

Nonparametric identification of an interdependent value model with buyer covariates from first-price auction bids

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Abstract

This paper introduces a version of the interdependent value model of Milgrom and Weber (1982), where the signals are given by an index gathering signal shifters observed by the econometrician and private ones specific to each bidders. The model primitives are shown to be nonparametrically identified from first-price auction bids under a testable mild rank condition. Identification holds for all possible signal values. This allows to consider a wide range of counterfactuals where this is important, as expected revenue in second-price auction. An estimation procedure is briefly discussed.

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1 Introduction

Most nonparametric identification results or empirical studies for first-price auctions consider the private value case. See for instance the review papers of Athey and Haile (2007) or Hendricks and Porter (2007). This is probably due to the non identification result of Laffont and Vuong (1996), which states that bids generated by interdependent values are also rationalized by private values. This negative result has not prevented empirical work for the interdependent case. In particular, Hendricks, Porter and Wilson (1994) consider an asymmetric common value model for drainage tracts, where an informed bidder bids for a neighbor tract and competes with non neighbor buyers. Hendricks, Pinkse and Porter (2003) have used *ex post* values observed after the auction to test rational bidding in a common value framework. They consider an application to wild cat leases, where bidders can commission seismic studies to evaluate the quantity of petrol or gas in the tracts. Shneyerov (2006) has shown that the seller expected revenue in a first or second price auction can still be identified. His results are applied to municipal bonds, which values are determined after the auction, when sold to some final investors. Paarsch (1992), Haile, Hong and Shum (2003) and Compiani, Haile and Sant’Anna (2018) propose to test whether bids are generated by a common or a private value model. Hong and Shum (2002) restore identification using a parametric common value model. Aradillas-López, Gandhi and Quint (2013) use a set identification approach in the more restrictive framework of correlated private values.

These papers fall in the interdependent value framework, where each bidder has a possibly unknown value V_i and observes a univariate private signal X_i , $i = 1, \dots, n$. The parameters of interest are the joint signal distribution and the *valuation* or *value functions*

$$\Phi_i(X_1, \dots, X_n) = \mathbb{E}[V_i | X_1, \dots, X_n] \tag{1.1}$$

which are sufficient to compute most counterfactuals. In the private value case, the valuation only depends upon the bidder’s signal. By contrast, in the interdependent case, the value of a given bidder can depend upon the signals of other bidders, creating so a network of interactions which is difficult to identify from first-price auction bids without further

restrictions.

In the symmetric case, Laffont and Vuong (1996) show that the bids only identify

$$\mathbf{V}_i(x, x) = \mathbb{E} \left[V_i \left| X_i = x, \max_{1 \leq j \neq i \leq n} X_j = x \right. \right].$$

In particular, the “pseudo” private values $\mathbf{V}_i = \mathbf{V}_i(X_i, X_i)$ generate equilibrium bids which are observationally equivalent to the initial ones. As the private values \mathbf{V}_i are independent and identically distributed (i.i.d) when the signals X_i ’s are, it would be tempting to expect that revenue equivalence results valid under the symmetric independent private value paradigm extends to symmetric interdependent values. This is however misusing the observational equivalence results of Laffont and Vuong (1996) by ignoring bidder valuation dependence. In particular, it is known that ascending auctions, during which bidders can learn about their opponent’s signals, generates a higher expected seller revenue than first-price auction. The optimal reserve price computed from the distribution of the pseudo private values \mathbf{V}_i is also unlikely to be identical with the one taking into account bidder’s interdependence. As the valuation functions are typically positively correlated, so will be the bidder’s participation decisions, suggesting the seller faces a higher risk of non participation under interdependent value than for independent private ones. Recovering the function $\Phi_i(\cdot)$ in (1.1) and the signal distribution is therefore important from an auction design perspective.

Functional restrictions have been used to restore identification within a symmetric framework. Hong and Shum (2002) have shown that a Gaussian Wilson model is identified. Li, Perrigne and Vuong (2000) consider an extension of the Wilson model where $V_i = V$ for all i , the signals satisfy $X_i = V\varepsilon_i$. They assume that, for some unknown parameter (θ_0, θ_1) , $\mathbf{V}_i(x, x) = \theta_0 x^{\theta_1}$ for identification and estimation purposes. Février (2008) relaxes the latter assumption and shows identification when the conditional support of X_i given the common value depends upon V . He (2015) considers $\Phi_i(x_1, \dots, x_n) = \bar{x}$ for all i .

Alternatively, observable asymmetries generated by bidder specific variables can be used to obtain identification with such restrictions on $\Phi_i(\cdot)$ or $\mathbf{V}_i(\cdot)$. Somaini (2018) considers a valuation exclusion restriction, under which bidder i valuation only depends upon a bidder specific shifter Z_i , which is observed by all bidders and the econometrician. This is sufficient

to obtain identification for additive valuation function. The present paper explores another route, focusing on the signal, which is now supposed to be partly observable by all bidders and the econometrician. More specifically, all the signals X_j appearing in (1.1) can be decomposed into a D dimensional common knowledge “signal shifter” Z_j and a private vector component $\gamma_{ij}(A_j)$, where A_j is normalized to have a uniform distribution. These two components are combined using a linear index structure, $X_j = Z_j' \gamma_{ij}(A_j)$.¹ In the latter expression, $\gamma_{ij}(\cdot)$ is a common knowledge slope function which may depend upon the identity of the considered bidder. If so, $\gamma_{ij}(\cdot)$ incorporates a specific bidder i fixed effect, or can be viewed as bidder i belief about the slope $\gamma_{jj}(\cdot)$ of bidder j .

