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# Reliability analysis for a $k / n(F)$ system with a repairable repair-equipment 

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#### Abstract

In this paper, the reliability and replacement policy of a $k / n(F)$ (i.e. $k-o u t-o f-n: F$ ) repairable system with a repairable repair equipment is analyzed. We assume that both the working and repair times of all components in the system and the repair-equipment follow exponential distributions, and the repair on the components is perfect whereas that on the repair equipment is imperfect. Under these assumptions, we derive reliability indices for such a system and discuss its properties. We also optimize a replacement policy $N$, under which the repair-equipment is replaced when its failure number reaches $N$. The explicit expression for the average cost rate of the repair-equipment is derived, and the corresponding optimal replacement policy $N^{*}$ can be obtained analytically or numerically. Finally, a numerical example for policy $N$ is given.


Key words: Geometric process, supplementary variables, vector Markov process, $M / M / 1$ queueing system, repairable repair-equipment.

## 1 Introduction

A $k / n(F)$ system consists of $n$ components: it fails if and only if at least $k$ components have failed. The dual of a $k / n(F)$ is $k / n(G)$ (i.e. $k$-out-of- $n: G$ ), which consists of $n$

[^0]components but it works if and only if at least $k$ components works. Obviously, a $k / n(F)$ system is equivalent to a $(n-k+1) / n(G)$ system. A $1 / n(F)$ system (or $n / n(F)$ ) system is a $n$-component series (or parallel) system. If $k$ components are consecutive in a $k / n(F$ or $G)$ system, the system becomes a $C(k, n: F$ or $G)$ (i.e. consecutive- $k$ -out-of- $n$ : $F$ or $G$ ) system. Therefore, a $k / n(F$ or $G)$ can be seen as an extension of various reliability systems, and it plays an important role in the reliability theory and real applications., This important feature attracts considerable research. For example, Barlow and Proschan [1], Linton and Saw [2], Phillips [3], Gupta and Sharma [4], Kenyon and Newell [5], Nakagawa [6], McGrady [7] and Moustafa [8] etc. They studied such a system with different approaches: they commonly assume that either the system is not repairable or the repair equipment does not fail. However, in some real cases, a repairequipment may experience failures.

The purpose of this paper is to analyze the reliability of a $k / n(F)$ repairable system with a repairable repair-equipment. We assume that a failed component of the system can be repaired as good as new, whereas the survival times of the repair-equipment after repairs follows a geometric process. The geometric process has been applied to optimise maintenance policies in various repairable systems, including simple systems, two-component systems and multi-component systems since it was first introduced by Lam [9, 10]. For more references, the reader is referred to. Lam [11], Zhang [12, 13, 14, 15], Lam et al [16], Zhang et al [17, 18, 19], Lam and Zhang [20, 21, 22], Wu and Clements-Croome [23], Wang and Zhang [24, 25], Zhang and Wang [26, 27, 28], and Lam et al [29].

Using both queueing theory and stochastic process theory, we not only derive reliability indices of such a $k / n(F)$ repairable system, but also optimize replacement policy $N$. The replacement policy aims to search an optimum number $N^{*}$ of replacements such that the average cost rate of the repair-equipment is minimized.

This paper is structured as follows. Section 2 introduces the definition of the geometric process and assumptions for the reliability analysis in the paper. Section 3 conducts reliability analysis using the vector Markov chain. Section 4 discusses properties of the $k / n(F)$ system. Section 5 derives replacement policy $N^{*}$ and provides numerical examples. Section 6 concludes this paper.

## 2 Definition and assumptions

Definition 1 Given two random variables $\xi$ and $\eta, \xi$ is said to be stochastically larger than $\eta$ or $\eta$ is stochastically smaller than $\xi$, if

$$
P(\xi>\alpha) \geq P(\eta>\alpha), \quad \text { for all real } \alpha,
$$

denoted by $\xi \geq_{s t} \eta$ or $\eta \leq_{s t} \xi$ (see e.g., Ross[30]). Furthermore, we say that a stochastic process $\left\{X_{n}, n=1,2, \cdots\right\}$ is stochastically decreasing if $X_{n} \geq_{s t} X_{n+1}$ and stochastically increasing if $X_{n} \leq_{s t} X_{n+1}$ for all $n=1,2, \cdots$.

Definition 2 A stochastic process $\left\{\xi_{n}, n=1,2, \cdots\right\}$ is a geometric process, if there exists a real $a>0$ such that $\left\{a^{n-1} \xi_{n}, n=1,2, \cdots\right\}$ forms a renewal process. The real $a$ is called the ratio of the geometric process (see e.g., Lam [10], Zhang [12] for more details).

Obviously, from Definition 2, we have:
(i) If $a>1$, then $\left\{\xi_{n}, n=1,2, \cdots\right\}$ is stochastically decreasing, i.e.

$$
\xi_{n} \geq_{s t} \xi_{n+1}, \quad n=1,2, \cdots
$$

(ii) If $0<a<1$, then $\left\{\xi_{n}, n=1,2, \cdots\right\}$ is stochastically increasing, i.e.

$$
\xi_{n} \leq_{s t} \xi_{n+1}, \quad n=1,2, \cdots
$$

(iii) If $a=1$, then the geometric process becomes a renewal process.
(iv) If $E \xi_{1}=\frac{1}{\lambda}$, then $E \xi_{n}=\frac{1}{a^{n-1} \lambda}$.

Suppose the following assumptions holds.

Assumption 1 A system consists of $n$ identical components and a repairable repairequipment. The system fails if and only if at least $k$ components have failed. The $n$ components are repairable, and the order of repair for failed components is with a "first in first out" rule.

Assumption 2 At the beginning, a new $k / n(F)$ system, a repairable repair-equipment and one repairman is installed. A failed component is maintained by the repair-equipment and the repair equipment is maintained by the repairman. Repair for a failed component in the system is perfect whereas repair for the repair-equipment is imperfect. Assume the survival times after repairs for the repair-equipment follow a geometric process.

Assumption 3 If the repair-equipment fails while a component is being repaired, the repairman will repair the repair-equipment immediately and the failed component will be waiting for repair. The repair-equipment will be re-started immediately after the completion of its repair, and the repair on the failed component will be continued. During the repair for the repair-equipment, the system is shut down and the un-failed components in the system do not fail any more. The repair-equipment does not fail when it
is idle. As soon as at least $k$ components are ready for work, the system will be re-started.
Assumption 4 Assume that the successive working times $\xi_{n}, n=1,2, \cdots$ and the consecutive repair times $\eta_{n}, n=1,2, \cdots$ of all $n$ components are respectively i.i.d. random variables, and their survival distributions

$$
\begin{aligned}
& F(t)=P\left(\xi_{n} \leq t\right)=1-e^{-\lambda t} \\
& G(t)=P\left(\eta_{n} \leq t\right)=1-e^{-\mu t}
\end{aligned}
$$

where $t \geq 0, \quad n=1,2, \cdots$, respectively. Assume that $\mu>\lambda$.

Assumption 5 The time interval between the completions of the $(n-1)$ th and $n$th repairs of the repair-equipment is called the $n$th cycle of the repair-equipment. Let $X_{n}$ and $Y_{n}$ be respectively the working and the repair times of the repair-equipment in the $n$th cycle, $n=1,2, \cdots$. Then $\left\{X_{n}, n=1,2, \cdots\right\}$ and $\left\{Y_{n}, n=1,2, \cdots\right\}$ form respectively a decreasing geometric process with ratio $a \geq 1$ and a increasing geometric process with ratio $0<b \leq 1$, and survival distributions of $X_{n}$ and $Y_{n}$ are

$$
\begin{aligned}
& H_{n}(t)=P\left(X_{n} \leq t\right)=1-e^{-a^{n-1} \alpha t} \\
& K_{n}(t)=P\left(Y_{n} \leq t\right)=1-e^{-b^{n-1} \beta t}
\end{aligned}
$$

where $t \geq 0, \alpha>0, \beta>0, \quad n=1,2, \cdots$, respectively.

Assumption $6 \xi_{n}, \eta_{n}, X_{n}, Y_{n}, n=1,2, \cdots$ are all independent random variable sequences.

