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1 **Title: The implications of thumb movements for Neanderthal and modern human**
2 **manipulation**

3
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19 **Abstract**

20 Much research has debated the technological abilities of Neanderthals relative to those of early
21 modern humans, with a particular focus on subtle differences in thumb morphology and how this
22 may reflect differences in manipulative behaviors in these two species. Here, we provide a novel
23 perspective on this debate through a 3D geometric morphometric analysis of shape covariation
24 between the trapezial and proximal first metacarpal articular surfaces of Neanderthals (*Homo*
25 *neanderthalensis*) in comparison to early and recent humans (*Homo sapiens*). Results show a
26 distinct pattern of shape covariation in Neanderthals, consistent with more extended and
27 adducted thumb postures that may reflect habitual use of grips commonly used for hafted tools.
28 Both Neanderthals and recent humans demonstrate high intraspecific variation in shape
29 covariation. This intraspecific variation is likely the result of genetic and/or developmental
30 differences, but may also reflect, in part, differing functional requirements imposed by the use of
31 varied tool-kits. These results underscore the importance of holistic joint shape analysis for
32 understanding the functional capabilities and evolution of the modern human thumb.

33 **Introduction**

34 Variation in fossil hominin hand morphology has played a key role in the interpretation
35 of how human manipulative abilities evolved [1-5]. There has been a particular focus on the
36 thumb and the radial wrist bones, as their morphology is thought to reflect interspecific
37 differences in the frequency and complexity of tool-related behaviors [2-15]. To better
38 understand the morphological transitions that lead to the anatomically modern human (*Homo*
39 *sapiens*) hand, many studies have analyzed how the human hand differs from that of
40 Neanderthals (*Homo neanderthalensis*) [4, 11-13, 16]. Morpho-functional interpretations
41 generally agree that both modern humans and Neanderthals were likely capable of the same
42 dexterity [4, 17]. However, based on their robust phalanges, broader distal phalanges and joint
43 configurations (see below), Neanderthal hands appear better adapted for forceful power grips
44 that are considered important for the effective use of some tools, such as hafted Mousterian
45 spears and scrapers [11, 13, 17-20]. However, a recent study by Karakostis and colleagues [16]
46 argued that Neanderthal hand muscle attachment areas (entheses) are similar to those of recent
47 humans that used precision grips throughout their professional life (e.g., tailors, shoemakers,
48 joiners), suggesting the use of habitual precision, rather than power, grasping in Neanderthals.
49 To better understand how Neanderthal and modern human thumb function may have varied, it is
50 important to evaluate how the joints of the trapezium (including the first and second metacarpals,
51 trapezoid and scaphoid facets) and the proximal joint of the first metacarpal (Mc1) correspond to
52 each other. These joints are the primary osteological determinant of thumb mobility [21] and we
53 refer to all of these joints together as the trapeziometacarpal (TMc) complex. Building on
54 previous work [4, 11-12, 18], we investigate the morpho-functional characteristics of the thumb
55 in Neanderthals, as well as early and recent modern humans, through a three-dimensional (3D)

56 geometric morphometric (GM) analysis [22] of shape covariation between the joints of the TMc
57 complex. This analysis of the entire trapeziometacarpal anatomical region is a more holistic
58 approach than in previous studies that have only focused on the trapezium-Mc1 articulation or
59 these bones in isolation [7-8, 10, 12, 14-15].

60 The morphological configuration of the thumb and radial side of the wrist is broadly
61 similar between the modern human and Neanderthal hands [5]. Compared with other great apes,
62 as well as some fossil hominins [23-24], modern humans and Neanderthals both show a broad,
63 relatively flat trapezium-metacarpal joint, including a palmarly-expanded trapezoid and an
64 extensive trapezium-scaphoid joint. Together, these features have been interpreted as
65 biomechanically advantageous for high loading from the thumb during frequent tool use and
66 production [3, 6-8]. However, the biomechanical implications of subtle morphological
67 differences between the TMc complexes of Neanderthals and modern humans have been less
68 clear [18]. Compared with modern humans, Neanderthals have a larger trapezium-Mc1 joint area
69 that is dorsopalmarly flatter [10, 12-13, 18]. This joint morphology has been interpreted as less
70 congruent and, therefore, possessing greater mobility that, in turn, would require greater
71 muscular force, or ligamentous support, than that of modern humans to achieve the same level of
72 joint stability [18]. Combined with other features of the hand, including robust phalanges, rugose
73 musculotendinous attachment sites, more parasagittally-oriented capitate-second metacarpal
74 facets, reduced third metacarpal styloid processes, radioulnarly flat fifth metacarpal bases, and
75 large, projecting carpal tubercles, this trapezium-Mc1 joint morphology has been interpreted as
76 evidence that power grips may have been more frequently used in the Neanderthal manipulative
77 repertoire than that of early modern humans [12, 19-20]. However, there is considerable
78 intraspecific variation in Neanderthal trapezium-Mc1 joint shape, and some specimens (e.g., La

79 Ferrassie 1) are difficult to distinguish from recent humans. Together with notable morphological
80 variation in the TMc complex morphology overall (e.g. Kebara 2) [19-20], this morphology
81 makes characterizing a ‘typical’ Neanderthal morphology challenging. An analysis of shape
82 covariation across the TMc complex may shed light on the subtle functional consequences of this
83 morphological variation within different Neanderthal individuals. Neanderthals had tool-kits
84 comprising diverse lithic types and sizes [25] that would require different hand grips to use [26],
85 but Neanderthals may also have practiced varied grasping behaviours due to differences in
86 geography [27], activities, time [28] and/or sex [29], all of which could be reflected within hand
87 morphology.

88 The shape variation found in previous studies in Neanderthals and modern humans [7-8,
89 10-15, 20], may be the result of multiple of factors, including genetics, evolutionary history,
90 hormones, sex, geography, and common developmental origin [30]. However, since bone
91 (re)models throughout life, it may also reflect, in part, variation in habitual use of the hand
92 during ontogeny. Although joint shape is commonly considered to be more genetically and
93 functionally constrained than other aspects of bone shape (e.g., shaft external or internal bone
94 structure) [31-32], within the hand, and in particular the small bones of the carpus, the
95 constraints on joint shape are less clear. The trapezium does not complete ossification in humans
96 until 9-10 years of age [33], while the base of the Mc1 does not completely fuse until 14-16.5
97 years of age. The trapezium develops within the hand surrounded by, and incurring load from,
98 five other bones. Further, both the trapezium and Mc1 will incur substantial muscular force,
99 directly or indirectly, from the intrinsic and extrinsic muscles of the radial side of the hand.
100 Strong and complex manipulative abilities are observed in modern humans before the end of the
101 total ossification of their carpal bones and the Mc1 [34]. Furthermore, Neanderthals are thought

