from matrix or the
900 computational power required to quantify complex internal structures in 3D), and 3) lack of
901 access to particular fossil specimens or, when accessible, the lack of adequate preservation of
902 internal structures. Below we consolidate the functional inferences that have been drawn from
903 analysis of the cortical or trabecular structures in gracile and robust australopiths (Fig. 4) to
904 highlight the value that internal analyses can bring to understanding the dual nature of the upper-
905 and lower-limb external morphology that Hunt's (1994) hypothesis aimed to accommodate.

906 *Australopithecus afarensis* Relative differences in cortical bone cross-sectional geometry
907 between the upper and lower limb bones can provide information about the significance of
908 forelimb-dominated vs. bipedal locomotion. Analysis of the cross-sectional geometry of A.L.
909 288-1 shows femoral/humeral diaphyseal strength proportions that are intermediate between

910 those of chimpanzees and modern humans, indicating more mechanical loading of the forelimb
911 than in humans, which is consistent with significant use of arboreal locomotor behaviors (Ruff et
912 al., 2016). Moreover, relative femoral head size, femoral neck cortical bone distribution, and
913 cross-sectional shape of the proximal shaft suggest a bipedal gait involving more lateral
914 deviation of the body's center of mass over the support limb than is typical of a modern human
915 gait, which would have increased the costs of terrestrial locomotion (Ruff et al., 2016).

916 Trabecular analysis of *Au. afarensis* metacarpals also shows a pattern of trabecular
917 distribution that is intermediate between that of modern humans and other extant apes, and
918 distinct from other australopiths, suggesting the use of powerful flexed-fingered grasping during
919 both arborealism and manipulation (Kivell et al., 2018b; Dunmore et al., 2020b). Future analyses
920 of other *Au. afarensis* skeletal elements will likely provide a more refined reconstruction of *Au.*
921 *afarensis* behavior, although preservation of internal bone structures in the Pliocene remains of
922 East Africa is limited.

923 *Australopithecus africanus* The internal structure of the *Au. africanus* lower limbs has been
924 thoroughly investigated, providing subtle, complementary information to the external
925 morphology that can be used to reconstruct the locomotor behavior in this taxon. One of the first
926 analyses used a series of calibrated radiographs to comparatively describe the trabecular
927 architecture of several adult and juvenile *Au. africanus* ilia (Macchiarelli et al., 1999, 2001). The
928 trabecular structures suggest that the *Au. africanus* pelvis underwent a loading regime
929 commensurate with a bipedal gait, but somewhat different from that typical of modern humans
930 (Macchiarelli et al., 1999, 2001). A volume-of-interest analysis of the trabecular structure within
931 multiple *Au. africanus* femoral head specimens revealed a pattern more similar to that of modern
932 humans and Pleistocene *Homo* than to the typical extant ape condition, which is also consistent

933 with a human-like bipedal gait, including the habitual use of a more extended hip (Ryan et al.,
934 2018). Similarly, a ‘whole-bone’ analysis of the trabecular structure in *Au. africanus* femoral
935 head specimen StW 522 also revealed a human-like pattern of loading at the hip joint and that
936 *Au. africanus* likely did not climb (i.e., habitually load its hip joint in a flexed posture) at the
937 frequencies seen in extant nonhuman apes or other Sterkfontein hominins (Georgiou et al.,
938 2020).

939 In line with these results, the cortical distribution at the femoral neck confirmed a bipedal gait
940 in *Au. africanus*, but somewhat different from that typical of modern humans. Sterkfontein *Au.*
941 *africanus* specimens have relatively more symmetric superior and inferior femoral neck cortices
942 at the mid-neck than modern humans, but a more human-like pattern at the base of the neck,
943 suggesting greater superoinferior bending loads during bipedal locomotion in *Au. africanus*
944 (Ruff and Higgins, 2013; Ruff et al., 2016). The orientation of trabecular struts in *Au. africanus*
945 distal tibiae indicates that *Au. africanus* primarily loaded its ankles in a relatively extended
946 posture (plantarflexed) like that of modern humans and unlike chimpanzees, indicating a human-
947 like gait with an efficient, extended lower limb (Barak et al., 2013). Indeed, the trabecular bone
948 orientation of the distal tibia implies the use of talocrural joint plantarflexion, which humans use
949 at the end of the push-off phase—a distinctive feature of the biomechanics of bipedalism (Sockol
950 et al., 2007; Pontzer et al., 2009; Barak et al., 2013).