## Remarks

(1) The assumption $\mu>\lambda$ makes the $k / n(F)$ system closer to real situations.
(2) If we regard the three items, the repair-equipment, the failed component and the repairman, as a service station, a customer and a service respectively, then the three forms a queueing system. Under the above assumptions, the $k / n(F)$ repairable system is equivalent to a repairable $M / M / 1$ queueing system with finite customer-source. Hence, the system in this paper can regard as a repairable $M / M(M / M) / 1 / k / n$ queueing system, where the symbol $(M / M)$ denotes the working times and repair times of the service station (i.e. the repair-equipment) to be exponential. The difference between our queueing system and the classical $M / M / 1 / k / n$ queueing system is that the service station in our queueing system is subject to failure. In this paper, we shall study a $k / n(F)$ repairable
system with repairable repair-equipment by dint of a $M / M(M / M) / 1 / k / n$ queueing system with repairable service station.
(3) Assumption 3 is reasonable. For example, consider a local area computer network system with a repairable printer, and there are several workstations connectting to the printer. Now, we regard the printer and a print job as a service station and a customer in the print system respectively. Printing jobs submitted from a workstation have to queue up as a customer in the print system. If the printer fails to work, it will be repaired, and the jobs have to wait for printing. The printer will be restarted immediately after the completion of its repair, and the queueing printing jobs can be conducted. The reader is also referred Lam et al [29] for more detailed discussion. Hence, from an application perspective, the research of this paper is helpful for some maintenance engineers.

## 3 System analysis

Now, let $N(t)$ be the system state at time $t$. According to the model assumptions, we have


In fact, the state $N(t)$ of the $k / n(F)$ system as the above-discussed is equivalent to the following state $N(t)$ of a $M / M(M / M) / 1 / k / n$ queueing system with a repairable service station, i.e.


Obviously, the state space is $\Omega=\left\{0,1_{w}, 1_{f}, \cdots, m_{w}, m_{f}, \cdots,(k-1)_{w},(k-1)_{f}, k_{w}, k_{f}\right\}$, the set of working states is $W=\left\{0,1_{w}, \cdots, m_{w}, \cdots,(k-1)_{w}\right\}$, and the set of failure states is $F=\left\{1_{f}, \cdots, m_{f}, \cdots,(k-1)_{f}, k_{w}, k_{f}\right\}$. Although $\{N(t), t \geq 0\}$ is not a Markov process, we can obtain a vector Markov process by introducing a supplementary variable. Let the supplementary variable $S(t)=l_{w}$ or $l_{f},(l=1,2, \cdots)$ be the working state or the repair state of the repair-equipment in $l$ th cycle at time $t$, then $\{N(t), S(t), t \geq 0\}$ forms a vector Markov process.

Denote the state probability of the system by

$$
p_{m l_{w}}(t)=P\left(N(t)=m_{w}, S(t)=l_{w}\right),(m=0,1, \cdots, k-1 ; l=1,2, \cdots),
$$

and

$$
p_{m l_{f}}(t)=P\left(N(t)=m_{f}, S(t)=l_{f}\right),(m=1,2, \cdots, k-1, k ; l=1,2, \cdots)
$$

According to the classical probability theory, it is straightforward to derive the following differential equations:

$$
\begin{align*}
\frac{d}{d t} p_{0 l_{w}}(t)= & -n \lambda p_{0 l_{w}}(t)+\mu p_{1 l_{w}}(t), \quad(l=1,2, \cdots)  \tag{1}\\
\frac{d}{d t} p_{m 1_{w}}(t)= & -((n-m) \lambda+\mu+\alpha) p_{m 1_{w}}(t)+(n-m+1) \lambda p_{(m-1) 1_{w}}(t)+\mu p_{(m+1) 1_{w}}(t) \\
& (m=1,2, \cdots, k-1)  \tag{2}\\
\frac{d}{d t} p_{k 1_{w}}(t)= & -(\mu+\alpha) p_{k 1_{w}}(t)+(n-k+1) \lambda p_{(k-1) 1_{w}}(t),  \tag{3}\\
\frac{d}{d t} p_{m l_{w}}(t)= & -\left((n-m) \lambda+\mu+a^{l-1} \alpha\right) p_{m l_{w}}(t)+(n-m+1) \lambda p_{(m-1) l_{w}}(t)+\mu p_{(m+1) l_{w}}(t)  \tag{t}\\
& +b^{l-2} \beta p_{m(l-1)_{f}}(t), \quad(m=1,2, \cdots, k-1 ; \quad l=2,3, \cdots)  \tag{4}\\
\frac{d}{d t} p_{k l_{w}}(t)= & -\left(\mu+a^{l-1} \alpha\right) p_{k l_{w}}(t)+(n-k+1) \lambda p_{(k-1) l_{w}}(t)+b^{l-2} \beta p_{k(l-1)_{f}}(t), \\
& (l=2,3, \cdots)  \tag{5}\\
\frac{d}{d t} p_{m l_{f}}(t)= & \left.-b^{l-1} \beta\right) p_{m l_{f}}(t)+a^{l-1} \alpha p_{m l_{w}}(t),(m=1,2, \cdots, k-1, k ; \quad l=1,2, \cdots) \tag{6}
\end{align*}
$$

The initial conditions are:

$$
\begin{gathered}
p_{01_{w}}(0)=1 ; \quad p_{0 l_{w}}(0)=0 \quad(l=2,3, \cdots), \\
p_{m l_{w}}(0)=0 \quad(m=1,2, \cdots, k-1, k ; \quad l=1,2, \cdots),
\end{gathered}
$$

and

$$
p_{m l_{f}}(0)=0 \quad(m=0,1, \cdots, k-1, k ; \quad l=1,2, \cdots) .
$$

## 4 Some characters of the $k / n(F)$ system

It is known there are three important indices in the queueing theory, i.e. queue length, waiting time and busy period and their distributions. This section will derive reliability indices, including system availability, mean waiting time and the idle probability of the repair-equipment, for the system, on the basis of the queueing theory. Let

$$
p_{m l_{w}}^{*}(s)=\int_{0}^{\infty} e^{-s t} p_{m l_{w}}(t) d t, \quad m=0,1,2, \cdots, k ; l=1,2, \cdots
$$

$$
p_{m l_{f}}^{*}(s)=\int_{0}^{\infty} e^{-s t} p_{m l_{f}}(t) d t, \quad m=1,2, \cdots, k ; l=1,2, \cdots
$$

be the Laplace transform of the state probability distribution. Then taking the Laplace transform on the both sides of the differential equations (1)-(6), considering the initial conditions, that the following equations are given

$$
\begin{align*}
(s+n \lambda) p_{01_{w}}^{*}(s)= & \mu p_{11_{w}}^{*}(s)+1  \tag{7}\\
(s+n \lambda) p_{0 l_{w}}^{*}(s)= & \mu p_{1 l_{w}}^{*}(s),(l=2,3, \cdots)  \tag{8}\\
(s+(n-m) \lambda+\mu+\alpha) p_{m 1_{w}}^{*}(s)= & (n-m+1) \lambda p_{(m-1) 1_{w}}^{*}(s)+\mu p_{(m+1) 1_{w}}^{*}(s), \\
& (m=1,2, \cdots, k-1)  \tag{9}\\
(s+\mu+\alpha) p_{k 1_{w}}^{*}(s)= & (n-k+1) \lambda p_{(k-1) 1_{w}}^{*}(s)  \tag{10}\\
\left(s+(n-m) \lambda+\mu+a^{l-1} \alpha\right) p_{m l_{w}}^{*}(s)= & (n-m+1) \lambda p_{(m-1) l_{w}}^{*}(s)+\mu p_{(m+1) l_{w}}^{*}(s) \\
& +b^{l-2} \beta p_{m(l-1)_{f}}^{*}(s), \\
& (m=1,2, \cdots, k-1 ; l=2,3, \cdots)  \tag{11}\\
\left(s+\mu+a^{l-1} \alpha\right) p_{k l_{w}}^{*}(s)= & (n-k+1) \lambda p_{(k-1) l_{w}}^{*}(s)+b^{l-2} \beta p_{k(l-1)_{f}}^{*}(s), \\
& (l=2,3, \cdots)  \tag{12}\\
\left(s+b^{l-1} \beta\right) p_{m l_{f}}^{*}(s)= & a^{l-1} \alpha p_{m l_{w}}^{*}(s), \\
& (m=1,2, \cdots, k-1 ; l=1,2, \cdots) \tag{13}
\end{align*}
$$

To solve equations (7)-(13), we recall from classical $M / M / 1$ queueing system, the busy periods $\left\{b_{1}, b_{2}, \cdots\right\}$ are i.i.d. with distribution $B(t)=P(b \leq t)$, where $b$ is denoted the busy length.