102 to have made and used tools as juveniles [35]. As such, it is possible that frequent loading from
103 habitual manual activities during development and adulthood may subtly affect how the bones of
104 the TMc complex articulate with each other as their joint surfaces ossify. In this study, we assess
105 the morphological variation in the associated trapezia and first metacarpals of five Neanderthal
106 individuals (La Ferrassie 1 and 2, Le Régourdou 1, Kebara 2, Shanidar 4) and compare them to
107 five early modern humans (Qafzeh 9, Ohalo 2, Abri Pataud 26227 (AP-P1), Abri Pataud 26230
108 (AP-P3), Dame du Cavillon) as well as a broad sample of recent humans (Table 1, Fig. 1, and
109 Supplementary Information Table S1). Through a 3D GM approach using sliding semi-
110 landmarks [22], we analyze shape covariation across the joints of the TMc complex. While
111 previous analyses of 3D shape variation in the isolated trapezium, Mc1 or trapezoid have
112 revealed interspecific differences across hominins species [7-8, 14-15], the movement and
113 loading of the thumb is largely delimited by the interaction of the bones of the TMc complex
114 together. By analyzing shape covariation, we quantify, for the first time, how joint shapes vary
115 together across the trapezium and Mc1. That is, we explore how change in articular shape of
116 each articular facet is reflected in the shape of the remaining TMc complex facets. Just as the
117 functional interaction of the trapezium-Mc1 joint is the primary osteological determinant of thumb
118 mobility [21], we assume that all the functional joints of the two bones covary to some extent.
119 We aim to test the null hypothesis that joints of the TMc complex covary in the same way (i.e.,
120 same shape and relative orientations of the TMc joints) within Neanderthals, early modern and
121 recent modern humans, respectively. By quantifying the shape of all the joints of the TMc
122 complex together, we can holistically characterize its morphology in each species. This
123 characterization can elucidate which specific thumb movements and, by extension, which grip(s)
124 would have been favored by this morphology; that is, would each TMc complex be better suited

125 to precision (i.e., involvement of the pad of the fingers in opposition to the pad of the thumb) or
126 power grips (i.e., involvement of the palm of the hand).

127 Following previous studies of external and internal bone morphology, we predict that
128 humans will demonstrate a TMc complex morphology that favors thumb abduction [36-38] as
129 this movement, combined with axial pronation and flexion of the thumb, comprises thumb
130 opposition. An opposed thumb is habitually used by modern humans in strong precision “pad-to-
131 pad” grips [39], in which the thumb pad opposes the index finger pad, and the joints of the TMc
132 complex are oriented obliquely relative to the transverse plane. In contrast, we predict that
133 Neanderthals will show a morphology of the TMc complex favoring extended thumb
134 movements, associated with axially/parasagittally-oriented joints. This morphology is consistent
135 with habitual use of a transverse power squeeze grip, in which an object is held transversely
136 across the palm of the hand with strongly flexed fingers and the thumb is extended and adducted
137 to brace against the object [40]. This grip was used by humans when using hafted tools to scrape
138 wood in an experimental setting [41]. Thus, by studying the manner of shape covariation within
139 the TMc complex, we can infer the degree to which Neanderthals and modern humans shared
140 similar biomechanical advantages for high loading from a thumb held in different postures
141 during varied manipulative or tool-related behaviours [3, 6, 7-8].

142

143 **Results**

144 A multivariate regression of shape on centroid size tested for the size effects on
145 morphology. No allometric effect was found for either the trapezium or Mc1 indicating that the
146 size of bone alone cannot explain shape differences found between individuals and taxa
147 (Supplementary Information Table S2).

148 The 2B-PLS analysis showed that patterns of shape covariation between the joints of
149 trapezium and the Mc1 were significantly different between Neanderthals and recent humans
150 (Fig. 2A, C, and Table 2). Early modern humans showed no significant shape covariation
151 differences with either recent humans or Neanderthals (Table 2), and were always placed
152 intermediately in the PLS axes, presenting a shape covariation pattern between recent humans
153 and Neanderthals (Fig. 2). The 2B-PLS analysis revealed substantial intraspecific variation in
154 shape covariation for both recent humans and Neanderthals (Fig. 2).

155 The plot of the first PLS axis (PLS1) (33% of total covariance) separated Neanderthals
156 (positive values on PLS1 axis) from recent humans (negative values on PLS1 axis; Table 2), a
157 difference that was statistically significant. However, the Le Régourdou 1 Neanderthal fell
158 within the recent human morphological range of variation (Fig. 2A), and Qafzeh 9, the oldest
159 early modern human in our sample, fell within the Neanderthal morphological range of variation
160 (Fig. 2A). The range of PLS1 axis values reflected both differences in shape and relative joint
161 orientation, and these features did not vary in the same way within Neanderthals and within
162 modern humans. In recent modern humans (negative values on PLS1 axis), the joint surfaces of
163 both the trapezium and Mc1 were generally more curved and more obliquely-oriented relative to
164 the transverse plane, and the trapezium-Mc1 joint showed an extension of the radial border that
165 would be advantageous for more abducted, rather than adducted, thumb movements (Fig. 2A,
166 Fig. 3). In contrast, Neanderthals (positive values on PLS1 axis) showed joint surfaces of both
167 the trapezium and the Mc1 that were flatter and oriented closer to the transverse plane, with the
168 exception of the trapezium-Mc2 joint, which was oriented roughly parasagittally (Fig. 2A, Fig. 3).
169 The anteroposterior-flat and radioulnarly-convex shape of the Neanderthal trapezium-Mc1 joint is
170 radioulnarly wider and so more advantageous for a greater range of radio-ulnar, as well as

171 extended, thumb movements compared to recent modern humans (Fig. 2A, Fig. 3). Two
172 Neanderthal individuals fell out at opposite extremes (Fig. 2A); Le Régourdou 1 was the only
173 Neanderthal to fall within the modern human range of variation, while Kebara 2 was at the
174 extreme positive side of the axis, being most distinct from modern human shape covariation (Fig.
175 4).

176 The plot of PLS2 axis (28% of total covariance) revealed substantial overlap in shape
177 covariation between species, with all Neanderthals and all but two early modern human
178 individuals (Qafzeh 9 and AP-P3) falling within the range of variation seen in recent humans
179 (Fig. 2B). For individuals on the negative side of the PLS2 axis (including Neanderthals
180 specimens, La Ferrassie 1 and 2), the shape covariation was characterized by a posterolaterally
181 extended articular surface of the trapezium-Mc1 joint, which could be more advantageous for
182 extended and adducted thumb movements. The trapezium joints were more obliquely-oriented
183 relative to the transverse plane, apart from the trapezium-Mc2 joint, which was oriented roughly
184 orthogonal to the transverse plane (Fig. 2B, Fig. 3). In contrast, individuals on the positive side
185 of the PLS2 axis (including Neanderthal specimens Kebara 2, Le Régourdou 1, Shanidar 4)
186 showed a posteriorly extended surface of the trapezium-Mc1 joint that could be advantageous
187 for extended and abducted thumb movements, and with joints more transversally-oriented (Fig.
188 2B and Fig. 3).