951 While the investigation of the ilium, femur, and tibia internal bone structure generally agree
952 that *Au. africanus* engaged in habitual, terrestrial bipedalism with a slightly altered gait
953 compared with modern humans, the results of the trabecular and cortical distribution in the foot
954 bones are more puzzling. For example, *Au. africanus* tali show that trabecular strut orientation in
955 the antero-medial region is ape-like, implying that this hominin may not have had the derived

956 human-like medial weight shift during the last half of stance phase (Su and Carlson, 2017).
957 Trabecular bone density distribution in the calcaneum (StW 352) suggests that the *Au. africanus*
958 heel experienced more variable loading than modern humans but less so than African apes,
959 consistent with a large range of foot movements with locomotor kinematics that are unlike those
960 of extant humans or apes (Zeininger et al., 2016). Finally, the cortical diaphysis of the *Au.*
961 *africanus* fifth metatarsal shows a human-like dorsoplantar reinforcement for resisting
962 dorsoplantar loading, but which is achieved via cortical thickening rather than increased
963 dorsoplantar external dimensions, as seen in extant humans (Dowdeswell et al., 2016).

964 Reconstruction of the locomotor behavior in *Au. africanus* from upper limb internal bone
965 structure has focused on the humerus and hand bones. Functional inferences from the trabecular
966 structure within the *Au. africanus* StW 328 humeral head are limited due to the fragmentary
967 preservation of this specimen, but its high trabecular bone volume and more isotropic trabecular
968 structure is most similar to nonhuman hominoids (Kivell et al., 2018c). This pattern indicates
969 higher magnitude and more diverse loading of the humeral head than that of modern humans and
970 suggests *Au. africanus* may still have used its forelimbs for arboreal locomotion (Kivell et al.,
971 2018c). *Australopithecus africanus* metacarpal trabecular structure shows a pattern that is
972 intermediate between that of humans and other apes (Skinner et al., 2015; Dunmore et al.,
973 2020b). Although the metacarpals show a high *Pan*-like trabecular density, the asymmetrical
974 distribution of trabeculae within the metacarpal heads is similar to that of modern humans,
975 suggesting habitual, and potentially forceful, opposition of the thumb towards the fingers
976 (Skinner et al., 2015). However, an analysis of the cortical bending stiffness of the *Au. africanus*
977 StW 418 first metacarpal relative to that of the ulnar rays was more similar to great apes
978 (Dunmore et al., 2020b). Future study of the *Au. africanus* distal humerus (Arias-Martorell et al.,

979 2021), and radius and ulna internal bone structure, will provide further clarity on arm loading
980 and use in this taxon.

981 *Paranthropus robustus* and *Paranthropus boisei* Investigation of internal bone structure in
982 *Paranthropus* shows that it presents a similar picture to that outlined above for *Au. africanus*.
983 Indeed, many studies have grouped gracile and robust australopiths together because the
984 functional signals are similar, including in the ilium (Macchiarelli et al., 1999, 2001), femoral
985 head (Ryan et al., 2018), femoral neck (Ruff and Higgins, 2013; Ruff et al., 2016), and first
986 metacarpal (Skinner et al., 2015). Functional interpretations from *P. robustus* lower limb cortical
987 and trabecular structure confirm habitual, terrestrial bipedal locomotion but with a slightly
988 different gait compared with modern humans (Macchiarelli et al., 1999, 2001; Bleuze, 2010;
989 Ruff and Higgins, 2013; Ruff et al., 2016), including a more limited range of habitual hip joint
990 postures (Ryan et al., 2018) and increased mechanical loading of the proximal femoral diaphysis
991 (Ruff et al., 1999).