The common knowledge variable Z can indicate better information or a higher value.² For instance, Somaini (2018) considers the bidder distance to the place where works of the auctioned contract has to be performed, which inverse can be both an indicator of increasing information or lower cost. Bidder capacity constraints can also affect the value of an auctioned contract. Length of common tract borders can be used as a measure of information strength in the application of Hendricks et al. (1994.) The cost paid by bidders to acquire information on a gas or oil contents on an auctioned lease, as described in Hendricks, Pinske and Porter (2003), can also be used if common knowledge. Bidder reputation and experience, measured for instance by time spent in activities related with the auctioned good can again indicate a better information or a higher ability to process it for resale.

The variations of the continuous Z_j 's are used to identify the function $\Phi_i(\cdot)$ in (1.1) and the slope functions $\gamma_{ij}(\cdot)$, $j = 1, \dots, n$, from the bids observed in a first-price auction. The joint distribution of the private signals is also identified assuming that a low signal does

¹ The index structure is general enough to include sieve approximation of a signal function $x_{ij}(z_j, A_j)$, provided $Z_j = [b_1(z_j), \dots, b_D(z_j)]$ for a sieve $\{b_d(\cdot)\}_{d=1}^\infty$ and D growing with the sample size. Such extension is however out of the scope of the present paper.

²Variation of the common knowledge slope functions $\gamma_{ij}(\cdot)$ across i can also indicate a stronger bidder due to an unobserved variable which stay constant across the sample, or a fixed effect. For instance, each bidder collection of $\gamma_{ij}(\cdot)$, $j = 1, \dots, n$ may take the two distinct values $\underline{\gamma}_i(\cdot) \leq \bar{\gamma}_j(\cdot)$, $j = 1, \dots, n$ indicating a weak or a strong bidder.

not prevent bidding and that bids increase with signal. Hence this interdependent value model is fully identified and can be used for most usual counterfactual exercises. As our nonparametric identification result uses local variation at given small value of the Z_j 's, the model is overidentified and can therefore be tested.

Athey and Haile (2002) have similarly considered good covariate variations for ascending auctions with dependent private values. The nonparametric identification result stated in Athey and Haile (2002, Theorem 5) relies on order statistic properties that are not relevant here. The harder parameters to identify are the slope functions $\gamma_{ij}(\cdot)$. In the two bidder case, identification is obtained by differentiating with respect to the signal A_i and to the covariate Z_j . This gives a system of differential equations with a unique solution, identifying so the slope functions. Similar identification procedure, based on uniqueness of the solution of a differential equation, can be traced back to Elbers and Ridder (1982) in the context of duration models, see also Abbring and van der Berg (2003). The case where three bidders or more attend the auction is more involved but proceeds similarly: differentiating with respect to the signal and covariate gives an integro-differential system, but it is shown that it also identifies the slope functions.

The rest of the paper is organized as follows. The next section introduces our interdependent value models and three illustrative examples. Section 3 presents our main nonparametric identification results. Section 4 discusses a possible two stage estimation procedure. Section 5 concludes the paper and proofs are grouped in Section 6.

2 Model, examples and assumptions

A single and indivisible object is sold to a known number $n \geq 2$ of buyers using a first-price auction. There is no reserve price and the seller accepts all nonnegative bids. The observations consist on the bidder identities, bids B_j and the signal shifters Z_j , $j = 1, \dots, n$ where n is the total number of buyers. The next Section describes the model and bidding strategies, and gives our key identification assumptions. The framework focuses on a particular bidder,

say bidder i , which valuation function, or value, is a parameter of interest together with the joint signal distribution introduced below.

2.1 Valuation function and examples

Buyers asymmetry is common knowledge and driven by individual D dimensional variables Z_j . Prior bidding, each buyers receive a private signal A_i . The joint distribution of the signals $A = (A_1, \dots, A_n)$ given $Z = (Z_1, \dots, Z_n)$ is known to the buyers but not to the analyst. The marginal distribution of each A_i is normalized to be uniform over $[0, 1]$. The valuation function of buyer i is

$$V_i(A; Z) = \Phi_i [Z'_1 \gamma_{i1}(A_1), \dots, Z'_n \gamma_{in}(A_n)] = \Phi_i [Z, \Gamma_i(A)], \quad (2.2)$$

$i = 1, \dots, n$, where $\Phi_i(\cdot)$ and $\Gamma_i(A) = (\gamma_{i1}(A_1), \dots, \gamma_{in}(A_n))$ are unknown parameters of interest.³ In this specification, the index $Z'_j \gamma_{ij}(A_j)$ can be viewed as a *mixed signal* combining observable and unobservable components, and replaces the signal X_i from (1.1). The function Φ_i combines these signals and reveals the interactions of the other bidders with i , in terms of value. Examples are as follows, for which $\Gamma_i(\cdot) = \Gamma(\cdot)$ is common to buyers.

- **Additive valuation model.** Bidder j observes a component $Z'_j \gamma_j(A_j)$ of the total valuation of the auctioned good, which is weighted with a weight π_{ij} by bidder i in her value function

$$V_i(A; Z) = \sum_{j=1}^n \pi_{ij} Z'_j \gamma_j(A_j) \text{ with } \pi_{ij} \geq 0$$

in which case $\Phi_i(x_1, \dots, x_n) = \sum_{j=1}^n \pi_{ij} x_j$. He (2015) obtains identification in the symmetric case $V_i(A; Z) = \sum_{j=1}^n \gamma(A_j) / n$, but asymmetric specifications can be more relevant for applications. For instance the auctioned good can be a piece of land expected to contain some resources, as in mineral rights auctions. In this type of auction,

³This specification can easily be extended to allow for an auction specific variable Z_0 , ie $V_i(A; Z, Z_0) = \Phi_i [Z'_1 \gamma_{i1}(A_1|Z_0), \dots, Z'_n \gamma_{in}(A_n|Z_0)|Z_0]$, by conditioning on Z_0 . Identification of this model follows from applications, for each value of Z_0 , of Theorems 3 and 4 below.

bidders exploit similar lots which can be adjacent or have similar characteristics to the auctioned one, a observable information that can be recorded in Z . The signal A_i is private to bidder i , being for instance the outcomes of her lot. A π_{ij} set to 0 may indicate that bidders i and j would use the lot for different purposes, so that information of i is not relevant for j and vice versa.