189 The plot of the PLS3 axis (14% of total covariance) showed overlap between taxa but
190 Neanderthals (positive values on PLS3 axis) were significantly different from recent humans
191 (negative values on PLS3 axis). Kebara 2 fell near the centre of the recent human distribution
192 and two recent humans fell within the Neanderthal distribution (Fig. 2C, Table 2). The PLS3 axis
193 showed high intraspecific variation in shape covariation of recent humans but also distinguished

194 western European Neanderthals (extreme positive values on PLS3 axis) from Near Eastern
195 Neanderthals, which were closer to the modern human distribution (Fig. 2C). The morphologies
196 reflected by PLS3 axis for western European Neanderthals and one recent human were quite
197 similar to those of the PLS2 axis: a flat and broad trapezium-Mc1 joint associated with an
198 anteroposteriorly thin ulnar portion of the trapezium-trapezoid joint, and joints more obliquely-
199 oriented relative to the transverse plane, apart from the trapezium-Mc2 joint, which was oriented
200 roughly orthogonal to the transverse plane (Fig. 2C). The trapezium-Mc1 joint showed extension
201 of the radial border that could be advantageous for abducted and extended movements of the
202 thumb (Fig. 2C, Fig.3). In contrast, the recent human specimens on the negative side of this axis
203 showed anteroposteriorly broad joints, a more anteroposteriorly-curved trapezium-Mc1 joint
204 obliquely-oriented relative to the transverse plane, a larger trapezium-trapezoid joint, and more
205 transversely-oriented trapezium joints (Fig. 2C). Furthermore, the shape of the trapezium-Mc1 joint
206 showed extension of the radial and ulnar border that would be advantageous for a greater range
207 of radioulnar movements of the thumb (Fig. 2C, Fig.3).

208

209 **Discussion**

210 We found significantly different patterns of shape covariation in Neanderthals and
211 modern humans on PLS axes that cumulatively comprise half of the total shape covariation (Fig.
212 2 A, C). These patterns demonstrate different shapes and relative joint orientations that suggest
213 contrasting patterns of habitual thumb movements and force transmission in Neanderthals and
214 modern humans.

215 The shape covariation patterns in early and recent modern humans support previous
216 studies; most joints are more obliquely-oriented relative to the transverse plane, which suggests a

217 biomechanical adaptation to the transmission of oblique force from the radial side of the hand [3,
218 6-8]. Thus, the general shape covariation pattern of the recent modern human TMc complex
219 would be advantageous for abducted thumb movements that would obliquely load the large
220 trapezial-trapezoid articular surface [6]. This human pattern is therefore also consistent with the
221 habitual use of forceful precision grips involving abduction of the thumb, such as during forceful
222 “pad-to-pad” precision grips [3, 39-40]. Interestingly, around half of modern humans have a
223 slightly different TMc complex morphology that could be more advantageous for adducted
224 thumb movements (Fig. 2 B, Fig. 3), which are used during oblique power squeeze gripping
225 (defined as an object held diagonally across the palm of the hand, clenched by flexed fingers and
226 buttressed by adducted thumb) [40], and powerful “pad-to-side” grip (handling of objects by the
227 thumb pad and the side of the index finger; 3). These results are consistent with that of
228 Karakostis and colleagues [16] that found different hand bone enthesal patterns between
229 individuals known to engage in heavy manual work compared to precision workers. Thus, the
230 variation we found among modern humans may reflect different habitual manual activities across
231 our recent human sample.

232 In contrast to modern humans, most of the Neanderthals – though their intraspecific
233 variation is high – possess trapezial carpometacarpal joints that are more parallel to the
234 transverse plane while the trapezial-Mc2 joint is oriented parasagittally. Together, the joint
235 orientations of the Neanderthal TMc complex suggest a biomechanical adaptation to the
236 transmission of axial/parasagittal (i.e., parallel to the long axis of Mc1) force from the thumb
237 across the radial side of the hand [3, 7-8, 14]. The general shape covariation pattern would
238 facilitate an extended and adducted thumb during opposition of the thumb with the other fingers
239 in Neanderthals. This thumb posture suggests the habitual use of powerful transverse power

240 squeeze grips, like those used to grip hafted tools [12, 41]. The large axial loads generated by
241 this grip could be distributed across the joint surfaces provided by the more orthogonal/axial
242 orientation of the trapezial-Mc2 and trapezial-scaphoid joints in Neanderthals. The relatively
243 smaller trapezial-trapezoid joint surface on the Neanderthal trapezium also suggests that a greater
244 proportion of Mc1 load would be transmitted to the trapezium and the scaphoid. Conversely, the
245 large size of this joint in humans favours more force transmission across the anterior trapezoid to
246 the capitate during the power grip [6]. This pattern of shape covariation of Neanderthal TMc
247 morphology could have mechanically disadvantaged thumb abduction during grips such as
248 powerful “pad-to-pad” grip involving strong abduction, flexion and rotation of the thumb [3]
249 since more force would likely be transmitted through the smaller trapezial-trapezoid joint (Fig. 3-
250 4). However, we do not mean to suggest Neanderthals were incapable of the abducted hand
251 postures, but merely that their morphology made this less mechanically advantageous than in
252 modern humans. Indeed, Karakostis and colleagues [16] have shown that the same Neanderthals
253 specimens, apart Le Régourdou 1, possess an enthesal pattern consistent with this type of
254 precision grasping.

255 We cannot directly associate Neanderthal hand morphology with the specific lithic
256 assemblages as we do not know which individuals, or species in some cases, made or used these
257 artefacts. However, we know that late *Homo* species produced stone tools in this temporal and
258 geographical context. The different lithic technology and typology found, can inform us about
259 behavioural traditions occupying the region. Kebara 2 and Le Régourdou 1 showed the most
260 extreme differences in shape covariation among our Neanderthal sample (Fig. 2A, C). The
261 morphology of the TMc complex of Kebara 2 suggests mechanical advantage when loading a
262 more abducted thumb (Fig. 4), in agreement with current trabecular evidence [42], suggesting a

263 morphology favoring the use of “pad-to-pad” grips. This result is consistent with that of
264 Karakostis and colleagues [16] in which the Kebara 2 enthesal morphology suggests habitual
265 use of precision grips. Also, the Kebara 2 trapezium has a narrow and transversely-oriented Mc2
266 facet that brings it closer to the ulnar portion of the Mc1 facet. This particular morphology could
267 be disadvantageous to transmitting high load from the Mc2 to the trapezium during the adducted
268 thumb posture of powerful “pad-to-side” grips typically used with short and small flakes [26].
269 This is consistent with the Mousterian technology at Kebara where there are few retouched
270 flakes [27] and a greater abundance of longer flakes compared to Le Régourdou 1. Le Régourdou
271 1 is the only Neanderthal in our sample associated with Quina lithics, an industry with a high
272 proportion of scrapers [43], and smaller tools than those associated with Kebara 2. Le Régourdou
273 1 has a morphology advantageous for loading an adducted thumb, that this is used in a “pad-to-
274 side” grips used on scrapers. Therefore though it is only circumstantial evidence, it is interesting
275 that the two most disparate fossil Neanderthals in our sample appear to have morphologies that
276 would be mechanically advantageous for the grips associated with the type of tools frequently
277 found in techno complexes evidenced at the same site where these morphologies were found.