992 However, recent studies of cortical distribution and trabecular organization of the femoral
993 neck in five *P. robustus* specimens from Swartkrans reveal distinct internal features in *P.*
994 *robustus* that are not observed in modern humans or *Pan* (Cazenave et al., 2019, 2021). The
995 functional significance of this specific configuration in the *P. robustus* femoral neck or their
996 presence in other australopiths may support a somewhat different locomotor repertoire in *P.*
997 *robustus* compared with *Au. africanus*, a hypothesis that requires further investigation. Analysis
998 of the trabecular distribution throughout the femoral head in two Sterkfontein specimens, one
999 attributed to *Au. africanus* (StW 522) and one possibly attributed to *P. robustus* (or *Homo*; StW
1000 311), indicates distinctly different loading regimes despite overall similarity in external
1001 morphology (Georgiou et al., 2020). The possible *P. robustus* specimen shows an ape-like

1002 pattern of femoral head loading in both flexed- and extended-hip postures, consistent with
1003 regular bouts of climbing and terrestrial bipedalism (Georgiou et al., 2020).

1004 Trabecular structure within the *P. robustus* (TM 1517) and presumed *P. boisei* tali (KNM-ER
1005 1464) show a human-like pattern in the antero-medial subregion (in contrast to the ape-like
1006 pattern in *Au. africanus*), suggesting *Paranthropus* may have had a human-like medial weight
1007 shift during the last half of stance phase (Su et al., 2013; Su and Carlson, 2017). This is one of
1008 the few studies identifying functional differences between *P. robustus* and *Au. africanus* (see
1009 also Beaudet et al., 2019; Braga et al., 2021). The trabecular structure of the *P. robustus* first
1010 metatarsal (SKX 5017 from Swartkrans Member 1) suggests hyper-dorsiflexion at the
1011 metatarsophalangeal joint, which is distinct from the trabecular pattern found in SK 1813,
1012 another (juvenile) first metatarsal from Swartkrans that is not attributed to a specific taxon
1013 (Komza and Skinner, 2019). Evidence for consistent loading in hyper-dorsiflexion in SKX 5017
1014 suggests terrestrial bipedal gait with a toe-off that is beyond the range of motion typically found
1015 in modern humans (Komza et al., 2019). Like *Au. africanus*, the *P. robustus* fifth metatarsal also
1016 shows dorsoplantar cortical thickening to resist human-like dorsoplantar loading but does not
1017 exhibit distal shaft tapering in cortical thickness, which is found in modern humans and *Au.*
1018 *africanus* (Dowdeswell et al., 2016).

1019 For the upper limb, only the internal structure of the distal humerus of *Paranthropus* has been
1020 investigated, showing a clear dichotomy between *P. robustus* and modern humans and *Homo*
1021 *erectus* in the morphology and cortical bone distribution, including thicker cortex in *P. robustus*
1022 (Cazenave et al., 2017). The distal humerus of *P. boisei* also shows high bending strength
1023 comparable to that of extant great apes (as well as *Au. afarensis* and *H. habilis*) and considerably

1024 higher than that observed in later *Homo*, indicating powerful upper limbs and habitual climbing
1025 behavior (Lague, 2019).

1026

1027 **6. Where is the field and future directions**

1028

1029 What have we learned about australopiths since Hunt (1994)? Over the last two and half
1030 decades, more paleoanthropologists have accepted that australopiths were both committed bipeds
1031 and adept climbers. This greater consensus has stemmed from additional fossil evidence that has
1032 made clear that the dual-functional signal of the *Au. afarensis* skeleton is common to all known
1033 australopiths (and other hominins). Moreover, this dual-functional signal comprises different
1034 combinations of anatomical features across australopiths, the consequences of which are
1035 biomechanical variation in bipedal posture and gait and likely overall positional behavior. Thus,
1036 the australopith ‘lower-body biped’ and ‘upper-body arborealist’ (be it arm-hanging or climbing)
1037 ‘Bauplan’ that was the anatomical basis for Hunt’s (1994, 1996) postural feeding hypothesis is
1038 still upheld, but with greater variation across all regions of the skeleton and perhaps greater
1039 variation temporally than originally imagined. Indeed, recent fossil evidence and new analyses
1040 suggest *Au. afarensis* had more human-like morphology and was a more committed terrestrial
1041 biped than geologically younger australopiths (e.g., *Au. africanus*, *Au. sediba*) and even some
1042 *Homo* taxa (e.g., Ward et al., 2011; Prang et al., 2015a,b, 2016b; Boyle et al., 2018; DeSilva et
1043 al., 2019; Prabhat et al., 2021). Current debates are perhaps less divisive than in the 1980s since
1044 new fossil discoveries urged more researchers to move closer to the ‘compromise camp’
1045 approach. Instead, debates center on more detailed biomechanical implications of australopith
1046 anatomical variation, including the specifics of bipedal gait or climbing strategy, within and