- **A simplified auction with resale.** Suppose each bidder is tied with a final buyer to whom he can sell for sure the good at a price $\pi_{ii}Z'_i\gamma_i(A_i)$ if she wins the auction. After the auction, the winner can sell the good to the other final buyers at a price $\pi_{ij}Z'_j\gamma_j(A_j)$. This gives the value functions

$$V_i(A; Z) = \max_{i=1, \dots, n} \{ \pi_{ij}Z'_j\gamma_j(A_j) \}$$

in which case $\Phi_i(x_1, \dots, x_n) = \max_{i=1, \dots, n} \{ \pi_{ij}x_i \}$.

- **A non-Gaussian and asymmetric Wilson model.** Suppose the value V of the good is not observed by the buyers, who receive instead a noisy signal which accuracy is bidder specific and common knowledge. A possible parameter of interest is the quantile function $\gamma_0(\cdot)$ of V . Hence for a uniform A_0 , $V = \gamma_0(A_0)$, which can also be written as

$$V = \gamma_0(F(\nu))$$

where ν is a standard normal and $F(\cdot)$ its cdf. In the standard Wilson model, the value is normal, ie $V = \nu$ up to a scale parameter, and assuming that the distribution of V is unknown introduces additional complications. The signal structure resembles the standard Wilson model, the signal of bidder i with observed accuracy σ_i for ν being

$$\nu_i = \nu + \sigma_i\varepsilon_i$$

with independent $\nu, \varepsilon_1, \dots, \varepsilon_n$ drawn from the standard normal distribution. Note that the information carried by the signal ν_i is equivalent to the uniform signal

$$A_i = F\left(\frac{\nu_i}{\sqrt{1 + \sigma_i^2}}\right)$$

It follows that the distribution of ν given A_1, \dots, A_n is

$$\mathcal{N}\left(\frac{\sum_{i=1}^n \frac{\nu_i}{\sigma_i^2}}{1 + \sum_{i=1}^n \frac{1}{\sigma_i^2}}, \frac{1}{1 + \sum_{i=1}^n \frac{1}{\sigma_i^2}}\right) = \mathcal{N}\left(\frac{\sum_{i=1}^n \frac{\sqrt{1+\sigma_i^2}}{\sigma_i^2} F^{-1}(A_i)}{1 + \sum_{i=1}^n \frac{1}{\sigma_i^2}}, \frac{1}{1 + \sum_{i=1}^n \frac{1}{\sigma_i^2}}\right)$$

Set $Z_i = \frac{\sqrt{1+\sigma_i^2}}{\sigma_i^2}$, which gives $\frac{1}{\sigma_i^2} = (Z_i^2 + \frac{1}{4})^{1/2} - \frac{1}{2}$, so that a large Z_i means a small signal variance σ_i^2 . The value function $V(A; Z) = \mathbb{E}[V | A, Z]$ is identical across buyers and satisfies, for $\Sigma^2(Z) = 1 + \sum_{i=1}^n \frac{1}{\sigma_i^2}$,

$$\begin{aligned} V(A; Z) &= \frac{1}{\sqrt{2\pi}} \int \gamma_0\left(\frac{\sum_{i=1}^n Z_i F^{-1}(A_i)}{\Sigma^2(Z)} + \Sigma(Z)t\right) \exp\left(-\frac{t^2}{2}\right) dt \\ &= \Psi\left(\sum_{i=1}^n Z_i F^{-1}(A_i), \Sigma(Z)\right) \end{aligned}$$

which, conditionally on $\Sigma(Z)$, falls in the considered framework. Note that, for $Z_j = \infty$, the variance σ_j vanishes so that bidder j knows the value V . Little algebra then gives that

$$\lim_{Z_i \rightarrow +\infty} V(A; Z) = \gamma_0(A_i), \text{ for any } i = 1, \dots, n, \quad (2.3)$$

showing that the quantile function $\gamma_0(\cdot)$ is identified from the value function under a large support assumption for the bidder covariate.

As detailed below, the revisited Wilson model is easier to identify than the other Examples, due to the possibility of perfect information. We now detail our main Assumptions for the value specification. In the sequel, we shall focus on the identification of buyer i valuation function. Let \mathcal{I} be the set of active signals, that is the signal affecting the valuation of bidder i , or in other words, the smallest subset of $\{1, \dots, n\}$ such that

$$\Phi_i(x_1, \dots, x_n) = \Phi_i[x_j, j \in \mathcal{I}]. \quad (2.4)$$

Assumption Z. *The variable $Z = (Z_1, \dots, Z_n)$ has support $\mathbb{R}_{+*}^D \times \dots \times \mathbb{R}_{+*}^D = \mathcal{Z}$.*

Assumption A. *The buyer signal A_j is uniform over $[0, 1]$ given Z , $j = 1, \dots, n$. The joint p.d.f $c(\cdot|Z)$ of $A = (A_1, \dots, A_n)$ given Z is strictly positive and continuously differentiable with respect to the signal and the covariate.*

Assumption G. *The slope $\gamma_{ij}(\cdot)$ are continuously differentiable over $[0, 1]$ with non-negative and nondecreasing entries, at least one being strictly increasing. In addition, one of the following terminal and initial conditions holds: (i) $\gamma_{ij}(1) \neq 0$ for all j in \mathcal{I} or (ii) $\gamma_{ij}(0) \neq 0$ for all j in \mathcal{I}*

Assumption P. *The set \mathcal{I} is not empty. The function $\Phi_i(x_1, \dots, x_n)$ maps \mathbb{R}_+^n into \mathbb{R}_{+*} and is twice continuously differentiable with partial derivatives $\frac{\partial \Phi_i(\cdot)}{\partial x_j} > 0$ over \mathbb{R}_+^n for all j in \mathcal{I} .*

Assumption Z imposes signal shifter linear independence and rules out discrete entries to allow differentiation. Constant entries are also ruled out as it can cause identification loss as in Laffont and Vuong (1996). That the entries of Z can be unbounded is a simplifying assumption that can be weakened, but allows here to identify $\Phi_1(\cdot)$ over its unbounded definition domain. That the vector Z can go to 0 is used to identify the initial or terminal values of the $\gamma_{ij}(\cdot)$'s later on.