278 We found no significant differences in shape covariation between early modern humans
279 and Neanderthals, although sample sizes were small. The range of morphological variation found
280 in early modern humans was intermediate between that of recent modern humans and
281 Neanderthals. Interestingly, the closest early modern human to Neanderthals was Qafzeh 9, the
282 oldest individual in our sample at 95 ka [44] (Fig. 2A). Qafzeh hominins (found in Israel) and
283 Near Eastern Neanderthals existed during the same time period and both were found in
284 association with Middle Paleolithic industry, the Mousterian lithic technologies [44]. However,
285 previous analyses of the Qafzeh 9 hand morphology have interpreted this individual has likely

286 using finer and precise finger movements more often than Neanderthals [11], suggesting the use
287 of similar technology but with different manual abilities. The other early modern humans in our
288 sample, all younger than Qafzeh 9, were within the recent human range of morphological
289 variation, and are associated with a different technological context (i.e., including more blade
290 tools) than Qafzeh 9 [45-47].

291 To conclude, our results demonstrate that modern human and Neanderthal TMc complex
292 morphology does not covary in the same manner. Neanderthals possess trapezial
293 carpometacarpal joints that are flatter and more transversely oriented with extension of their
294 radial and ulnar borders, a trapezial-Mc2 joint that is orthogonal relative to the transverse plane,
295 and a small trapezial-trapezoid joint surface. All these features suggest transmission of axial
296 force from the thumb across the radial side of the hand, favoring more extended and adducted thumb
297 movements during powerful opposition of the thumb with the other fingers. In support of shape
298 covariation reflecting habitual hand use, our results show that both Levantine and European
299 Neanderthals in our sample possess a thumb morphology suited for use in transverse power
300 squeeze grips on hafted tools. Although it should be noted that Shea [27] suggested that
301 Levantine Mousterians could have more frequently utilized hafted artefacts (e.g., spear points)
302 than European Mousterians. The morphology of Neanderthal hands analyzed here, would better
303 facilitate a type of force transmission through the wrist bones associated with the use hafted
304 tools, than that associated with non-hafted tools such as small flakes that require the use of “pad-
305 to-side” or “pad-to-pad” grips [3]. Comparing fossil morphology with contemporaneous lithic
306 industries can help us to infer past behavior and better understand the evolution of modern
307 human manipulative abilities.

308

309 **Materials and Methods**

310 **Materials**

311 The sample of recent modern humans comprises 40 adults with no sign of external
312 pathology from a broad geographic range (North America, Europe, Africa, North Asia;
313 Supplementary Information Table S1). As the fossil sample of early modern humans and
314 Neanderthals includes individuals of both or unknown sex and bones from both right and left
315 sides, our comparative human sample incorporated the same range of variation: 22 males, 15
316 females, three with no sex identified, and 25 bones (paired trapezium-Mc1) from the right side
317 and 15 from the left. Original fossils specimens were used for La Ferrassie 1 and 2, and we used
318 high-quality resin casts of the original specimens for Kebara 2, Le Régourdou 1 and Shanidar 4
319 (see Table 1 for additional information about these fossils). All the data were analyzed together
320 as neither sex nor side significantly affected shape covariation (Table 2).

321

322 **3D scanning**

323 Shape covariation of the Mc1 and trapezium were explored using 3D digital surface
324 models created from scan data collected via different methods including micro-computed
325 tomography (μ CT), laser scanning (LS), and photogrammetry (P) (Supplementary Information
326 Table S1). The μ CT scans of the samples were obtained as in Stephens et al. [37]. The 3D
327 models from μ CT scans were constructed from TIFF data using Avizo 6.3 (FEI Visualization
328 Sciences Group, Hillsboro, USA) software. The LS scans were obtained with a NextEngine laser
329 scanner using a resolution of 28,000 points per square centimeter. Twelve scans were taken at
330 different positions on both side of the bone and then merged using the ScanStudio HD PRO
331 software. P scans were obtained using a Nikon D5100 DSLR camera with a resolution of 24

332 megapixels with a focal length was fixed to 55 mm (Objectif AF-S DX NIKKOR 18–55 mm VR
333 II) for all pictures. Fifty pictures were captured on both sides of the bone from different
334 viewpoints. For the reconstruction of the 3D models we used the Agisoft PhotoScan software
335 (2014 Agisoft LLC) obtaining a pixel size of 0.00490961 x 0.00490961 mm. Final meshes were
336 created using the Agisoft PhotoScan software with high values of 180000 optimal number of
337 polygons. Scanning artifacts or anomalies in the polygonal mesh, from all the μ Ct and LS
338 methods, were corrected using Geomagic Wrap 2015 (3D Systems, Inc) software. All imaging
339 data were analyzed together as there was no significant effect of acquisition method on shape
340 variation across species for either the trapezium joints or the McI joint (MANOVA tests, $p >$
341 0.05). As we used right and left bones, we mirrored the left bones using Geomagic Wrap 2015
342 software, in order to ensure homologous comparisons.

343

344 **3D geometric morphometrics**

345 Because of the shape complexity of wrist bones and the challenges of identifying
346 homologous anatomical landmarks (i.e., point locations that are biologically homologous
347 between species) on irregularly-shaped joint surfaces, we quantified shape variation using a GM
348 approach with both 3D anatomical landmarks and 3D sliding semi-landmarks on curves and
349 surfaces [22]. 3D sliding semi-landmarks allow for the accurate description of anatomical zones
350 of high biological interest (like joint surfaces) even if the lack clear anatomical landmarks. 3D
351 sliding semi-landmarks on curves and surfaces correspond to Type III landmarks, in the typology
352 of Bookstein [48], which are geometric points dependent on the location of other landmarks.
353 Consequently, these semi-landmarks do not constitute absolute anatomical reference points and

354 so additional operations must be performed to be able to use them for shape comparisons (see
355 description of sliding procedure below).