1047 between species. Such debates will likely continue as future fieldwork will undoubtedly reveal
1048 more surprise morphologies in temporal periods or geographical regions we currently would not
1049 predict. A greater understanding of human and great ape anatomy, positional behavior, and
1050 locomotor kinematics and kinetics, as well as a greater appreciation of anatomical and
1051 biomechanical variability within extant taxa, has allowed researchers to better test functional
1052 hypotheses about fossil hominin morphology and offer more refined locomotor reconstructions.

1053

1054 *6.1. Are extant primates good models for reconstructing past behaviors and, in turn, hominin*
1055 *evolution?*

1056

1057 As Washburn (1967:p. 21) aptly summarized, “[t]he understanding of human evolution comes
1058 from three different sources: from general evolutionary theory, from the fossils, and from the
1059 behavior and biology of the living primates”. Over the last 50+ years, we have improved our
1060 knowledge of all three sources and, in turn, have a much deeper appreciation of the complexity
1061 of human evolutionary history. Hypotheses about the origins of bipedalism are contingent on the
1062 reconstructed positional behavior of the panin-hominin last common ancestor and that of early
1063 hominins, for which there are two general approaches; one which directly relies on
1064 morphofunctional interpretations of the fossil record (i.e., the ‘bottom-up’ or ‘worm’s eye’
1065 approach) and the other founded in the behavior and biomechanics of living primates, notably
1066 *Pan* (i.e., the ‘top-down’ or ‘bird’s eye’ approach; e.g., Diogo et al., 2017; Pilbeam and
1067 Lieberman, 2017; Almécija et al., 2021). Each approach offers valuable, complementary
1068 information and both are needed to understand the earliest stages of human evolution, as well as
1069 those of African apes. However, the hominid fossil record of the Late Miocene and earliest

1070 hominin radiation is both scanty and heterogeneous, especially for the postcranial elements. In
1071 addition, extant apes represent a restricted and biased sample of a much larger Middle-to-Late
1072 Miocene ape radiation that very likely displayed a much greater variety of locomotor solutions
1073 (e.g., Pina 2016; Böhme et al., 2019).

1074 Thus, any additional information we can learn about how African apes, and primates in
1075 general, adapt, behave, or interact within their varying ecological settings provides potential
1076 natural experimental evidence for improving our understanding of the behavior and selective
1077 pressures in the past (in addition to improved conservation efforts to ensure we have more time
1078 to learn from the many endangered primate species). We support the perspective of Pontzer et al.
1079 (2014:p. 79) that understanding the relationship between locomotor form and function in African
1080 apes “is important, not because *Pan* is a perfect model of the earliest hominins, but because it
1081 enables us to test biomechanical models of locomotor performance in a large-bodied semi-
1082 arboreal primate”. This perspective reaches beyond biomechanical models and beyond just
1083 chimpanzees: it is only through the (ethical) investigation of living primates that we can test
1084 hypotheses of how behavior is reflected in external and internal bone structure to more
1085 accurately interpret past behavior. Although we must remember that modern humans and extant
1086 great apes are not ideal models with which to compare fossil hominin taxa (Daegling, 2002),
1087 experimental or behavioral studies of primates in captivity (e.g., Schmitt, 2003; Hanna et al.,
1088 2008; Pontzer et al., 2014; O’Neill et al., 2015; Samuel et al., 2018) or in natural settings (e.g.,
1089 DeSilva, 2009; Thompson et al., 2018; Neufuss et al., 2018; Ostrofsky et al., 2019; Thompson et
1090 al., 2018;Wessling et al., 2018), 3D imaging of human bone structure (e.g., Schipilow et al.,
1091 2013; Macintosh et al., 2017; Pomeroy et al., 2019), and recent advances in primate archaeology
1092 (e.g., Luncz et al., 2016; Proffitt et al., 2016, 2018) are excellent examples of the utility of

1093 studying living primates and their impact on our interpretation of the hominin paleontological or
1094 archaeological record.