Assumption A includes a standard normalization of the conditional signal distribution, which are assumed to be uniform. This permits the use of the quantile approach of Gimenes and Guerre (2019), see Lemma 1 below. Note however that the signal vector (A_1, \dots, A_n) can depend upon Z .

Assumption G imposes smooth and bounded mixed signals $Z'_j \gamma_{ij}(\cdot)$.⁴ The terminal slope condition G-(i) will be used when $n = 2$, while the initial one G-(ii), which implies G-(i) when the slope entries are strictly increasing, is used for $n = 3$. Assumption P requests a valuation function which is strictly increasing with respect to its argument and smooth.

⁴Assumption G rules out the revisited Wilson model example, for which $\gamma_{ji}(\cdot)$ is infinite at 0 or 1. But Assumption G is only needed to identify the unknown $\gamma_{ji}(\cdot)$, and therefore not for this example since its $\gamma_{ij}(\cdot)$ are known.

Assumptions G and P together imply that the value function $V_i(A; Z)$ increases with each private signal A_j , as assumed in Milgrom and Weber (1982). In the sequel, we shall focus on the identification of buyer i valuation function, or equivalently of the pair $[\Phi_i(\cdot), \Gamma_i(\cdot)]$ up to a scaling normalization, as $[\Phi_i(\cdot/\lambda), \lambda\Gamma_i(\cdot)]$ gives the same valuation function for all $\lambda > 0$. A convenient normalization used in the proofs of the main results is

$$\frac{\partial \Phi_i(0, \dots, 0)}{\partial x_j} = 1 \text{ for all } j \text{ in } \mathcal{I}. \quad (2.5)$$

2.2 Bidding strategies

Our identification results are based on high level bidding assumptions inspired by the Bayesian Nash Equilibrium framework. It is assumed that bids depend upon Z and bidder private signals

$$B_j = s_j(A_j; Z) > 0, \quad j = 1, \dots, n, \quad Z \in \mathcal{Z}.$$

In what follows, $\varphi^{(1)}(\cdot; z)$ is the partial derivative $\varphi^{(1)}(\alpha; z) = \frac{\partial}{\partial \alpha} \varphi(\alpha; z)$ with respect to the quantile level.

Assumption S. *For each Z in \mathcal{Z} (i) the bidding strategy $s_i(\cdot; Z)$ satisfies the best response condition*

$$s_i(\alpha; Z) \in \arg \max_{b > 0} \mathbb{E} \left[(V_i(A; Z) - b) \mathbb{I} \left\{ b \geq \max_{1 \leq j \neq i \leq n} B_j \right\} \mid A_i = \alpha, Z \right]. \quad (2.6)$$

(ii) The initial condition $s_1(0; Z) = \dots = s_n(0; Z)$ holds. (iii) The terminal condition $s_1(1; Z) = \dots = s_n(1; Z)$ holds. (iv) For each $j = 1, \dots, n$, $s_j(\cdot; Z)$ is twice continuously differentiable with $s_j^{(1)}(\cdot; Z) > 0$ over $[0, 1]$.

As in the preceding section, the focus is on identification of the valuation function of bidder i , so that the best response condition (2.6) in Assumption S-(i) only concerns this specific bidder: the other bidders do not need to use a best response bidding strategy. Note however that, apart the initial condition of S-(ii), most of Assumption S is inspired by the Bayesian Nash Equilibrium framework where all the bidders use a best response bidding strategy.

Assumption S-(iv) is used in particular for the joint signal distribution, see Lemma 1, together with S-(ii,iii) to get its identification over the whole support $[0, 1]^n$. The monotonicity condition in S-(iv) is standard in the Econometrics of auctions when assuming bids from the Bayesian Nash Equilibrium. For affiliated signal and valuation functions $V_i(A; Z)$ increasing with respect to each signals, Reny and Zamir (2004) have established existence, but not uniqueness, of a Bayesian Nash equilibrium with increasing bidding strategies. In the two bidder case, Lizzeri and Persico (2000, Appendix) have studied uniqueness, strict monotonicity and smoothness of the optimal bidding strategies as in S-(iv). But these assumptions may not hold for bids not generated by a Bayesian Nash equilibrium. Discontinuities in the strategy $s_j(\cdot|Z)$ should generate flat parts in the cumulative distribution function of B_j or discontinuities for its pdf. A non monotonic but differentiable $s_j(\cdot|Z)$ can lead to a diverging pdf, so that both are in principle testable.

The common terminal condition in Assumption S-(iii) is from Lizzeri and Persico (2000), who established it in the two bidder case under the Bayesian Nash Equilibrium framework. Intuitively, if a group of bidders have a common terminal bid larger than their opponents, they can increase their profit by slightly decreasing their terminal bids and still be sure to win the auction. Hence all the bidders should have the same $s_j(1; Z)$ as assumed in S-(iii). This condition can be tested in principle, because if S-(iii) does not hold for a given Z , there is a dominated bidder, say i_0 , with bid support upper bound $\bar{b}_0(Z)$ such that $\mathbb{P}(B_{i_0} \leq \bar{b}_0(Z) | Z) = 1$ and $\mathbb{P}(\max_{1 \leq i \leq n} B_i > \bar{b}_0(Z) | Z) > 0$.