356 Initially we created a landmark template for each bone by manually placing 3D
357 anatomical landmarks and 3D sliding semi-landmarks on curves and surfaces on one specimen
358 (Fig. 1, and Supplementary Information Figure S1 and Table S3), using Landmark [49]. Type II
359 3D anatomical landmarks [48] (five for the trapezium and two for the Mc1) were defined as
360 points of maximum curvature at the limits of joint surfaces on each specimen (described in
361 Supplementary Information Table S3). 3D curves were defined at the margins of articular
362 surfaces and were bordered by anatomical landmarks as recommended by Gunz *et al.* [50]. The
363 curves were digitized with a high density of points (62-142 points per curve depending on the
364 curve length) and then sub-sampled to the number listed in supplementary information
365 (Supplementary Information Table S3). A high density of 3D sliding semi-landmarks were
366 manually placed at approximately equidistant intervals on the entire surface of each bone (147
367 for all the joints of the trapezium and 41 for the proximal joint of first metacarpal). The template
368 used for the trapezium contains a total of 294 points including five anatomical landmarks, 142
369 semi-landmarks sliding on curves, and 147 semi-landmarks sliding on surfaces (Fig. 1 and
370 Supplementary Information Figure S1). The template used for the Mc1 contains a total of 105
371 points including two anatomical landmarks, 62 semi-landmarks sliding on curves and 41 semi-
372 landmarks sliding on surfaces (Fig. 1 and Supplementary Information Figure S1). To assess the
373 repeatability of the manual placement of the anatomical landmarks and curves for the trapezium
374 joints and the Mc1 proximal joint, we landmarked three similar Neanderthal specimens (same
375 sex, side and bone) ten times. Following a procrustes procedure, the first two principle
376 components of principle components analyses (PCA) revealed that shape variation among the

377 repetitions on each specimen tested was much lower than inter-specimen shape variation
378 (Supplementary Information Figure S2). Anatomical landmarks and curves for both bones were
379 thus considered repeatable.

380 The landmarking procedure continued by manually placing anatomical landmarks and
381 sliding semi-landmarks on curves on all the specimens, as was done for the templates. Next,
382 surface sliding semi-landmarks were projected onto each of the bone's surface [20] using the
383 function "placePatch" in the "Morpho" package [51] in R [52]. Then, the function "relaxLM" in
384 the "Morpho" package was used to relax landmark configuration onto each surface of both bones
385 (Mc1 and trapezium) by minimizing bending energy [51]. A sliding procedure was then
386 performed using the function "slider3d" in the "Morpho" package by minimizing the Procrustes
387 distance (see for details [20, 50]). After sliding, a general Procrustes analysis [53] was performed
388 for each specimen with the function "procSym" in the "Morpho" package, controlling for
389 differences in size, position and orientation of the bones between specimens. After this step, all
390 landmarks and sliding semi-landmarks can be analyzed as Procrustes 3D landmarks. Finally, the
391 size of each specimen, and for each bone separately, was quantified as centroid size (i.e. square
392 root of the summed of squared distances between each landmark and the center of gravity) [48]
393 in order to test for potentially confounding allometric effects on the study (see below).

394

395 **Statistical Analysis**

396 To reduce our large data set for statistical analysis, principle components analyses (PCA)
397 were performed using on the Procrustes landmark sets using the function "procSym" in "Morpho"
398 package [51] on R. To investigate patterns of shape covariation between the trapezium and the
399 Mc1, Two-Block Partial Least-Squares (2B-PLS) analyses [54] were performed on the principle

400 component (PC) scores of each specimen with the “pls2B” function in the Morpho package [51].
401 By calculating a covariance matrix, 2B-PLS identifies axes that describe common shape
402 variation between the two bones (PLS axes) while reducing dimensionality of the dataset. To
403 visualize the co-varying morphology changes associated with the extremes of each PLS axes, the
404 “plsCoVar” function in “Morpho” was used [51]. To test for differences between the mean shape
405 covariation across the three groups (early modern humans, recent humans and Neanderthals)
406 omnibus one-way permutational MANOVAs (1000 permutations) were run on the Euclidean
407 distance matrices of the first three PLS axes scores (i.e. those that described more than 10% of
408 the total covariance). If these omnibus tests were significant, pairwise versions of the same test
409 were run to understand which groups were significantly different from each other. These
410 permutational MANOVA’s were run using the “Vegan” [55] and “RVAideMemoire” [56]
411 packages with the “adonis” and “pairwise.perm.manova” functions, respectively. Before we
412 performed these tests, a test of multivariate homogeneity of variance was performed on the
413 Euclidean distance matrix that describes the PLS scores (function “betadisper” in the “Vegan”
414 package) and a Bonferroni correction was applied to all pairwise results, to ensure valid
415 comparisons (Table 2). Allometric effects on the results were tested using the function
416 “procD.lm” in the “geomorph” package [57].

417

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560

561 **Acknowledgments**

562 We are grateful to the following institutions and researchers for providing us with access to fossil
563 and modern specimens and/or 3D data: National Museum of Natural History in Paris (D.
564 Grimaud-Hervé, M. Friess, V. Laborde, L. Huet and A. Fort), the University of Florence (J.
565 Moggi-Cecchi and S. Bortoluzzi), the Johann-Friedrich-Blumenbach-Institut für Zoologie und
566 Anthropologie der Georg-August-Universität Göttingen (B. Großkopf), Tel Aviv University (I.
567 Herskovitz), University of Haifa (D. Nadel), Université Bordeaux (B. Vandermeersch), Natural
568 History Museum, Vienna (M. Teschler-Nicola and R. Muehl), Max Planck Institute for

569 Evolutionary Anthropology (J-J Hublin). We thanks M. Tocheri for help with analyses and
570 sharing surface scans of Shanidar 4 and Le Régoudou 1. This research was supported by a
571 Fyssen Foundation Research Fellowship to A.B., by a SU emergence funding “HUMDEXT”
572 (grant no. 19SB207U7179) to E.P., the French Ministry of Research, Service regional de
573 l'Archéologie Auvergne-Rhône-Alpe to M.-H.M., the H2020 European Research Council
574 Consolidator Grant (No. 819960) to C.J.D. and T.L.K. and the Dept. of Human Evolution, Max
575 Planck Institute for Evolutionary Anthropology to T.L.K.

576

577 **Author contributions**

578 A.B., M.-H. M., E.P., and R.C. conceived of and designed the study. A.B. collected and analyzed
579 the data. C.J.D. and R.C. contributed analysis tools. T.L.K. and M.-H. M. contributed data and
580 theoretical context. C.J.D. and T.L.K. contributed substantially to the interpretation of data. A.B.
581 wrote the manuscript with input from all authors.