1095

1096 *6.2. Do we need more fossils?*

1097

1098 In 2000, White questioned: “[w]ill our textbooks ever be illustrated with skeletons rather than
1099 scraps?” (White, 2000:p. 290). Many others have recognized the need to find more, and more
1100 complete, fossil evidence. For instance, Wood and Leakey (2011:p. 264) stated that “[t]he early
1101 hominin fossil record is too meager to do anything other than offer very provisional statements
1102 about hominin taxonomy and phylogeny”. Foley et al. (2016:p. 6) concluded that “[i]t might
1103 seem that modeling, ancient genomes and three-dimensional morphometrics are the keys to the
1104 future, but all these depend on the continuing accumulation of new fossils and the discovery of
1105 new archaeological and palaeontological sites”.

1106 In 2022, this review has highlighted only a few of the many incredible paleontological
1107 discoveries of the last two decades, including several near-complete skeletons of different
1108 hominin species (e.g., White et al., 1994; Brown et al., 2004; Lordkipanidze et al., 2007; Berger
1109 et al., 2015; Williams et al., 2018; Stratford and Crompton, 2021) that have challenged previous
1110 knowledge based on isolated and/or more fragmentary specimens. These discoveries allow us to
1111 robustly estimate body proportions or the overall Bauplan and to provide more holistic functional
1112 inferences about behavior, including from both the upper and lower limbs. These discoveries
1113 have also brought to light intriguing combinations of morphologies in hominin individuals that
1114 paleoanthropologists could not have predicted (e.g., Brown et al., 2004; Berger et al., 2010,
1115 2015; Stratford and Crompton, 2021). But to interpret these morphologies, these discoveries also

1116 highlight the importance of using and developing new tools that allow us to extract more
1117 accurate and refined functional information from the fossils themselves. These discoveries show
1118 that we will always need more fossils, ideally representing both sexes and a variety of
1119 ontogenetic stages, and that each will add both clarity and complexity to our understanding of
1120 hominin evolution.

1121 Evolutionary questions, however, inherently rely on the phylogenetic relationships among
1122 fossils. Therefore, more fossils will not necessarily or automatically provide better resolution of
1123 evolutionary questions. Chronology alone cannot be used as a proxy for phylogeny as fossils
1124 sample only snap-shots in time, older lineages can persist through time and retain ancestral
1125 character states, and homoplasy (via parallelisms or reversals) will be pervasive. With each fossil
1126 discovery, new hominin phylogenetic reconstructions and the subsequent interpretations that are
1127 drawn from them should be considered one of many possible hypotheses and homoplasy is a
1128 given (Wood and Harrison, 2011; Daegling, 2022).

1129

1130 *6.3. Do we need more tools to investigate the fossil record?*

1131

1132 The need for more fossils is undeniable and when we find them, there are few opportunities to
1133 appropriately extract the specimens and to exhaustively document their immediate context before
1134 irrevocably altering the ‘crime scene’ (e.g., Flannery, 1982; White, 2000; Foley, 2016). New
1135 developments in geochemistry (e.g., Passey et al., 2010), paleoproteomics (e.g., Welker et al.,
1136 2016), and ancient DNA (e.g., Massilani et al., 2022) have demonstrated that valuable
1137 evolutionary information can be derived from sources that only a few years ago would have
1138 likely been discarded or ignored. Thus, any methodological effort to improve or preserve the

1139 resolution of fossils in situ should be encouraged, especially in anticipation of future
1140 methodological developments to answer functional and evolutionary questions.