The initial condition in Assumption S-(ii) does not necessarily hold in the Bayesian Nash Equilibrium framework, especially with asymmetric bidders. It ensures that there is no bidder who would lose the auction with probability 1 given a too low signal value. As a consequence, the best-response characterization (2.6) of the bidding strategy implies the first order condition (3.4) in Lemma 2 below, which is key for identification. Another important econometric role of the initial condition S-(ii) together with the terminal one S-(iii) is to allow for identification of the slope functions $\gamma_{ij}(\cdot)$ over the whole quantile interval $[0, 1]$, therefore avoiding censoring. As Assumption S-(iii), Assumption S-(ii) is in principle testable.

Strategy common initial condition and Bayesian Nash equilibrium. For bids from Bayesian Nash equilibrium, additional restrictions may be needed to ensure that the common initial condition S-(ii) holds, as discussed now. Assumption S-(ii) typically fails when the initial valuations $V_i(0; Z)$ differ across bidders. If the $V_i(0; Z)$ are identical, say equal to $V(0; Z)$, it must hold for all i $s_i(0; Z) = V(0; Z)$ under Assumption S-(iv).⁵ Hence Assumption S-(ii) holds if

$$V(0; Z) = \Phi_1(Z'_1\gamma_{11}(0), \dots, Z'_n\gamma_{1n}(0)) = \dots = \Phi_n(Z'_1\gamma_{n1}(0), \dots, Z'_n\gamma_{nn}(0)). \quad (2.7)$$

Assuming, for the sake of simplicity, that the set \mathcal{I} of all bidders is $\{1, \dots, n\}$ and the normalization (2.5), (2.7) holds when $\gamma_{j1}(0) = \dots = \gamma_{jn}(0)$ for all j and, if these slope do not vanish, $\Phi_1(\cdot) = \dots = \Phi_n(\cdot)$. So a sufficient condition for Assumption S-(ii) is the following:

Condition BNE. *One of the two restrictions holds:*

- (i). *Common initial value:* $\Phi_1(0, \dots, 0) = \dots = \Phi_n(0, \dots, 0)$ and $\gamma_{ij}(0) = 0$ for all $i, j = 1, \dots, n$;
- (ii). *Common $\Phi_i(\cdot)$ and initial slope:* $\Phi_i(x_1, \dots, x_n) = \Phi(x_1, \dots, x_n)$ and $(\gamma_{i1}(0), \dots, \gamma_{in}(0)) = (\gamma_1(0), \dots, \gamma_n(0))$ for all i .

⁵To see this, let $\underline{\alpha}_i(Z) = \inf \{\alpha \in [0, 1]; \mathbb{P}(s_i(A_i; Z) \text{ wins and } A_i \geq \alpha | Z) > 0\}$ be the signal threshold above which bidder i has a non trivial probability to win the auction. Under Assumption S-(iv), it must hold that $s_1(\underline{\alpha}_1(Z); Z) = \dots = s_n(\underline{\alpha}_n(Z); Z)$. Arguing as for (3.5), (3.6) and (3.4) give

$$s_j(\underline{\alpha}_j(Z); Z) = \Phi_j [Z'_1\gamma_{j1}(\underline{\alpha}_1(Z)), \dots, Z'_n\gamma_{jn}(\underline{\alpha}_n(Z))]$$

which is strictly larger than the common $V(0; Z)$ if one of the $\underline{\alpha}_i(Z)$ is strictly larger than 0 by Assumptions G and P. Suppose now that one of $\underline{\alpha}_i(Z)$ is strictly larger than 0, say $\underline{\alpha}_1(Z) > 0$ assuming it is the unique one for the sake of brevity. It follows that bidder $i = 2$ expected profit given $A_2 = \alpha$ is equivalent to, when α goes to 0

$$C\alpha^{n-1} \int_0^{\underline{\alpha}_1} \{\Phi_2 [Z'_1\gamma_{21}(\alpha), Z'_2\gamma_{22}(0), \dots, Z'_n\gamma_{2n}(0)] - \Phi_2 [Z'_1\gamma_{21}(\underline{\alpha}_1(Z)), Z'_2\gamma_{22}(0), \dots, Z'_n\gamma_{2n}(0)]\} d\alpha < 0$$

which is not possible as bidder 2 would achieve a non negative expected profit making a bid close to $V(0; Z)$ when A_2 goes to 0. Hence it must hold that $\underline{\alpha}_1(Z) = 0$.

Condition BNE-(i) allows for more asymmetry, with a set \mathcal{I} that can vary across bidders. The common initial condition holds with $\Phi_i(0) = 0$ in the three examples considered earlier. By contrast, the common $\Phi_i(\cdot)$ condition of BNE-(ii) is more demanding: it holds in the Wilson model examples but requests, in the two first examples, that the weights do not depend upon bidder identity, $\pi_{ij} = \pi_j$. More generally, Condition BNE-(ii) forces the set \mathcal{I} of active bidders to be identical across bidders. Because the slope $\gamma_{ij}(\cdot)$ can be very small, this may nevertheless be flexible enough to mimic any set \mathcal{I} of active signals.