Lemma 1 The Laplace-Stieltjes tranform of $B(t)$ is given by

$$
B^{*}(s)=\int_{0}^{\infty} e^{-s t} d B(t)=\frac{s+\lambda+\mu-\sqrt{(s+\lambda+\mu)^{2}-4 \lambda \mu}}{2 \lambda}
$$

The proof of Lemma 1 can be find in Takacs[31] or Kleinrock[32].
Lemma 2 The distribution of $\sum_{i=1}^{n} X_{i}$ is given by

$$
H^{(n)}(t)=1-\sum_{i=1}^{n} \prod_{\substack{j=1 \\ j \neq i)}}^{n} \frac{a^{j-1}}{a^{j-1}-a^{i-1}} e^{-a^{i-1} \alpha t}
$$

Proof It is known that if $n$ random variables $X_{1}, X_{2}, \cdots, X_{n}$ are independent, and $X_{i}$ has exponential distribution with the parameter $\lambda_{i}$, i.e.

$$
H_{i}(t)=1-e^{-\lambda_{i} t} \text {, where, } \lambda_{i}=a^{i-1} \alpha ; i=1,2, \cdots, n
$$

with the definition of Laplace-Stieltjes transform of $H^{(n)}(t)$, we have

$$
\begin{aligned}
H^{*(n)}(s) & =\int_{0}^{\infty} e^{-s t} d H^{(n)}(t) \\
& =E\left\{e^{-s\left(\sum_{i=1}^{n} X_{i}\right)}\right\}=\prod_{i=1}^{n} E\left\{e^{-s X_{i}}\right\} \\
& =\prod_{i=1}^{n} \int_{0}^{\infty} e^{-s t} d H_{i}(t)=\prod_{i=1}^{n} \frac{\lambda_{i}}{s+\lambda_{i}}=\sum_{i=1}^{n} \frac{c_{i} \lambda_{i}}{s+\lambda_{i}}
\end{aligned}
$$

where

$$
c_{i}=\prod_{\substack{j=1 \\ j \neq i}}^{n} \frac{\lambda_{j}}{\lambda_{j}-\lambda_{i}}
$$

In reverse, we can obtain

$$
H^{(n)}(t)=\sum_{i=1}^{n} c_{i} H_{i}(t)=\sum_{i=1}^{n} c_{i}\left(1-e^{-\lambda_{i} t}\right)=\sum_{i=1}^{n} c_{i}-\sum_{i=1}^{n} c_{i} e^{-\lambda_{i} t}
$$

If $t \longrightarrow \infty$ and $H^{(n)}(t) \longrightarrow 1, \sum_{i=1}^{n} c_{i}=1$. Hence, Lemma 2 holds.
Theorem 1 At time $t$, the probabilities of all components working in the system are given by

$$
\begin{aligned}
p_{01_{w}}(t)= & e^{-\lambda t}+\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)}(t-u)-F^{(n)}(t-u)\right] e^{-\alpha u} d B^{(n-1)}(u), \\
p_{0 l_{w}}(t)= & \sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)} * K^{(l-1)}(t-u)-F^{(n)} * K^{(l-1)}(t-u)\right] \\
& \cdot\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u), \quad(l=2,3, \cdots)
\end{aligned}
$$

where

$$
\begin{gathered}
F^{(n)}(t)=F(t) * F(t) * \cdots * F(t) \\
B^{(n)}(t)=B(t) * B(t) * \cdots * B(t) \\
H^{(n)}(t)=H(t) * H(a t) * \cdots * H\left(a^{n-1} t\right)
\end{gathered}
$$

and

$$
K^{(n)}(t)=K(t) * K(b t) * \cdots * K\left(b^{n-1} t\right)
$$

are respectively the cumulative probability distribution functions of $\sum_{i=1}^{n} \xi_{i}, \sum_{i=1}^{n} b_{i}, \sum_{i=1}^{n} X_{i}$ and $\sum_{i=1}^{n} Y_{i}$.

Proof According to the model assumptions and $N(0)=0$, at $t=0$, the repairequipment is idle. Since the idle period $v_{i}$ and the busy period $b_{i}(i=1,2, \cdots)$ occur alternatively, we have

$$
\begin{aligned}
p_{01_{w}}(t)= & P\left\{N(t)=0, S(t)=1_{w}\right\} \\
= & P\left(v_{1}>t\right)+\sum_{n=2}^{\infty} P\left\{\sum_{i=1}^{n-1}\left(v_{i}+b_{i}\right) \leq t<\sum_{i=1}^{n-1}\left(v_{i}+b_{i}\right)+v_{n} ; \sum_{i=1}^{n-1} b_{i}<X_{1}\right\} \\
= & 1-F(t)+\sum_{n=2}^{\infty} \int_{0}^{t} P\left\{\sum_{i=1}^{n-1} v_{i} \leq t-u<\sum_{i=1}^{n} v_{i} ; X_{1}>u\right\} d B^{(n-1)}(u) \\
= & e^{-\lambda t}+\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)}(t-u)-F^{(n)}(t-u)\right] e^{-\alpha u} d B^{(n-1)}(u), \\
p_{0 l_{w}}(t)= & P\left\{N(t)=0, S(t)=l_{w}\right\} \\
= & \sum_{n=2}^{\infty} P\left\{\sum_{i=1}^{n-1}\left(v_{i}+b_{i}\right)+\sum_{i=1}^{l-1} Y_{i} \leq t<\sum_{i=1}^{n-1}\left(v_{i}+b_{i}\right)+v_{n}+\sum_{i=1}^{l-1} Y_{i} ;\right. \\
& \left.\sum_{i=1}^{l-1} X_{i} \leq \sum_{i=1}^{n-1} b_{i}<\sum_{i=1}^{l} X_{i}\right\} \\
= & \sum_{n=2}^{\infty} \int_{0}^{t} P\left\{\sum_{i=1}^{n-1} v_{i}+\sum_{i=1}^{l-1} Y_{i} \leq t-u<\sum_{i=1}^{n} v_{i}+\sum_{i=1}^{l-1} Y_{i} ; \sum_{i=1}^{l-1} X_{i} \leq u<\sum_{i=1}^{l} X_{i}\right\} \\
& d B^{(n-1)}(u) \\
= & \sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)} * K^{(l-1)}(t-u)-F^{(n)} * K^{(l-1)}(t-u)\right] \\
& \cdot\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u), \quad(l=2,3, \cdots) .
\end{aligned}
$$

Theorem 2

$$
\begin{align*}
p_{01_{w}}^{*}(s)= & \frac{1}{s+\lambda-\lambda B^{*}(s+\alpha)},  \tag{14}\\
p_{0 l_{w}}^{*}(s)= & \prod_{j=1}^{l-1} \frac{(a b)^{j-1} \beta}{s+b^{j-1} \beta} \sum_{\left.\substack{i=1 \\
l} \prod_{\substack{r=1 \\
r \neq i}}^{l} \frac{1}{a^{r-1}-a^{i-1}}\right] \frac{\lambda B^{*}\left(s+a^{i-1} \alpha\right)}{(s+\lambda)\left[s+\lambda-\lambda B^{*}\left(s+a^{i-1} \alpha\right)\right]},}  \tag{15}\\
& (l=2,3, \cdots) .
\end{align*}
$$

Proof It follows from Theorem 1 that

$$
\begin{aligned}
p_{01 w_{w}}^{*}(s) & =\int_{0}^{\infty} e^{-s t} p_{01_{w}}(t) d t \\
& =\int_{0}^{\infty} e^{-s t}\left\{\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)}(t-u)-F^{(n)}(t-u)\right] e^{-\alpha u} d B^{(n-1)}(u)+e^{-\lambda t}\right\} d t
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{n=2}^{\infty} \int_{0}^{\infty}\left\{\int_{u}^{\infty} e^{-s t}\left[F^{(n-1)}(t-u)-F^{(n)}(t-u)\right] d t\right\} e^{-\alpha u} d B^{(n-1)}(u)+\frac{1}{s+\lambda} \\
& =\sum_{n=2}^{\infty} \int_{0}^{\infty}\left[\int_{0}^{\infty} e^{-s(u+v)}\left(F^{(n-1)}(v)-F^{(n)}(v)\right) d v\right] e^{-\alpha u} d B^{(n-1)}(u)+\frac{1}{s+\lambda} \\
& =\sum_{n=2}^{\infty} \int_{0}^{\infty} e^{-s u}\left[\int_{0}^{\infty} e^{-s v} F^{(n-1)}(v) d v-\int_{0}^{\infty} e^{-s v} F^{(n)}(v) d v\right] e^{-\alpha u} d B^{(n-1)}(u)+\frac{1}{s+\lambda} \\
& =\frac{1}{s+\lambda}+\sum_{n=2}^{\infty} \frac{1}{s}\left[\left(\frac{\lambda}{s+\lambda}\right)^{n-1}-\left(\frac{\lambda}{s+\lambda}\right)^{n}\right] \int_{0}^{\infty} e^{-(s+\alpha) u} d B^{(n-1)}(u) \\
& =\frac{1}{s+\lambda}+\sum_{n=2}^{\infty} \frac{\lambda^{n-1}}{(s+\lambda)^{n}}\left[B^{*}(s+\alpha)\right]^{n-1} \\
& =\frac{1}{s+\lambda-\lambda B^{*}(s+\alpha)}
\end{aligned}
$$