582

583 **Competing interests**

584 The authors declare that they have no competing interests.

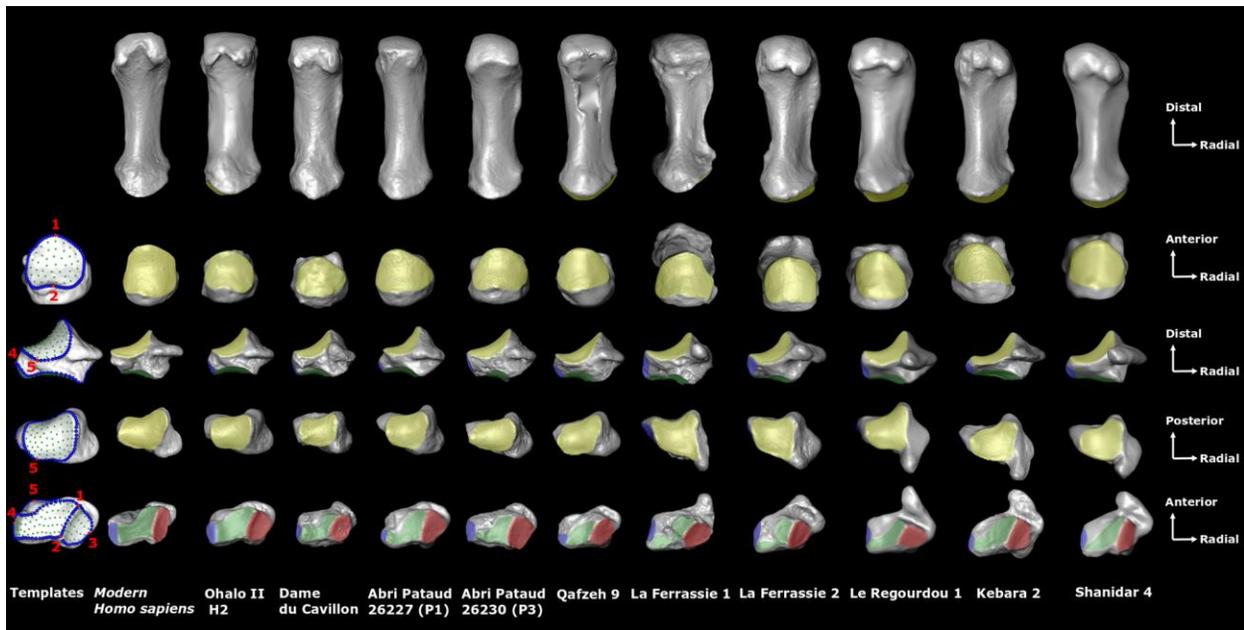
585

586 **Data and materials availability**

587 All data needed to evaluate the conclusions in the paper are present in the paper and/or the
588 Supplementary Information. Additional data related to this paper may be requested from the
589 authors.

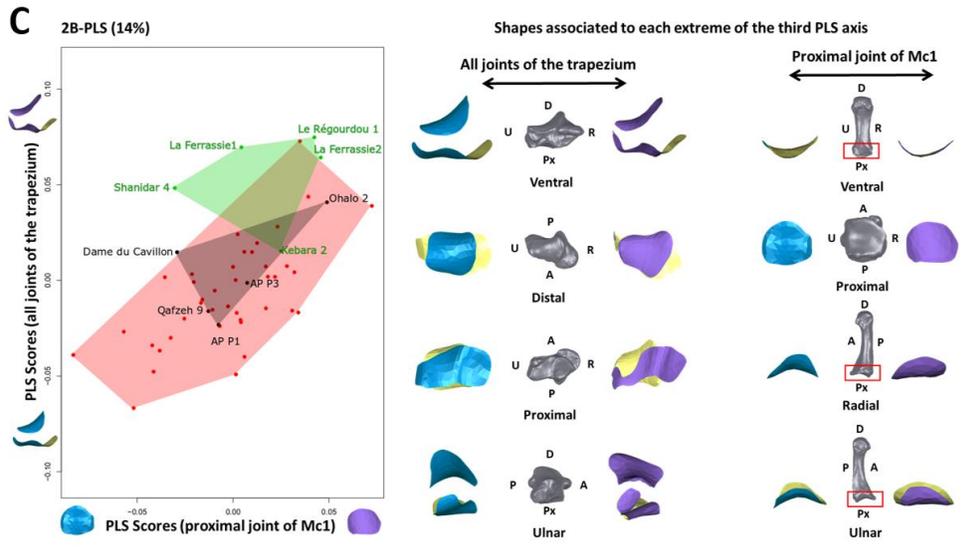
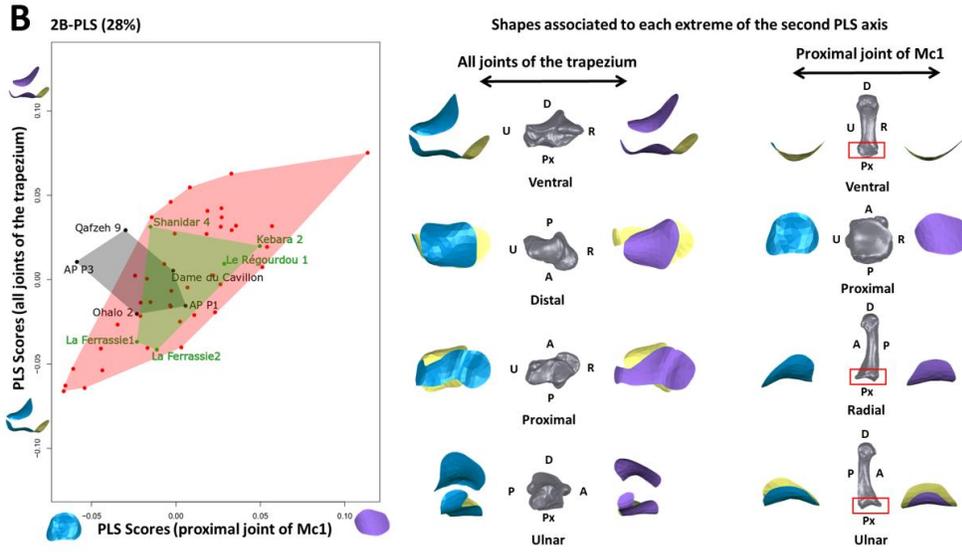
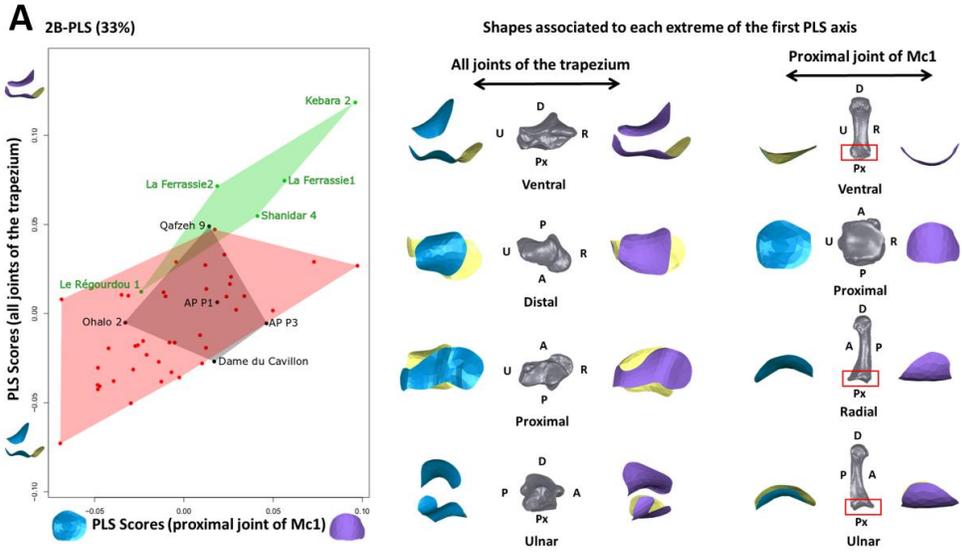
590 **Figure legends**