2.3 Rank condition

Our main identification condition is a rank condition stated in Assumption I below. Let

$$G_j(b|Z) = \mathbb{P}(B_j \leq b|Z)$$

be the c.d.f of B_j given Z , $B_j(\alpha|Z) = G_j^{-1}(\alpha|Z)$ be the associated conditional quantile function and set

$$G_j B_i(\alpha|Z) = G_j[B_i(\alpha|Z)|Z].$$

An important consequence of Assumption S-(ii,iii) and Lemma 1-(ii) below, which states that $s_i(\cdot|Z) = B_i(\cdot|Z)$, is that $G_j B_i(0|Z) = 0$ and $G_j B_i(1|Z) = 1$ for all j . Recall that \mathcal{I} is the smallest subset satisfying $\Phi_i(x_1, \dots, x_n) = \Phi_i[x_j, j \in \mathcal{I}]$. Recall $Z'_k = (Z_{1k}, \dots, Z_{Dk})'$ and let $\partial_{Z_k} G_j B_i(\alpha|Z)$ be the gradient column vector

$$\partial_{Z_k} G_j B_i(\alpha|Z) = \left[\frac{\partial G_j B_i(\alpha|Z)}{\partial Z_{1k}}, \dots, \frac{\partial G_j B_i(\alpha|Z)}{\partial Z_{Dk}} \right]'$$

Assumption I. *Let \mathcal{I} be as in (2.4) and suppose $\mathcal{I} \neq \{i\}$. For all j in $\mathcal{I} \setminus \{i\}$, $G_j B_i(\alpha|Z)$ is twice continuously differentiable with respect to (α, Z) in $[0, 1] \times \mathcal{Z}$. For all (α, Z) of $[0, 1] \times \mathcal{Z}$, the $(\text{Card}(\mathcal{I}) - 1) \times (\text{Card}(\mathcal{I}) - 1)$ matrix with typical entries*

$$\frac{Z'_k \partial_{Z_k} G_j B_i(\alpha|Z)}{\alpha(1-\alpha)}, \quad j, k \in \mathcal{I} \setminus \{i\}$$

is full rank.

Assumption I is not binding in the private value case due to the condition $\mathcal{I} \neq \{i\}$. Observe also that, for $\alpha = 0$ and $\alpha = 1$ respectively, $\partial_{Z_k} G_j B_i(\alpha|Z) / \alpha$ and $\partial_{Z_k} G_j B_i(\alpha|Z) / (1 - \alpha)$ stands for the limit $\partial_{Z_k} g_j b_i(\alpha|Z)$. Note that a stronger rank condition than in Assumption I is in principle testable using the whole set of bidders $\{1, \dots, n\}$ instead of the unknown \mathcal{I} , as $Z'_k \partial_{Z_k} G_j B_i(\alpha|Z)$ can be consistently estimated.

The important role played by $G_j B_i(\alpha|Z)$ is better illustrated looking at Lemma 1 below, which shows in particular that the increasing strategy $s_i(\cdot|Z)$ is identical to the bid quantile function $B_i(\cdot|Z)$. If the other bidders j use strictly increasing and continuous strategies $s_j(\cdot|Z)$, then

$$G_j B_i(\alpha|Z) = s_j^{-1}[s_i(\alpha|Z)]$$

which is an indicator of asymmetric bidding. The rank condition in Assumption I fails in particular if $G_j B_i(\alpha|Z) = \alpha$ for all j , which means that the buyers bid using the same symmetric strategy $s(\alpha|Z)$. In such case, the variable Z plays a role similar to a characteristic of the auctioned good. If the bids are drawn from a Bayesian Nash equilibrium, the non-identification argument of Laffont and Vuong (1996) holds, showing that there is a private information value model which is observationally equivalent to the one at hand. The rank condition does not hold if $G_j B_i(\alpha|Z) = C_{ji}(\alpha)$ is independent of Z , which gives that $s_j(\alpha|Z) = s_i[C_{ji}^{-1}(\alpha)|Z]$ for all $j \neq i$ in \mathcal{I} .

3 Main identification results

This section considers first identification of the signal distribution. Section 3.2 then derives the identification implications for the valuation function of the best response condition (2.6) in Assumption S-(i). In particular, the revisited Wilson model is shown to be identified. However, other valuation function models may not be identified for all signal values. As shown in Section 3.3, the mixed signal value function is identified in full generality, which ensures that this specification can be used for counterfactuals that requests to know value functions for all possible signals. The latter includes in particular the computation of an

expected revenue, which involves integration over all possible signals.

3.1 Bidding strategy and signal distribution

The next lemma directly follows from the increasing strategy assumption. Lemma 1-(ii) shows that the bid quantile function is the bid strategy function, while identification of the distribution of the signal vector A given Z follows from (i). Lemma 1-(iii) will be used for identifying the valuation function later on.

Lemma 1 *Suppose Assumptions A and S-(ii,iii,iv) hold. Then*

(i). **[Signal identification]** *For each $j = 1, \dots, n$, the signals A_j satisfy*

$$A_j = G_j (B_j|Z).$$

and are therefore identified, as the conditional signal distribution.

(ii). **[Signal bid function identification]** *For each $j = 1, \dots, n$, the signal bid function satisfies*

$$s_j (\alpha; Z) = B_j (\alpha|Z).$$

(iii). **[Winning probability identification]** *Suppose bidder i bid is $s_i (a; Z)$ while her signal A_i is equal to α . Then the probability $\omega_i (a|\alpha, Z)$ that bidder i wins the auction given $A_i = \alpha$ and Z is identified and is equal to*

$$\omega_i (a|\alpha, Z) = \mathbb{P} \left[B_i (a|Z) > \max_{1 \leq j \neq i \leq n} B_j \mid A_i = \alpha, Z \right]$$

Proof of Lemma 1: see Appendix.