1141 Regarding the reconstruction of behavior in the past, recent advances in biomechanical
1142 modeling, including musculoskeletal modeling and the use of finite element analysis (e.g.,
1143 O’Higgins et al., 2017), have provided more nuanced interpretations of fossilized morphology.
1144 These methods are time-consuming and require living participants (e.g., O’Neill et al., 2015) or
1145 anatomical specimens (Synek et al., 2019) to ensure models are biologically realistic, but they
1146 have the potential ability to more accurately infer function from variation in form (e.g., O’Neill
1147 et al., 2015; Püschel and Seller, 2016; Püschel et al., 2018; Bucchi et al., 2020; Pina et al., 2020;
1148 Synek et al., 2020).

1149 Paleoanthropological research has also greatly benefited from the development of
1150 nondestructive investigative technologies based on high-resolution computed tomography (μ CT)
1151 and synchrotron radiation microtomography that are able to render at micrometric scale the
1152 external and internal structures of the mineralized tissues for detailed quantitative analyses.
1153 Importantly, the recent use of neutron microtomography for high-resolution imaging of highly-
1154 mineralized fossil specimens has been able to reveal internal structures that were not accessible
1155 via μ CT X-rays (e.g., Zanolli et al., 2020). It is thus probable that future analyses will
1156 increasingly combine information derived from both the external and internal fossil morphology.
1157 Although access to high-resolution imaging technology and freeware development offer
1158 researchers the ability to analyse the ‘hidden evidence’ from inside fossils, there is still a long
1159 way to go in terms of the infrastructure and accessibility of these resources in the countries for
1160 which almost all hominin fossils are discovered. Moves toward greater open-access data sharing

1161 in ways that support the curatorial institutions are a welcome improvement (e.g., [The Human](#)
1162 [Fossil Record](#) and [Morphosource.org](#)).

1163

1164 **7.0 Moving forward**

1165 Despite the advances described above, some enduring questions remain. Even if most researchers
1166 now recognize that commitment to bipedalism does not require the full abandonment of
1167 arboreality (c.f. e.g., Latimer and Lovejoy, 1990), determining the frequency of climbing or
1168 suspensory behaviors in the day-to-day life of a hominin is still a challenging, if not impossible,
1169 quest. The complete anatomy of any given organism does not map directly to its most frequent
1170 behavior(s), infrequent behaviors that are mechanically demanding or have a higher negative
1171 impact on fitness also influence morphology, and any given morphology can be used for a
1172 multitude of behaviors. All paleontologists must work under the assumption that morphology
1173 reflects behavior, but identifying the evolutionary significance of behavioral differences within
1174 (e.g., sex differences in positional behavior) and between hominin species will always be
1175 challenging. Such endeavors will likely require fossil samples of multiple individuals and
1176 differing ontogenetic stages, osteological or molecular data on sex (e.g., Stewart et al., 2017),
1177 independent (and detailed) ecological information (e.g., local landscape, diet), a combination of
1178 methodological approaches (e.g., biomechanical modeling, analyses of internal bone structure,
1179 extant analogues), and potentially archaeological evidence (lithic or organic; e.g., Luncz et al.,
1180 2020) to reach a robust understanding of how a particular hominin species interacted in its
1181 paleoenvironment. Advances along all of these lines of evidence make this goal more attainable.

1182

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1184

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Figure captions

Figure 1. List of human-like derived features and ape-like features in the upper limb and axial skeleton (orange) as well as pelvic girdle and lower limb (blue) in *Australopithecus afarensis* (A.a.), ‘*Australopithecus prometheus*’ (partial skeleton StW 573; A.p.) and *Australopithecus sediba* (A.s.). Note that if there is no specific mention of a species for a feature, it means either that the feature is absent or non-identifiable in this species for preservation and taphonomical reasons.