591

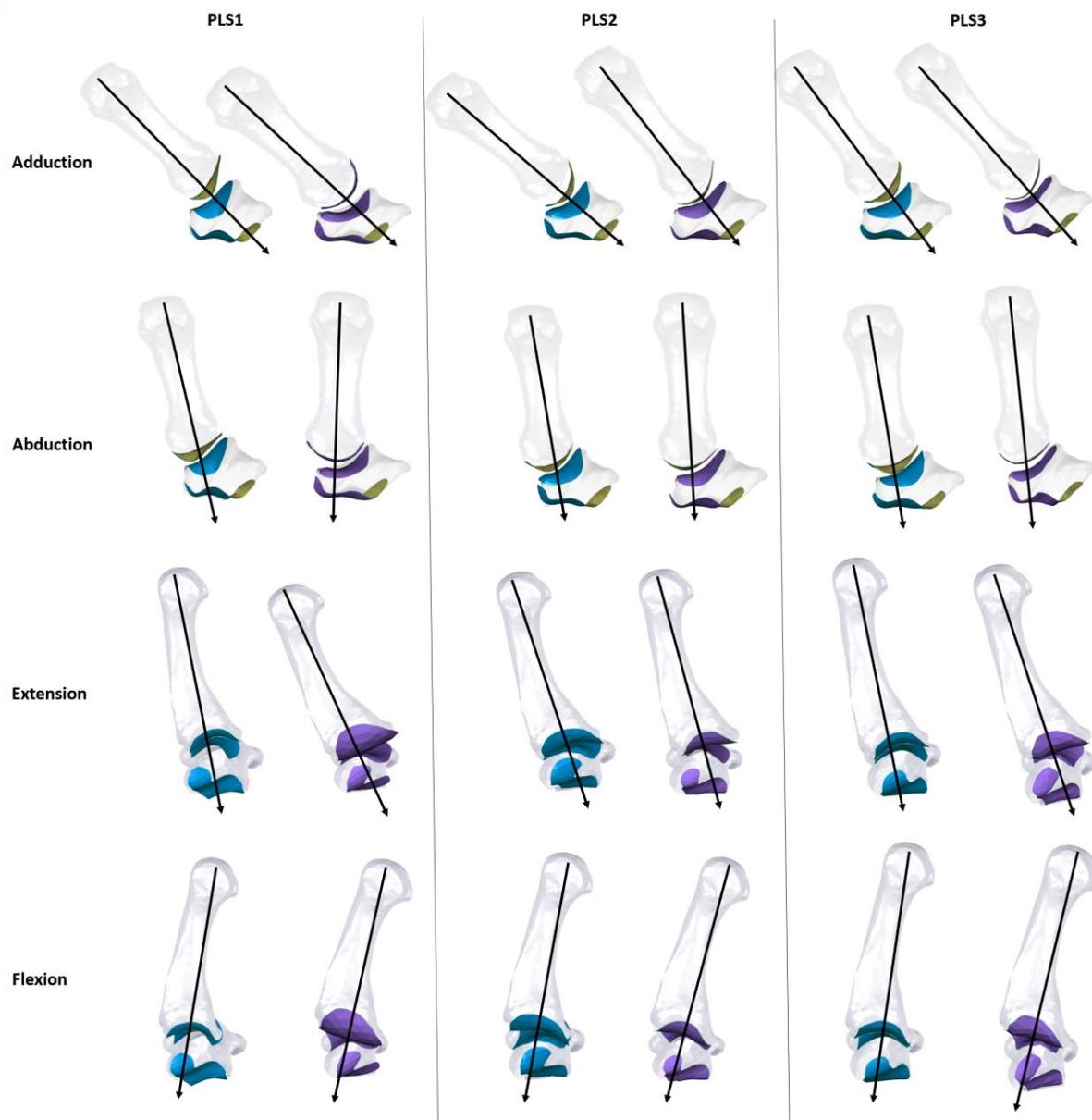


592

593 **Figure 1.** Joint shape comparison of the Mc1 (top 1st row, palmar view; top 2nd row, proximal
594 view) and trapezium (middle row, palmar view; 1st row from bottom, proximal view; 2nd row
595 from bottom, distal view) in modern human (2nd from left) and five early humans (3rd to 7th from
596 the left) and five Neanderthals (1st to 5th from right). Key colors: yellow, trapezium-Mc1 joint;
597 blue, 2nd metacarpal joint; green, trapezoid joint; red, scaphoid joint. The first column (left)
598 represents the landmark templates used in our analyses to quantify shape covariation (see
599 Materials and Methods, and detailed in Supplementary Information Figure S1 and Table S3).
600 The illustration is not scaled, and bones from the left-hand side (Le Régourdou 1, Kebara 2,
601 Shanidar 4, Abri Pataud P1, Abri Pataud P3, Dame du Cavillon) are mirrored for fair
602 comparison.



604 **Figure 2.** 2B-PLS of shape covariation between the proximal joint of Mc1 and all joints of the
605 trapezium across taxa. **(A)** 1st PLS axis; **(B)** 2nd PLS axis; **(C)** 3rd PLS axis. Neanderthals (green),
606 early modern humans (black) and modern humans (red). The figures on the right represent the
607 shapes associated with each minimum and maximum of the shape covariation axes (in blue and
608 purple, respectively) in different anatomical views (the full bone of a random *H. sapiens*
609 individual is depicted with each surface to aid interpretation). All shapes are scaled to
610 approximately the same length. A, anterior; P, posterior; D, distal; Px, proximal; R, radial; U,
611 ulnar.