3.2 A preliminary identification result for the valuation function

The next Lemma is an asymmetric version of first-order condition that determines the bidding strategy in Milgrom and Weber (1982), see also Laffont and Vuong (1996), Guerre,

Perrigne and Vuong (2000) and Haile et al. (2003) for econometric applications. A distinctive feature of the quantile approach developed here comes from Lemma 1-(ii), which shows that the bidding strategy $s_i(\cdot; Z)$ is equal to the bid quantile $B_i(\cdot|Z)$ because $s_i(\cdot; Z)$ is strictly increasing and continuous by Assumption S-(iv). It follows that the best response condition (2.6) is equivalent to

$$\alpha = \arg \max_{a \in [0,1]} \mathbb{E} \left[(V_i(A; Z) - B_i(a|Z)) \mathbb{I} \left\{ B_i(a|Z) \geq \max_{1 \leq j \neq i \leq n} B_j \right\} \mid A_i = \alpha, Z \right] \quad (3.1)$$

for all α in $[0, 1]$ under Assumption S. Define

$$\bar{V}_i(a|\alpha, Z) = \mathbb{E} \left[V_i(A; Z) \mathbb{I} \left\{ B_i(a|Z) \geq \max_{1 \leq j \neq i \leq n} B_j \right\} \mid A_i = \alpha, Z \right]. \quad (3.2)$$

Observe that the expected payoff in (3.1) is equal to

$$\bar{V}_i(a|\alpha, Z) - B_i(a|Z) \omega_i(a|\alpha, Z)$$

and that

$$\left\{ B_i(a|Z) \geq \max_{1 \leq j \neq i \leq n} B_j \right\} = \bigcup_{1 \leq j \neq i \leq n} \{A_j \leq G_j[B_i(a|Z)|Z]\}.$$

Since $B_i(\cdot|Z) = s_i(\cdot|Z)$, $G_j(\cdot|Z) = s_j^{-1}(\cdot|Z)$ and because the p.d.f $c(\cdot|Z)$ are continuously differentiable by Assumptions S-(iv) and A respectively, so are $\bar{V}_i(\cdot|\alpha, Z)$ and $\omega_i(\cdot|\alpha, Z)$.

The first-order condition associated with (3.1) therefore implies

$$\left. \frac{\partial \bar{V}_i(a|\alpha, Z)}{\partial a} \right|_{a=\alpha} - B_i(\alpha; Z) \left. \frac{\partial \omega_i(a|\alpha, Z)}{\partial a} \right|_{a=\alpha} - B_i^{(1)}(\alpha; Z) \omega_i(\alpha|\alpha, Z) = 0. \quad (3.3)$$

Define

$$\Omega_i(\alpha|Z) = \frac{\omega_i(\alpha|\alpha, Z)}{\left. \frac{\partial \omega_i(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}}, \quad U_i(\alpha|Z) = \frac{\left. \frac{\partial \bar{V}_i(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}}{\left. \frac{\partial \omega_i(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}}.$$

Rearranging (3.3) gives the next Lemma.

Lemma 2 *Under Assumptions A and S, it holds for each Z of \mathcal{Z} and all α in $[0, 1]$*

$$U_i(\alpha|Z) = B_i(\alpha|Z) + B_i^{(1)}(\alpha|Z) \Omega_i(\alpha|Z) \quad (3.4)$$

and $U_i(\cdot|\cdot)$ is identified.

As $\Omega_i(\cdot|Z)$ is identified by Lemma 1-(iii), Equation (3.4) in Lemma 2 shows that $U_i(\cdot|Z)$ is identified. The merits and limitations of this identification result are now discussed for the two and three bidders general case and for the revisited Wilson model.

3.2.1 Two bidders general case

It is assumed here that the bidder covariate are of dimension 1 and that $V_i(A; Z)$ is a general valuation function. Suppose without loss of generality that $i = 1$. Observe that the p.d.f of A_2 given $A_1 = \alpha$ and Z is $c(\alpha, \cdot|Z)$ as A_1 has a uniform distribution over $[0, 1]$ given Z . Recall that $G_2 B_1(a|Z) = G_2[B_1(a|Z)|Z]$ has a positive derivative $g_2 b_1(a|Z)$ by Lemma 1-(ii) and Assumption S-(iii). This gives for $\bar{V}_1(a|\alpha, Z)$ as in (3.2) and $\omega_1(a|\alpha, Z)$ as in Lemma 1-(iii)

$$\begin{aligned}\bar{V}_1(a|\alpha, Z) &= \int_0^1 V_1(\alpha, t; Z) \mathbb{I}[B_1(a|Z) \geq B_2(t|Z)] c(\alpha, t|Z) dt \\ &= \int_0^{G_2 B_1(a|Z)} V_1(\alpha, t; Z) c(\alpha, t|Z) dt, \\ \omega_1(a|\alpha, Z) &= \int_0^1 \mathbb{I}[B_1(a|Z) \geq B_2(t|Z)] c(\alpha, t|Z) dt = \int_0^{G_2 B_1(a|Z)} c(\alpha, t|Z) dt\end{aligned}$$

so that

$$\begin{aligned}\frac{\partial \bar{V}_1(a|\alpha, Z)}{\partial a} &= g_2 b_1(a|Z) V_1(\alpha, G_2 B_1(a|Z); Z) c(\alpha, G_2 B_1(a|Z)|Z) \\ \frac{\partial \omega_1(a|\alpha, Z)}{\partial a} &= g_2 b_1(a|Z) c(\alpha, G_2 B_1(a|Z)|Z).\end{aligned}$$

Hence

$$U_1(\alpha|Z) = \frac{\frac{\partial \bar{V}_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha}}{\frac{\partial \omega_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha}} = V_1(\alpha, G_2 B_1(\alpha|Z); Z). \quad (3.5)$$

It follows from Lemma 2 that, for each Z , $V_1(\alpha_1, \alpha_2; Z)$ is nonparametrically identified over the curve

$$\{(\alpha_1, \alpha_2); \alpha_2 = G_2 B_1(\alpha_1|Z), \alpha_1 \in [0, 1]\}.$$

This is insufficient to identify $V_1(\cdot)$ over $[0, 1]^2 \times \mathcal{Z}$ nonparametrically. However identification may hold under further restrictions of the valuation function as detailed here.