Similarly, from Theorem 1 and Lemma 2, we have

$$
\begin{aligned}
p_{0 l_{w}}^{*}(s)= & \int_{0}^{\infty} e^{-s t} p_{0 l_{w}}(t) d t \\
= & \int_{0}^{\infty} e^{-s t}\left\{\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)} * K^{(l-1)}(t-u)-F^{(n)} * K^{(l-1)}(t-u)\right]\right. \\
& {\left.\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u)\right\} d t } \\
= & \sum_{n=2}^{\infty} \int_{0}^{\infty}\left\{\int_{u}^{\infty} e^{-s t}\left[F^{(n-1)} * K^{(l-1)}(t-u)-F^{(n)} * K^{(l-1)}(t-u)\right] d t\right\} \\
& {\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u) } \\
= & \sum_{n=2}^{\infty} \int_{0}^{\infty}\left\{\int_{0}^{\infty} e^{-s(u+v)}\left[F^{(n-1)} * K^{(l-1)}(v)-F^{(n)} * K^{(l-1)}(v)\right] d v\right\} \\
& {\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u) } \\
= & \sum_{n=2}^{\infty} \frac{1}{s}\left[\frac{\lambda^{n-1}}{(s+\lambda)^{n-1}}-\frac{\lambda^{n}}{(s+\lambda)^{n}}\right]\left(\prod_{j=1}^{l-1} \frac{b^{j-1} \beta}{s+b^{j-1} \beta}\right) \int_{0}^{\infty} e^{-s u}\left[H^{(l-1)}(u)-H^{(l)}(u)\right] \\
& d B^{(n-1)}(u) \\
= & \prod_{j=1}^{l-1} \frac{b^{j-1} \beta}{s+b^{j-1} \beta} \sum_{n=2}^{\infty} \frac{\lambda^{n-1}}{(s+\lambda)^{n}} \int_{0}^{\infty} e^{-s u}\left[\sum_{i=1}^{l} \prod_{\substack{r=1 \\
(r \neq i)}}^{l} \frac{a^{r-1}}{a^{r-1}-a^{i-1}} e^{-a^{i-1} \alpha u}-\right. \\
& \left.\sum_{i=1}^{l-1} \prod_{\substack{r=1 \\
l-1}}^{l=a^{r-1}-a^{i-1}} e^{-a^{i-1} \alpha u}\right] d B^{(n-1)}(u)
\end{aligned}
$$

$$
\begin{aligned}
= & \prod_{j=1}^{l-1} \frac{b^{j-1} \beta}{s+b^{j-1} \beta}\left[\sum_{i=1}^{l} \prod_{\substack{r=1 \\
(r \neq i)}}^{l} \frac{a^{r-1}}{a^{r-1}-a^{i-1}} \sum_{n=2}^{\infty} \frac{\lambda^{n-1}}{(s+\lambda)^{n}}\left(B^{*}\left(s+a^{i-1} \alpha\right)\right)^{n-1}-\right. \\
& \left.\sum_{i=1}^{l-1} \prod_{\substack{r=1 \\
(\neq i)}}^{l-1} \frac{a^{r-1}}{a^{r-1}-a^{i-1}} \sum_{n=2}^{\infty} \frac{\lambda^{n-1}}{(s+\lambda)^{n}}\left(B^{*}\left(s+a^{i-1} \alpha\right)\right)^{n-1}\right] \\
= & \prod_{j=1}^{l-1} \frac{b^{j-1} \beta}{s+b^{j-1} \beta}\left[\sum_{i=1}^{l} \prod_{\substack{r=1 \\
(r \neq i)}}^{l} \frac{a^{r-1}}{a^{r-1}-a^{i-1}} \frac{\lambda B^{*}\left(s+a^{i-1} \alpha\right)}{(s+\lambda)\left[s+\lambda-\lambda B^{*}\left(s+a^{i-1} \alpha\right)\right]}-\right. \\
& \left.\sum_{i=1}^{l-1} \prod_{\substack{r=1 \\
(r \neq i)}}^{l-1} \frac{a^{r-1}}{a^{r-1}-a^{i-1}} \frac{\lambda B^{*}\left(s+a^{i-1} \alpha\right)}{(s+\lambda)\left[s+\lambda-\lambda B^{*}\left(s+a^{i-1} \alpha\right)\right]}\right] \\
= & \prod_{j=1}^{l-1} \frac{(a b)^{j-1} \beta}{s+b^{j-1} \beta} \sum_{i=1}^{l}\left[\prod_{\substack{r=1 \\
(r \neq i)}}^{l} \frac{1}{a^{r-1}-a^{i-1}}\right] \frac{\lambda B^{*}\left(s+a^{i-1} \alpha\right)}{(s+\lambda)\left[s+\lambda-\lambda B^{*}\left(s+a^{i-1} \alpha\right)\right]}
\end{aligned}
$$

On the basis of Theorem 2, we can derive the Laplace transform $p_{m l_{w}}^{*}(s)$ of $p_{m l_{w}}(t)$. To do this, first of all it follows from the equation (7) that

$$
\begin{equation*}
p_{11_{w}}^{*}(s)=\frac{s+n \lambda}{\mu} p_{01_{w}}^{*}(s)-\frac{1}{\mu}=\frac{(n-1) \lambda B^{*}(s+\alpha)}{\mu\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]} \tag{16}
\end{equation*}
$$

Furthermore, we have the following theorem.
Theorem 3

$$
p_{m 1 w}^{*}(s)=\frac{(n-1) \lambda B^{*}(s+\alpha)\left(M^{m}-N^{m}\right)+\mu\left(M N^{m}-N M^{m}\right)}{\mu(M-N)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]}, \quad(m=0,1,2, \cdots, k-1)
$$

where $M$ and $N$ are two roots of the quadratic equation

$$
\begin{equation*}
t^{2}-\frac{s+(n-m) \lambda+\mu+\alpha}{\mu} t+\frac{(n-m+1) \lambda}{\mu}=0 \tag{17}
\end{equation*}
$$

proof According to (9), we have

$$
\begin{gather*}
p_{(m+1) 1_{w}}^{*}(s)=\frac{s+(n-m) \lambda+\mu+\alpha}{\mu} p_{m 1_{w}}^{*}(s)-\frac{(n-m+1) \lambda}{\mu} p_{(m-1) 1_{w}}^{*}(s),  \tag{18}\\
(m=1,2, \cdots, k-1)
\end{gather*}
$$

Because $M$ and $N$ are two roots of the equation (17), then

$$
M+N=\frac{s+(n-m) \lambda+\mu+\alpha}{\mu}, \quad M N=\frac{(n-m+1) \lambda}{\mu}
$$

and equation (18) becomes

$$
p_{(m+1) 1_{w}}^{*}(s)-M p_{m 1_{w}}^{*}(s)=N\left[p_{m 1_{w}}^{*}(s)-M p_{(m-1) 1_{w}}^{*}(s)\right]
$$

or

$$
p_{(m+1) 1_{w}}^{*}(s)-N p_{m 1_{w}}^{*}(s)=M\left[p_{m 1_{w}}^{*}(s)-N p_{(m-1) 1_{w}}^{*}(s)\right]
$$

By iteration, it is straightforward that

$$
\begin{equation*}
p_{m 1_{w}}^{*}(s)-M p_{(m-1) 1_{w}}^{*}(s)=N^{m-1}\left[p_{11_{w}}^{*}(s)-M p_{01_{w}}^{*}(s)\right] \tag{19}
\end{equation*}
$$

and

$$
\begin{equation*}
p_{m 1_{w}}^{*}(s)-N p_{(m-1) 1_{w}}^{*}(s)=M^{m-1}\left[p_{11_{w}}^{*}(s)-N p_{01_{w}}^{*}(s)\right] \tag{20}
\end{equation*}
$$

According to the equations (14), (16), (19) and (20), we can obtain

$$
\begin{aligned}
p_{m 1_{w}}^{*}(s) & =\frac{M^{m}-N^{m}}{M-N} p_{11_{w}}^{*}(s)+\frac{M N^{m}-N M^{m}}{M-N} p_{01_{w}}^{*}(s) \\
& =\frac{(n-1) \lambda B^{*}(s+\alpha)\left(M^{m}-N^{m}\right)+\mu\left(M N^{m}-N M^{m}\right)}{\mu(M-N)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]},(m=0,1,2, \cdots, k-1)
\end{aligned}
$$