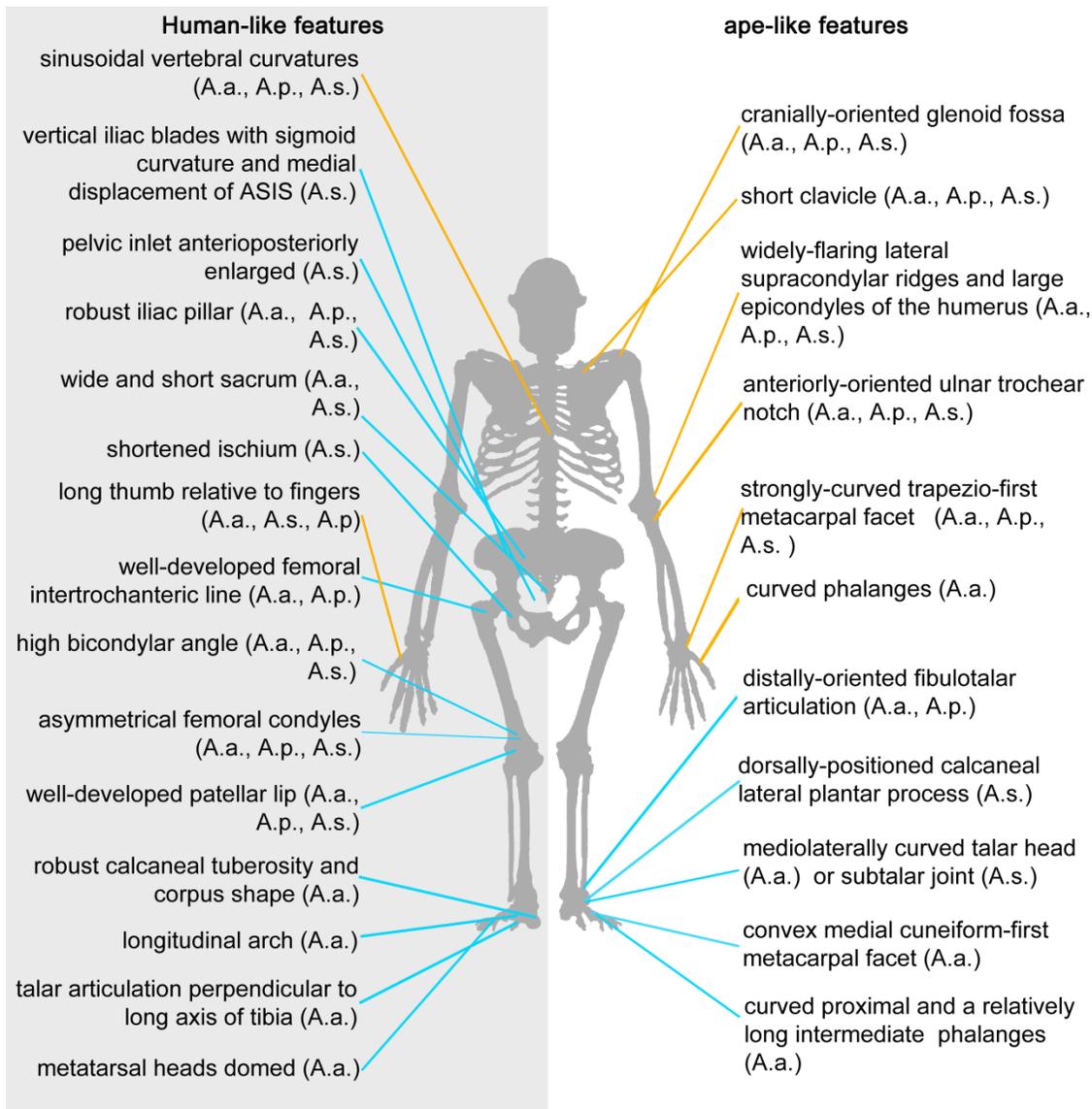


Figure 2. Partial skeletons of a) *Australopithecus afarensis* A.L. 288-1 adult female, b) StW 573 '*Australopithecus prometheus*', likely an adult female (courtesy of Paul Myburgh), and c) *Australopithecus sediba* MH2 adult female. Images sourced from Ruff et al. (2016), Williams et al. (2018), and Palakovic (2021). Reproduced with permission of The Licensor through RightLinks.