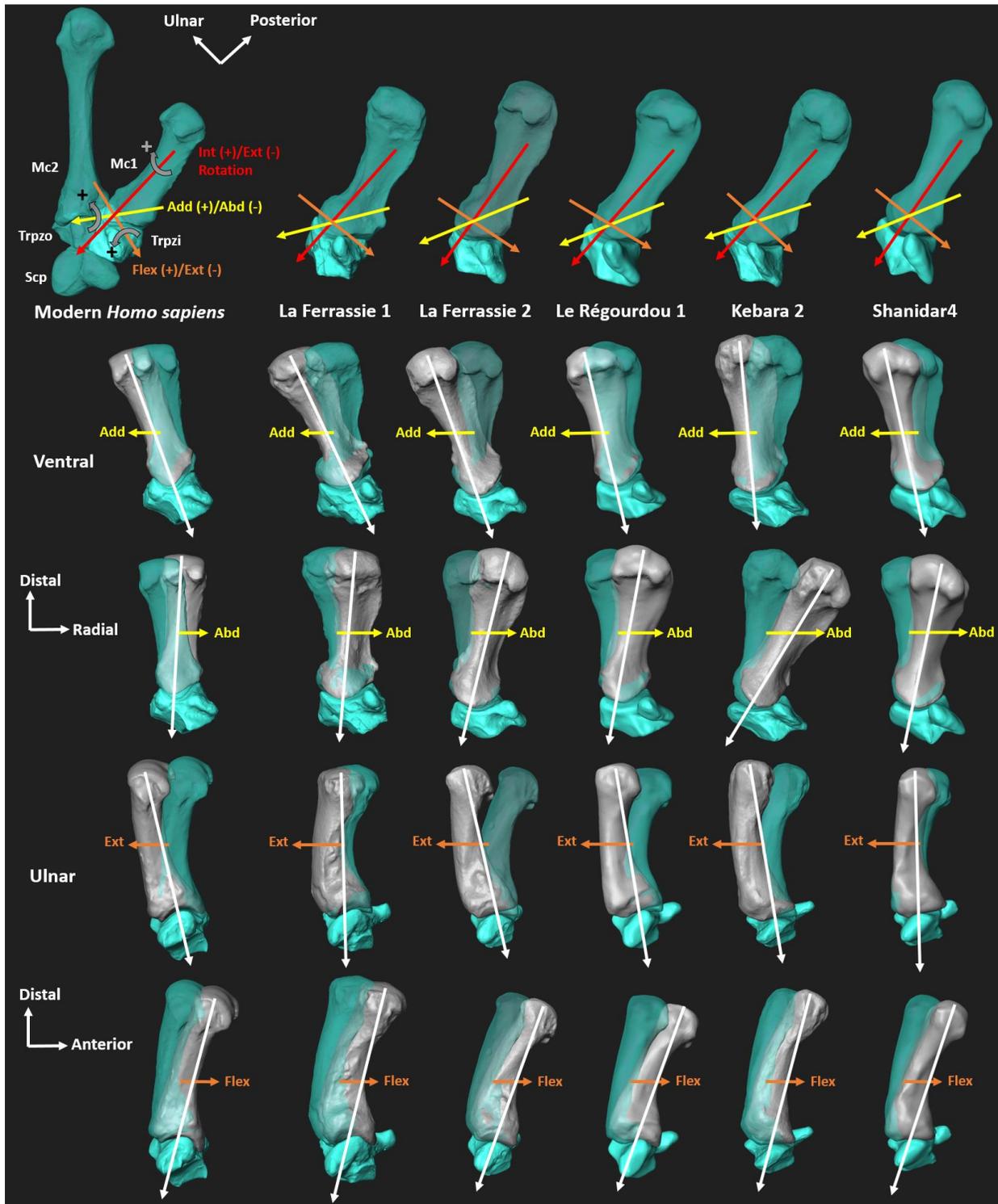


612

613 **Figure 3.** Illustration of possible movements of the TMC complex according to the shape
 614 covariations associated with each positive (purple) and negative (blue) extremes of the first—
 615 through-third PLS axes. For each shape configuration a direction of force transmission from the
 616 Mc1 to the trapezium is suggested (black arrow). The illustration is not scaled.

617

618



619

620 **Figure 4.** Illustration of potential TMC joint motion in the recent modern human (first column)

621 and for the Neanderthal sample. The modern human specimen lies at the negative extreme end of

622 the first PLS axis (Fig. 3A). This modern human specimen shows the other bones articulation

623 with the trapezium (Trpzi) and the first metacarpal (Mc1), the scaphoid (Scp), trapezoid (Trpzo)
624 and second metacarpal (Mc2). Each column corresponds to the suggested direction of trapezial-
625 Mc1 joint motion (following [61]) for one specimen. The bones are shown in neutral position
626 (grey) and in in motion (turquoise). Directions of motion are internal (Int +) and external (Ext -)
627 rotation (red), in adduction (Add +) and abduction (Abd -) (yellow), as well as flexion (Flex +)
628 and extension (Ext -) (orange). For each motion direction of force transmission from the Mc1 to
629 the trapezium is suggested based on the covarying morphology (white arrow). The trapezial-Mc1
630 joint is surrounded by a strong complex of ligaments and tendons [6, 33], which is not
631 considered in this illustration, as we don't have these soft tissues for fossils. Rotational
632 movements are not shown here. The illustration is not scaled.

633 **Tables**634 **Table 1.** The fossil sample. ^a Casts; ^b I = indeterminate sex, n.b. the sex of Le Régourdou 1 is635 still debated; ^c μ CT = micro-computed tomography, LS = laser scanning, P = photogrammetry.

Species	Specimens	Date	Sex	Location	Cultural association	Acquisition methods ^c
Neanderthals	La Ferrassie 1	Middle Paleolithic - 43-45 ka [58]	M	France	Mousterian	P
	La Ferrassie 2	Middle Paleolithic - 43-45 ka [58]	F	France	Mousterian	P
	Le Régourdou 1 ^a	Late Middle Paleolithic - 75 ka [43]	I ^b	France	Mousterian	LS
	Shanidar 4 ^a	Middle Paleolithic - 46-54 ka [59]	M	Iraq	Mousterian	LS
	Kebara 2 ^a	Middle Paleolithic - 43-50 ka [60]	M	Israel	Mousterian	P
Early modern humans	Qafzeh 9	Middle Paleolithic - 95 ka [44]	F	Israel	Mousterian	μ CT
	Ohalo II H2	Early Upper Paleolithic - 19 ka [45]	M	Israel	Kebaran	μ CT
	Abri Pataud 26227 (P1)	Early Upper Paleolithic - 26-28 ka [46]	F	France	"Proto-Magdalenian" (Gravettian)	P
	Abri Pataud 26230 (P3)	Early Upper Paleolithic - 26-28 ka [46]	F	France	"Proto-Magdalenian" (Gravettian)	P
	Dame du Cavillon	Early Upper Paleolithic - 24 ka [47]	F	France	Gravettian	P

636

637

638 **Table 2.** Results of omnibus and subsequent pairwise one-way permutational MANOVAs on the
 639 first three PLS axes testing for differences in shape covariation between joints of trapezium and
 640 proximal joint of the Mc1 across taxa, between the side of the bones (right and left) and sex.
 641 Group multivariate variances were not significantly different ($p > 0.05$) and pairwise one-way
 642 permutational MANOVAs were only carried out when omnibus permutational MANOVA tests
 643 were significant. All values marked in bold where significant at $p < 0.05$, and are reported
 644 subsequent to a Bonferroni correction.

645

	2B-PLS between all the joints of the trapezium and the Mc1 proximal joint		
	PLS1	PLS2	PLS3
All taxa	< 0.0001	0.6409	0.0028
<i>Recent modern humans / Early modern humans</i>	0.8895	-	1
<i>Recent modern humans / Neanderthals</i>	0.0006	-	0.0012
<i>Neanderthals / Early modern humans</i>	0.1464	-	0.1179
Side of the bones	0.0708	0.5351	0.6055
Sex	0.1404	0.2288	0.8324

646
647