According to the equation (13) and Theorem 3, we have

$$
\begin{align*}
& p_{m 1_{f}}^{*}(s)=\frac{\alpha}{s+\beta} p_{m 1_{w}}^{*}(s) \\
& =\frac{(n-1) \lambda \alpha B^{*}(s+\alpha)\left(M^{m}-N^{m}\right)+\mu \alpha\left(M N^{m}-N M^{m}\right)}{\mu(M-N)(s+\beta)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]}, \quad(m=1,2, \cdots, k) \tag{21}
\end{align*}
$$

According to the equation (15) in Theorem 2, we have

$$
\begin{equation*}
p_{02_{w}}^{*}(s)=\frac{\lambda \beta}{(s+\beta)(a-1)} \frac{B^{*}(s+\alpha)-B^{*}(s+a \alpha)}{\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]\left[s+\lambda-\lambda B^{*}(s+a \alpha)\right]} \tag{22}
\end{equation*}
$$

According to the equations (8), (11), (12), (21) and (22), we can obtain

$$
\begin{aligned}
p_{12 w}^{*}(s)= & \frac{\lambda \beta(s+n \lambda)}{\mu(s+\beta)(a-1)} \cdot \frac{B^{*}(s+\alpha)-B^{*}(s+a \alpha)}{\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]\left[s+\lambda-\lambda B^{*}(s+a \alpha)\right]} \\
p_{22_{w}}^{*}(s)= & \frac{\lambda \beta[(s+n \lambda)(s+(n-1) \lambda+\mu+a \alpha)-n \lambda \mu]\left[B^{*}(s+\alpha)-B^{*}(s+a \alpha)\right]}{\mu^{2}(s+\beta)(a-1)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]\left[s+\lambda-\lambda B^{*}(s+a \alpha)\right]} \\
& -\frac{(n-1) \lambda \alpha \beta B^{*}(s+\alpha)}{\mu^{2}(s+\beta)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]}
\end{aligned}
$$

Then we can determine $p_{m 2_{w}}^{*}(s)$, for $m=3,4, \cdots, k-1, k$ by using the equations (11), (12) and the above obtained results again and again. And by using the equation (13), we can get $p_{m 2_{f}}^{*}(s)$, for $m=1,2, \cdots, k-1, k$. In general, on the basis of Theorem 2 and 3, we can also determine the Laplace transform $p_{m l_{w}}^{*}(s)$ and $p_{m l_{f}}^{*}(s)$ from the equations (7) to (13) recurrently.

### 4.1 System availability

By the definition, the availability of the system at time $t$ is given by

$$
\begin{aligned}
A(t) & =P\{N(t) \in W\}=\sum_{l=1}^{\infty}\left[\sum_{m=0}^{k-1} p_{m l_{w}}(t)\right] \\
& =p_{01_{w}}(t)+\sum_{l=1}^{\infty}\left[\sum_{m=1}^{k-1} p_{m l_{w}}(t)\right]
\end{aligned}
$$

and the Laplace transform of $A(t)$ is given by

$$
A^{*}(s)=p_{01_{w}}^{*}(s)+\sum_{l=1}^{\infty}\left[\sum_{m=1}^{k-1} p_{m l_{w}}^{*}(s)\right]
$$

### 4.2 Mean of waiting time

A failed component at time $t$ is repaired immediately when the repair-equipment is idle, otherwise it will wait for repair according to the "first in first out" rule. Thus, the mean waiting time of a failed component at time $t$ is an interesting index for the $k / n(F)$ system. Let $W_{t}$ be the waiting time for repair of a failed component at time $t$, and let $G_{m}$ be the total chain-repair time for $m$ failed components in the system and denote the distribution of $G_{m}$ by $G^{(m)}$. Moreover, let $\hat{X}_{i}$ be the residual life of $X_{i}$. Then we can obtain the following theorem about the distribution of waiting time.

Theorem 4 Let the distribution of $W_{t}$ be $W_{t}(x)$, then

$$
W_{t}(x)=\sum_{l=1}^{\infty} \sum_{m=1}^{k-1} p_{m l_{w}}(t) \sum_{n=0}^{\infty} \int_{0}^{x} K_{l}^{(n)}(x-u)\left[H_{l}^{(n)}(u)-H_{l}^{(n+1)}(u)\right] d G^{(m)}(u)
$$

where $n$ is the failed number of the repair-equipment during the time $G_{m}$. And

$$
\begin{aligned}
& K_{l}^{(n)}(u)=K_{l}(u) * K_{l+1}(u) * \cdots * K_{l+n-1}(u) \\
& H_{l}^{(n)}(u)=H_{l}(u) * H_{l+1}(u) * \cdots * H_{l+n-1}(u) \\
& G^{(m)}(u)=G(u) * G(u) * \cdots * G(u)
\end{aligned}
$$

Proof According to the conditional probability and the formula of total probability, we have

$$
\begin{aligned}
W_{t}(x) & =P\left\{W_{t} \leq x\right\} \\
& =\sum_{l=1}^{\infty} \sum_{m=1}^{k-1} P\left\{W_{t} \leq x, N(t)=m_{w}, S(t)=l_{w}\right\}
\end{aligned}
$$

$$
\begin{aligned}
= & \sum_{l=1}^{\infty} \sum_{m=1}^{k-1} P\left\{N(t)=m_{w}, S(t)=l_{w}\right\} P\left\{W_{t} \leq x \mid N(t)=m_{w}, S(t)=l_{w}\right\} \\
= & \sum_{l=1}^{\infty} \sum_{m=1}^{k-1} p_{m l_{w}}(t) \sum_{n=0}^{\infty} P\left\{G_{m}+\sum_{i=l}^{l+n-1} Y_{i} \leq x, \hat{X}_{l}+\sum_{i=l+1}^{l+n-1} X_{i} \leq G_{m}<\hat{X}_{l}+\sum_{i=l+1}^{l+n} X_{i}\right\} \\
= & \sum_{l=1}^{\infty} \sum_{m=1}^{k-1} p_{m l_{w}}(t) \sum_{n=0}^{\infty} \int_{0}^{x} P\left\{\sum_{i=l}^{l+n-1} Y_{i} \leq x-u, \hat{X}_{l}+\sum_{i=l+1}^{l+n-1} X_{i} \leq u<\hat{X}_{l}+\sum_{i=l+1}^{l+n} X_{i}\right\} \\
& d G^{(m)}(u) \\
= & \sum_{l=1}^{\infty} \sum_{m=1}^{k-1} p_{m l_{w}}(t) \sum_{n=0}^{\infty} \int_{0}^{x} K_{l}^{(n)}(x-u)\left[H_{l}^{(n)}(u)-H_{l}^{(n+1)}(u)\right] d G^{(m)}(u)
\end{aligned}
$$

Thus, the mean of waiting time to a failed component for repair is given by

$$
E W_{t}=\int_{0}^{\infty} x d W_{t}(x)
$$

Clearly, if the value of $E W_{t}$ is larger, we should improve the repair efficiency of the repair-equipment so that the cost of the system is decreased.

### 4.3 Mean of busy period

It is well known that a busy period for the repair-equipment will start when a component in the system fails and the number of failed component in the system is 1 , it will end at the time that the number of the failed components in the system reduces to 0 . To determine the mean of busy period for the repair-equipment, we study a stochastic process $\{\tilde{N}(t), t \geq 0\}$. The only difference between the processes $\{N(t), t \geq 0\}$ and $\{\tilde{N}(t), t \geq 0\}$ is that the state 0 is an absorbing state in $\{\tilde{N}(t), t \geq 0\}$.

Let $\tilde{B}$ be the length of a busy period, then the distribution function is given by

$$
\tilde{B}(t)=P\{\tilde{B} \leq t\}=P\{\tilde{N}(t)=0\}
$$

Furthermore, we can obtain the following theorem about the distribution of busy period.