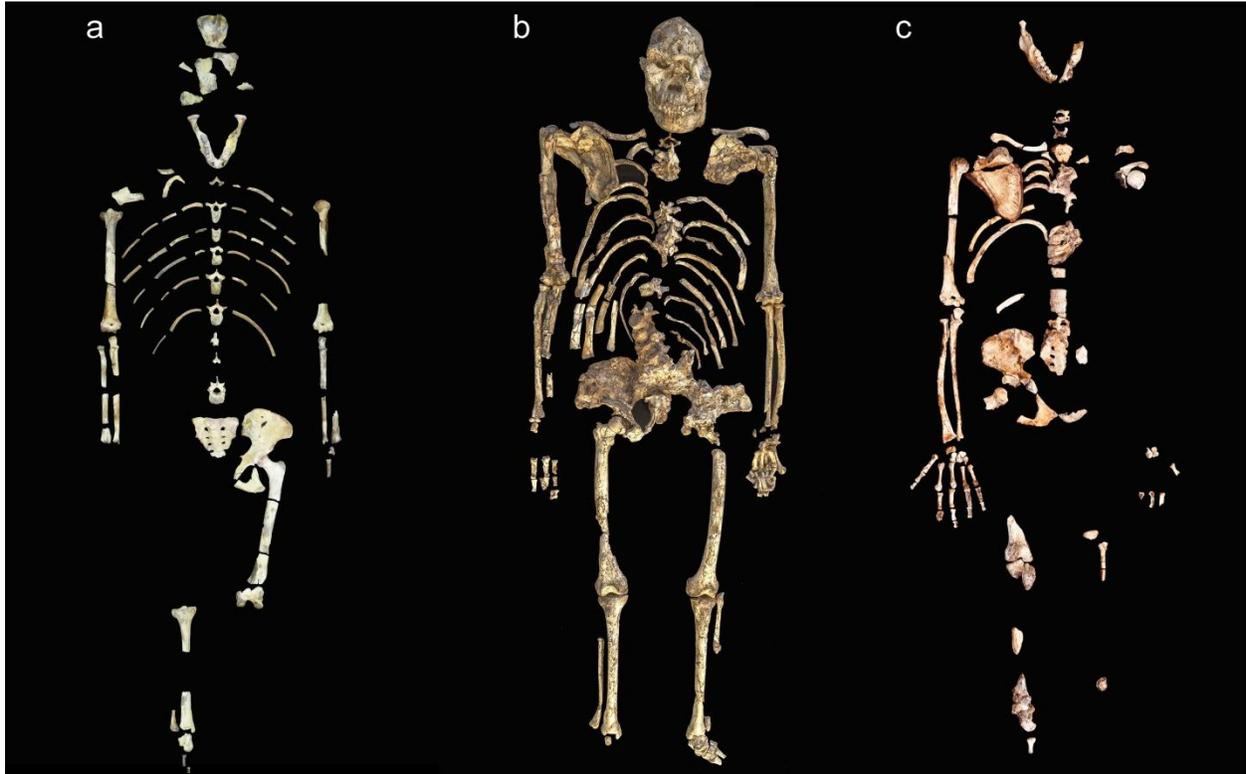


Figure 3. Chimpanzees (*Pan troglodytes schweinfurthii*) of Issa Valley, Tanzania that live in a, b) a savanna-mosaic habitat of miombo woodland and c) riparian forest similar to reconstructed paleoenvironments of early hominins. Contrary to expectations based on hominin evolutionary models, Issa chimpanzees engage more frequently in bipedalism in the forest than in the more open woodland, and use just as much arboreal locomotion in the open woodland as chimpanzees that live in more densely-forested habitats (Drummond-Clarke et al., 2021). Photo credit to Rhianna Drummond-Clarke.



Figure 4. Cortical and trabecular bone preservation and structure of different skeletal remains likely attributed to *Australopithecus africanus*, *Paranthropus robustus*, and *Paranthropus boisei*. Images sourced from Macchiarelli et al. (1999), Barak et al. (2013), Su et al. (2013), Zeininger et al. (2016), Cazenave et al. (2017, 2021), Su and Carlson (2017), Kivell et al. (2018c), Ryan et al. (2018), Komza et al. (2019), and Lague (2019). Reproduced with permission of The Licensor through RightLinks.