## Theorem 5

$$
\tilde{B}(t)=\sum_{l=1}^{\infty} B(t)\left[1-H_{l}(t)\right]+\sum_{l=1}^{\infty} \sum_{n=1}^{\infty} \int_{0}^{t} B(t-u)\left[H_{l}^{(n)}(t-u)-H_{l}^{(n+1)}(t-u)\right] d K_{l}^{(n)}(u)
$$

where $B(t)$ is the distribution of a busy period in the classical $M / M / 1$ queueing system.
Proof First of all, we introduce a supplementary variable $\tilde{S}(t)$ which is the same as the $S(t)$ in the process $\{N(t), t \geq 0\}$, such that $\tilde{S}(t)=l_{w}$, if the ( $l-1$ )th repair has
been completed. Thus we can also obtain a vector Markov process $\{\tilde{N}(t), \tilde{S}(t), t \geq 0\}$. Thus

$$
\begin{aligned}
\tilde{B}(t)= & P\{\tilde{N}(t)=0\} \\
= & \sum_{l=1}^{\infty} \sum_{j=l}^{\infty} P\left\{\tilde{N}(t)=0, \tilde{S}(t)=j_{w}, \tilde{S}(0)=l_{w}\right\} \\
= & \sum_{l=1}^{\infty} P\left\{\tilde{N}(t)=0, \tilde{S}(t)=l_{w}, \tilde{S}(0)=l_{w}\right\} \\
& +\sum_{l=1}^{\infty} \sum_{j=l+1}^{\infty} P\left\{\tilde{N}(t)=0, \tilde{S}(t)=j_{w}, \tilde{S}(0)=l_{w}\right\} \\
= & \sum_{l=1}^{\infty} P\left\{\tilde{N}(t)=0, \text { the repair-equipment works in }(0, t], \tilde{S}(0)=l_{w}\right\} \\
& +\sum_{l=1}^{\infty} \sum_{n=j-l=1}^{\infty} P\left\{\tilde{N}(t)=0, \text { the repair-equipment fails for } n \text { times in }(0, t], \tilde{S}(0)=l_{w}\right\} \\
= & \sum_{l=1}^{\infty} P\left\{B \leq t, \hat{X}_{l}>t\right\}+\sum_{l=1}^{\infty} \sum_{n=1}^{\infty} P\left\{B+\sum_{i=l}^{l+n-1} Y_{i} \leq t, \hat{X}_{l}+\sum_{i=l}^{l+n-1} Y_{i}+\sum_{i=l+1}^{l+n-1} X_{i} \leq t\right. \\
& \left.<\hat{X}_{l}+\sum_{i=l}^{l+n-1} Y_{i}+\sum_{i=l+1}^{l+n} X_{i}\right\} \\
= & \sum_{l=1}^{\infty} B(t)\left[1-H_{l}(t)\right] \\
& +\sum_{l=1}^{\infty} \sum_{n=1}^{\infty} \int_{0}^{t} P\left\{B \leq t-u, \hat{X}_{l}+\sum_{i=l+1}^{l+n-1} X_{i} \leq t-u<\hat{X}_{l}+\sum_{i=l+1}^{l+n} X_{i}\right\} d K_{l}^{(n)}(u) \\
= & \sum_{l=1}^{\infty} B(t)\left[1-H_{l}(t)\right]+\sum_{l=1}^{\infty} \sum_{n=1}^{\infty} \int_{0}^{t} B(t-u)\left[H_{l}^{(n)}(t-u)-H_{l}^{(n+1)}(t-u)\right] d K_{l}^{(n)}(u)
\end{aligned}
$$

Thus, the mean of busy period for the repair-equipment is given by

$$
E \tilde{B}=\int_{0}^{\infty} t d \tilde{B}(t)
$$

### 4.4 The idle probability of the repair-equipment

Clearly, the repair-equipment will be idle when all components are working at time $t$. Thus, according to Theorem 1, the idle probability of the repair-equipment at time $t$ is given by

$$
I(t)=P\{N(t)=0\}=p_{01_{w}}(t)+p_{0 l_{w}}(t)
$$

$$
\begin{aligned}
= & e^{-\lambda t}+\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)}(t-u)-F^{(n)}(t-u)\right] e^{-\alpha u} d B^{(n-1)}(u) \\
& +\sum_{n=2}^{\infty} \int_{0}^{t}\left[F^{(n-1)} * K^{(l-1)}(t-u)-F^{(n)} * K^{(l-1)}(t-u)\right] \\
& \cdot\left[H^{(l-1)}(u)-H^{(l)}(u)\right] d B^{(n-1)}(u), \quad(l=1,2, \cdots)
\end{aligned}
$$

### 4.5 Repair-equipment MTTFF

To determine the mean time to first failure(MTTFF) of the repair-equipment, we derive the distribution of the time to first failure of the repair-equipment. Given that there is no failed component in the system at the beginning, let $T_{f}$ be the time to the first failure of the repair-equipment, and let the distribution of $T_{f}$ be

$$
\begin{equation*}
\Psi_{0}(t)=P\left\{T_{f} \leq t \mid N(0)=0\right\} \tag{23}
\end{equation*}
$$

and denote the Laplace-Stieltjes tranform of $\Psi_{0}(t)$ by $\Psi_{0}^{*}(s)=\int_{0}^{\infty} e^{-s t} d \Psi_{0}(t)$. Then we have the following theorem.

Theorem 6

$$
\Psi_{0}^{*}(s)=\frac{\lambda \alpha\left[1-B^{*}(s+\alpha)\right]}{(s+\alpha)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]}
$$

Proof As before, let $v_{i}$ be the $i$ th idle period, then it follows from the equation (23) that

$$
\begin{aligned}
\Psi_{0}(t) & =P\left\{T_{f} \leq t \mid N(0)=0\right\} \\
& =\sum_{n=1}^{\infty} P\left\{\sum_{i=1}^{n} v_{i}+X_{1} \leq t, \sum_{i=1}^{n-1} b_{i}<X_{1} \leq \sum_{i=1}^{n} b_{i}\right\} \\
& =\sum_{n=1}^{\infty} \int_{0}^{t} P\left\{\sum_{i=1}^{n} v_{i} \leq t-u, \sum_{i=1}^{n-1} b_{i}<u \leq \sum_{i=1}^{n} b_{i}\right\} d H_{1}(u) \\
& =\sum_{n=1}^{\infty} \int_{0}^{t} F^{(n)}(t-u)\left[B^{(n-1)}(u)-B^{(n)}(u)\right] d H_{1}(u)
\end{aligned}
$$

Consequently, we have

$$
\begin{aligned}
\Psi_{0}^{*}(s) & =\int_{0}^{\infty} e^{-s t} d \Psi_{0}(t) \\
& =\sum_{n=1}^{\infty}\left(\frac{\lambda}{s+\lambda}\right)^{n} \int_{0}^{\infty} e^{-s t}\left[B^{(n-1)}(t)-B^{(n)}(t)\right] d H_{1}(t) \\
& =\sum_{n=1}^{\infty}\left(\frac{\lambda}{s+\lambda}\right)^{n} \int_{0}^{\infty} \alpha e^{-(s+\alpha) t}\left[B^{(n-1)}(t)-B^{(n)}(t)\right] d H_{1}(t)
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{n=1}^{\infty}\left(\frac{\lambda}{s+\lambda}\right)^{n}\left[\frac{\alpha}{s+\alpha}\left(B^{*}(s+\alpha)\right)^{n-1}-\frac{\alpha}{s+\alpha}\left(B^{*}(s+\alpha)\right)^{n}\right] \\
& =\frac{\alpha}{s+\alpha} \sum_{n=1}^{\infty}\left[\frac{\lambda}{s+\lambda}\left(\frac{\lambda B^{*}(s+\alpha)}{s+\lambda}\right)^{n-1}-\left(\frac{\lambda B^{*}(s+\alpha)}{s+\lambda}\right)^{n}\right] \\
& =\frac{\lambda \alpha\left[1-B^{*}(s+\alpha)\right]}{(s+\alpha)\left[s+\lambda-\lambda B^{*}(s+\alpha)\right]}
\end{aligned}
$$

Thus, the mean time to first failure (MTTFF) of the repair-equipment is given by

$$
E T_{f}=-\left.\frac{d}{d s} \Psi_{0}^{*}(s)\right|_{s=0}=\frac{1}{\alpha}+\frac{1}{\lambda\left[1-B^{*}(\alpha)\right]}
$$

### 4.6 Availability of the repair-equipment

Let the availability of the repair-equipment at time $t$ be

$$
A_{f}(t)=P\{\text { the repair-equipment works at time } t \mid N(0)=0\} .
$$

Then

$$
\bar{A}_{f}(t)=P\{\text { the repair-equipment fails at time } t \mid N(0)=0\}
$$

is the probability that the repair-equipment fails at time $t$. Now, denote the Laplace transforms of $A_{f}(t)$ and $\bar{A}_{f}(t)$ by $A_{f}^{*}(s)$ and $\bar{A}_{f}^{*}(s)$ respectively. Then, the following theorem follows directly.

Theorem 7

$$
A_{f}^{*}(s)=\sum_{m=0}^{k-1} \sum_{l=1}^{\infty} p_{m l_{w}}^{*}(s)
$$

Proof It is clear that

$$
\begin{aligned}
A_{f}(t) & =P\{\text { the repair-equipment works at time } t \mid N(0)=0\} \\
& =\sum_{m=0}^{k-1} \sum_{l=1}^{\infty} P\left\{N(t)=m_{w}, S(t)=l_{w} \mid N(0)=0\right\} \\
& =\sum_{m=0}^{k-1} \sum_{l=1}^{\infty} p_{m l_{w}}(t)
\end{aligned}
$$

Therefore

$$
A_{f}^{*}(s)=\sum_{m=0}^{k-1} \sum_{l=1}^{\infty} p_{m l_{w}}^{*}(s)
$$

Furthermore, due to the fact $A_{f}(t)+\bar{A}_{f}(t)=1$, we have

$$
A_{f}^{*}(s)+\bar{A}_{f}^{*}(s)=\frac{1}{s}
$$

Consequently, $\bar{A}_{f}^{*}(s)$ can also be determined.

### 4.7 Repair-equipment ROCOF

The ROCOF is one of important indices in reliability theory. Let $M_{f}(t)$ be the mean failure number of the repair-equipment in $(0, t]$, then its derivative $m_{f}(t)=\frac{d}{d t} M_{f}(t)$ is called the rate of occurrence of failure (ROCOF). According to Lam [33], the ROCOF can be evaluated in the following way:

$$
m_{f}(t)=\sum_{m \in W, n \in F} \sum_{l=1}^{\infty} p_{m l_{w}}(t) r_{m n l}
$$

where $r_{m n l}$ is transition rate from state $m$ to state $n$ in $l$ th cycle. Thus, we can obtain

$$
m_{f}^{*}(s)=\sum_{m=1}^{k} \sum_{l=1}^{\infty} a^{l-1} \alpha p_{m l_{w}}^{*}(s)
$$

where $m_{f}^{*}(s)$ is the Laplace transform of $m_{f}(t)$. Since $p_{m l_{w}}^{*}(s)$ has been determined in Section 4, we can then evaluate $m_{f}^{*}(s)$.

## 5 Replacement policy for the repair-equipment

### 5.1 Average cost rate under policy $N$

In this section, we consider a replacement policy $N$ based on the number of failures of the repair-equipment. The repair-equipment will be replaced by a new and identical one when the failure number of the repair-equipment reaches $N$. Our objective is to choose an optimal replacement policy $N^{*}$ such that the average cost rate of the repairequipment is minimized. To do this, besides the model assumptions in Section 2, we add some assumptions as follows.

Assumption 7 A replacement policy $N$ based on the number of failures of the repair-equipment is used. The repair-equipment will be replaced sometime by a new and identical one, and the replacement time is negligible.

Assumption 8 The repair cost rate of the repair-equipment is $c_{r}$, the working reward rate of the repair-equipment is $c_{w}$, and the fixed replacement cost of the repairequipment is $C$.

Let $\tau_{1}$ be the first replacement time of the repair-equipment after installation, and $\tau_{n}(n \geq 2)$ be the time between the $(n-1)$ th and the $n$th replacements of the repairequipment under policy $N$. Clearly, $\left\{\tau_{1}, \tau_{2}, \cdots\right\}$ forms a renewal process, and the time between two consecutive replacements is called a renewal cycle.

Let $C(N)$ be the average cost rate of the repair-equipment under policy $N$. Thus, according to the model assumptions and the renewal reward theorem (see, for example

Ross [30]), we have

$$
\begin{align*}
C(N) & =\frac{\text { the expected cost incurred in a renewal cycle }}{\text { the expected length of a renewal cycle }} \\
& =\frac{E\left(c_{r} \sum_{j=1}^{N-1} Y_{j}+C-c_{w} \sum_{j=1}^{N} X_{j}\right)}{E\left(\sum_{j=1}^{N-1} Y_{j}+\sum_{j=1}^{N} X_{j}\right)} \\
& =\frac{c_{r} \sum_{j=1}^{N-1} \frac{1}{b^{j-1} \beta}+C-c_{w} \sum_{j=1}^{N} \frac{1}{a^{j-1} \alpha}}{\sum_{j=1}^{N-1} \frac{1}{b^{j-1} \beta}+\sum_{j=1}^{N} \frac{1}{a^{j-1} \alpha}} \tag{24}
\end{align*}
$$

Obviously, we can determine an optimal replacement policy $N^{*}$ by analytical or numerical methods such that $C(N)$ is minimized.

### 5.2 Optimal replacement policy $N^{*}$

In order to determine the optimal replacement policy $N^{*}$ for minimizing $C(N)$ explicitly, we rewrite the equation (24) as

$$
C(N)=A(N)-c_{w}
$$

where

$$
A(N)=\frac{\left(c_{r}+c_{w}\right) \sum_{j=1}^{N-1} \frac{1}{b^{j-1} \beta}+C}{\sum_{j=1}^{N} \frac{1}{a^{j-1} \alpha}+\sum_{j=1}^{N-1} \frac{1}{b^{j-1} \beta}} .
$$

Thus, to minimize $C(N)$ is equivalent to minimize $A(N)$. The difference of $A(N+1)$ and $A(N)$ is given as:

$$
\begin{aligned}
& A(N+1)-A(N)=\frac{\left(c_{r}+c_{w}\right) \sum_{j=1}^{N} \frac{1}{b^{j-1} \beta}+C}{\sum_{j=1}^{N+1} \frac{1}{a^{j-1} \alpha}+\sum_{j=1}^{N} \frac{1}{b^{j-1} \beta}}-\frac{\left(c_{r}+c_{w}\right) \sum_{j=1}^{N-1} \frac{1}{b^{j-1} \beta}+C}{\sum_{j=1}^{N} \frac{1}{a^{j-1} \alpha}+\sum_{j=1}^{N-1} \frac{1}{b^{i-1} \beta}} \\
& =\frac{\frac{c_{r}+c_{w}}{b^{N-1} \beta} \sum_{j=1}^{N} b^{j-1}+C}{\frac{1}{a^{N} \alpha} \sum_{j=1}^{N+1} a^{j-1}+\frac{1}{b^{N-1} \beta} \sum_{j=1}^{N} b^{j-1}}-\frac{\frac{c_{r}+c_{w}}{b^{N-2} \beta} \sum_{j=1}^{N-1} b^{j-1}+C}{\frac{1}{a^{N-1} \alpha} \sum_{j=1}^{N} a^{j-1}+\frac{1}{b^{N-2} \beta} \sum_{j=1}^{N-1} b^{j-1}} \\
& =\frac{\left(c_{r}+c_{w}\right) h(N)-C\left(a^{N} \alpha+b^{N-1} \beta\right)}{a^{N} b^{N-1} \alpha \beta\left[\frac{1}{a^{N} \alpha} \sum_{j=1}^{N+1} a^{j-1}+\frac{1}{b^{N-1} \beta} \sum_{j=1}^{N} b^{j-1}\right]\left[\frac{1}{a^{N-1} \alpha} \sum_{j=1}^{N} a^{j-1}+\frac{1}{b^{N-2} \beta} \sum_{j=1}^{N-1} b^{j-1}\right]},
\end{aligned}
$$

where $h(N)=\sum_{j=1}^{N} a^{j}-\sum_{j=1}^{N-1} b^{j}$.
We now structure an auxiliary function

$$
\begin{equation*}
B(N)=\frac{\left(c_{r}+c_{w}\right) h(N)}{C\left(a^{N} \alpha+b^{N-1} \beta\right)} \tag{25}
\end{equation*}
$$

Because the denominator of $A(N+1)-A(N)$ is always positive, the sign of $A(N+1)-$ $A(N)$ is the same as the sign of its numerator. Thus, the following lemma is straightforward.

## Lemma 3

$$
A(N+1) \underset{<}{\stackrel{\geq}{<}} A(N) \Longleftrightarrow B(N) \frac{\geq}{<} 1 .
$$

Lemma 1 shows that the monotonicity of $A(N)$ is determined by the value of $B(N)$. We can simplify the difference of $B(N+1)$ and $B(N)$ as follows.

$$
\begin{aligned}
& B(N+1)-B(N)=\frac{\left(c_{r}+c_{w}\right) h(N+1)}{C\left(a^{N+1} \alpha+b^{N} \beta\right)}-\frac{\left(c_{r}+c_{w}\right) h(N)}{C\left(a^{N} \alpha+b^{N-1} \beta\right)} \\
& =\frac{c_{r}+c_{w}}{C}\left(\frac{h(N+1)\left(a^{N} \alpha+b^{N-1} \beta\right)-h(N)\left(a^{N+1} \alpha+b^{N} \beta\right)}{\left(a^{N+1} \alpha+b^{N} \beta\right)\left(a^{N} \alpha+b^{N-1} \beta\right)}\right) \\
& =\frac{c_{r}+c_{w}}{C}\left(\frac{a^{N} \alpha[h(N+1)-a h(N)]+b^{N-1} \beta[h(N+1)-b h(N)]}{\left(a^{N+1} \alpha+b^{N} \beta\right)\left(a^{N} \alpha+b^{N-1} \beta\right)}\right),
\end{aligned}
$$

where
$h(N+1)-a h(N)=\left(\sum_{j=1}^{N+1} a^{j}-\sum_{j=1}^{N} b^{j}\right)-a\left(\sum_{j=1}^{N} a^{j}-\sum_{j=1}^{N-1} b^{j}\right)=\left(a-b^{N}\right)+(a-1) \sum_{j=1}^{N-1} b^{j} \geq 0$,
$h(N+1)-b h(N)=\left(\sum_{j=1}^{N+1} a^{j}-\sum_{j=1}^{N} b^{j}\right)-b\left(\sum_{j=1}^{N} a^{j}-\sum_{j=1}^{N-1} b^{j}\right)=(1-b) \sum_{j=1}^{N} a^{j}+\left(a^{N+1}-b\right) \geq 0$.
Thus, $B(N+1)-B(N) \geq 0$, this implies:
Lemma $4 B(N)$ is nondecreasing in $N$.

According to Lemmas 3 and 4, an analytic expression for an optimal policy for minimizing $A(N)$ can be obtained. The following theorem can be obtained.

Theorem 8 The optimal replacement policy $N^{*}$ can be determined by

$$
\begin{equation*}
N^{*}=\min \{N \mid B(N) \geq 1\} \tag{26}
\end{equation*}
$$

Furthermore, if $B\left(N^{*}\right)>1$, then the optimal policy $N^{*}$ is unique.
Because $B(N)$ is nondecreasing in $N$, there exists an integer $N^{*}$ such that

$$
B(N) \geq 1 \Longleftrightarrow N \geq N^{*}
$$

and

$$
B(N)<1 \Longleftrightarrow N<N^{*}
$$

Note that $N^{*}$ is the minimum satisfying (26), and the policy $N^{*}$ is an optimal replacement policy. Furthermore, it is easy to see that if $B\left(N^{*}\right)>1$, then the optimal policy is also uniquely existent.

### 5.3 A numerical example for policy $N$

In this section, we provide a numerical example to illustrate the optimal replacement policy $N^{*}$ for minimizing $C(N)$. Now, let

$$
l_{1}=\sum_{j=1}^{N} \frac{1}{a^{j-1}}, l_{2}=\sum_{j=1}^{N-1} \frac{1}{b^{j-1}}, l_{3}=\sum_{j=1}^{N} a^{j}, l_{4}=\sum_{j=1}^{N-1} b^{j},
$$

then equations (24) and (25) become respectively

$$
\begin{equation*}
C(N)=\frac{\frac{c_{r}}{\beta} l_{2}+C-\frac{c_{w}}{\alpha} l_{1}}{\frac{l_{1}}{\alpha}+\frac{l_{2}}{\beta}} \tag{27}
\end{equation*}
$$

and

$$
\begin{equation*}
B(N)=\frac{\left(c_{r}+c_{w}\right)\left(l_{3}-l_{4}\right)}{C\left(a^{N} \alpha+b^{N-1} \beta\right)} \tag{28}
\end{equation*}
$$

Further let $a=1.15, b=0.85, \alpha=0.02, \beta=1, c_{r}=15, c_{w}=60$ and $C=4000$. Substituting the above values into equations (27) and (28), we can respectively obtain the results presented in Figure 1 and Table 1.
It is easy to find that $C(10)=-42.3998$ is the minimum of the average cost rate of the repair-equipment. In other words, the optimal policy is $N^{*}=10$ and we should replace the repair-equipment at the time of the 10th failure. And the optimal policy $N=10$ is unique from Figure 1, Table 1 or the conclusion of Theorem 8 because $B(10)=1.1396>$ 1.

Table 1: Results obtained from Equations (27) and (28)

| $\mathbf{N}$ | $\mathbf{C}(\mathbf{N})$ | $\mathbf{B}(\mathbf{N})$ | $\mathbf{N}$ | $\mathbf{C}(\mathbf{N})$ | $\mathbf{B}(\mathbf{N})$ | $\mathbf{N}$ | $\mathbf{C}(\mathbf{N})$ | $\mathbf{B}(\mathbf{N})$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 20.0000 | 0.0211 | 11 | -42.3063 | 1.5166 | 21 | -31.1221 | 5.9243 |
| 2 | -16.8684 | 0.0347 | 12 | -42.0093 | 1.9569 | 22 | -29.0294 | 6.1500 |
| 3 | -28.8058 | 0.0603 | 13 | -41.5236 | 2.4485 | 23 | -26.7891 | 6.3349 |
| 4 | -34.5588 | 0.1027 | 14 | -40.8560 | 2.9723 | 24 | -24.4224 | 6.4856 |
| 5 | -37.8255 | 0.1682 | 15 | -40.0090 | 3.5050 | 25 | -21.9552 | 6.6080 |
| 6 | -39.8282 | 0.2646 | 16 | -38.9820 | 4.0234 | 26 | -19.4178 | 6.7074 |
| 7 | -41.0853 | 0.4007 | 17 | -37.7733 | 4.5075 | 27 | -16.8432 | 6.7882 |
| 8 | -41.8512 | 0.5862 | 18 | -36.3815 | 4.9439 | 28 | -14.2662 | 6.8541 |
| 9 | -42.2633 | 0.8302 | 19 | -34.8067 | 5.3255 | 29 | -11.7212 | 6.9080 |
| $\mathbf{1 0}$ | $\mathbf{- 4 2 . 3 9 9 8}$ | $\mathbf{1 . 1 3 9 6}$ | 20 | -33.0515 | 5.6513 | 30 | -9.2408 | 6.9523 |

## 6 Concluding remarks

In this paper, the reliability and replacement policy of a $k / n(F)$ system with a repairable repair-equipment are conducted. The following findings are achieved.
(1) According to the model assumptions, we have indicated that the $k / n(F)$ system with a repairable repair-equipment is equivalent to a $M / M(M / M) / 1 / k / n$ queueing system with repairable service station. By using the queueing theory we derived properties and reliability indices of the $k / n(F)$ system on the basis of the concept of busy period for classical $M / M / 1$ queueing system. Hence, the work in this paper is a generalization of the existing work.
(2) Although the geometric process has been wildly applied to the maintenance problem for the simple repairable system and the multi-component series, parallel and cold standby repairable systems, this is the first work to apply the geometric process to a $k / n(F)$ system with a repairable repair-equipment.
(3) Let $N(t)$ be the state of the $k / n(F)$ system with a repairable repair-equipment at time $t$. It is clear from model assumptions that $\{N(t), t \geq 0\}$ is not a Markov process. However, it can be extended to be a vector Markov process (i.e. a two-dimensional Markov process) by introducing a supplementary variable. To obtain properties and reliability indices, we need to determine the state probabilities of the system at time $t$. Accordingly, we can derive the system of differential equations about $p_{m l_{w}}(t),(m=$ $0,1, \cdots, k-1 ; l=1,2, \cdots)$ and $p_{m l_{f}}(t),(m=1,2, \cdots, k-1, k ; l=1,2, \cdots)$. Finally,
the Laplace transform results of the system reliability indices are obtained. In general, conducting an inverse Laplace transformation to obtain transient results of reliability indices is not easy, and results from Laplace transformation of reliability indices of the system are hard to obtain for practical application. Thus, for practical use, a numerical method based on the Runge-Kutta method is often adopted (see, e.g., Zhang and Wang [28]).
(4) In this paper, we consider a replacement policy $N$ based on the number of failures of the repairable repair-equipment. An optimal replacement policy $N^{*}$ for minimizing $C(N)$ is determined. The uniqueness of the optimal replacement policy $N^{*}$ is proved. And a given numerical example can also illustrate the theoretical result. Theorem 8 can be used in practice as one can stop searching the optimum whenever $B(N)$ crosses over 1.
(5) Our future work will be to conduct research for the situation where all components in the system are not "as good as new" or there are $r(r>1)$ repairable repair-equipment.

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