- **Bidder covariate exclusion restriction.** Somaini (2018) considers the exclusion restriction $V_1(\alpha_1, \alpha_2; Z) = V_1(\alpha_1, \alpha_2; Z_1)$, which, for a given Z_1 , ensures identification of the latter for any α_1 in $[0, 1]$ and α_2 in $[\min_{Z_2} G_2 B_1(\alpha_1|Z), \max_{Z_2} G_2 B_1(\alpha_1|Z)]$ by a proper choice of Z_2 .
- **Separability restriction.** Consider the additive specification

$$V_1(\alpha_1, \alpha_2; Z) = v_1(\alpha_1, \alpha_2) + v_0(Z)$$

with the normalization $v_1(0, 0) = 0$.⁶ As $G_2 B_1(0|Z) = 0$ under Assumption S-(ii), $v_2(Z) = U_1(0|Z)$ is identified and so is $v_1(\alpha_1, G_2 B_1(\alpha_1|Z)) = U_1(\alpha_1|Z) - U_1(0|Z)$. It then follows that the valuation function of bidder 1 is identified for any α_1 in $[0, 1]$ and α_2 in $[\min_Z G_2 B_1(\alpha_1|Z), \max_Z G_2 B_1(\alpha_1|Z)]$, which may differ from $[0, 1]$. This restriction on α_2 can be removed under an additional additive assumption. Suppose now $v_1(\alpha_1, \alpha_2) = v_{11}(\alpha_1) + v_{12}(\alpha_2)$ with $v_{11}(0) = v_{12}(0) = 0$. Then $U_1(\cdot|Z)$ identifies

$$u_1(\alpha|Z) = v_{11}(\alpha) + v_{12}(G_2 B_1(\alpha|Z)).$$

As $\partial_Z u_1(\alpha|Z) = v_{12}^{(1)}(G_2 B_1(\alpha|Z)) \partial_Z G_2 B_1(\alpha|Z)$, it follows that $v_{12}^{(1)}(\cdot)$ is identified over $[0, 1]$ if, for each α in $[0, 1]$, there exists a Z such that $\partial_Z G_2 B_1(\alpha|Z) \neq 0$. Hence the initial condition $v_{12}(0) = 0$ yields that $v_{12}(\cdot)$ is identified, and then $v_{11}(\cdot)$ is also identified, both over the whole $[0, 1]$.

- **Signal exclusion restriction.** The value function is identified in the private value case $V_1(\alpha_1, \alpha_2; Z) = V_1(\alpha_1; Z)$. The signal exclusion restriction $V_1(\alpha_1, \alpha_2; Z) = V_1(\alpha_2; Z)$ yields, for each Z , identification for all α_2 between $\min_{\alpha_1 \in [0,1]} G_2 B_1(\alpha_1|Z)$

⁶As discussed for the mixed signal specification, the common initial strategy condition of Assumption S-(ii) holds for Bayesian Nash equilibrium bids if all bidders have the same $v_0(Z)$. Assuming an exclusion restriction $v_{0i}(Z) = v_{0i}(Z_i)$ as in Somaini (2018) is also possible, using for identification purpose values Z satisfying $v_{01}(Z_1) = \dots v_{0n}(Z_n)$, which are identified by the participation of all bidders. It is also desirable to assume that A and Z are independent as identifying the conditional distribution of A given Z is difficult when S-(ii) does not hold.

and $\max_{\alpha_1 \in [0,1]} G_2 B_1(\alpha_1|Z)$, i.e. in $[0, 1]$ under Assumption S-(ii) and the conditions in Lizzeri and Persico (2000).

Hence identification may not hold for all signals, possibly preventing to implement some counterfactuals such as computation of an optimal reserve price. As seen from Theorems 3 and 4 below, this contrasts with the mixed signal value functions considered here.

3.2.2 Three bidder general case

The case of a larger number n of bidders is more difficult because the identified expected value is a multiple integral of order $n - 2$. To see this, suppose that $n = 3$ and that the valuation of interest is the one of the first bidder. The p.d.f of (A_2, A_3) given $A_1 = \alpha$ and Z is $c(\alpha, \cdot, \cdot|Z)$ and $\bar{V}_1(a|\alpha, Z)$, $\omega_1(a|\alpha, Z)$ are now given by

$$\begin{aligned}\bar{V}_1(a|\alpha, Z) &= \int V_1(\alpha, t_2, t_3; Z) \mathbb{I}[B_1(a|Z) \geq \max\{B_2(t_3|Z), B_3(t_3|Z)\}] c(\alpha, t_2, t_3|Z) dt_2 dt_3 \\ &= \int_0^{G_3 B_1(a|Z)} \left[\int_0^{G_2 B_1(a|Z)} V_1(\alpha, t_2, t_3; Z) c(\alpha, t_2, t_3|Z) dt_2 \right] dt_3, \\ \omega_1(a|\alpha, Z) &= \int_0^{G_3 B_1(a|Z)} \left[\int_0^{G_2 B_1(a|Z)} c(\alpha, t_2, t_3|Z) dt_2 \right] dt_3.\end{aligned}$$

Hence

$$\begin{aligned}\frac{\partial \omega_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha} &\times U_1(\alpha|Z) \\ &= g_3 b_1(\alpha|Z) \int_0^{G_2 B_1(\alpha|Z)} V_1(\alpha, t_2, G_3 B_1(\alpha|Z); Z) c(\alpha, t_2, G_3 B_1(\alpha|Z)|Z) dt_2 \\ &+ g_2 b_1(\alpha|Z) \int_0^{G_3 B_1(\alpha|Z)} V_1(\alpha, G_2 B_1(\alpha|Z), t_3; Z) c(\alpha, G_2 B_1(\alpha|Z), t_3|Z) dt_3, \quad (3.6)\end{aligned}$$

$$\begin{aligned}\frac{\partial \omega_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha} &= g_3 b_1(\alpha|Z) \int_0^{G_2 B_1(\alpha|Z)} c(\alpha, t_2, G_3 B_1(\alpha|Z)|Z) dt_2 \\ &+ g_2 b_1(\alpha|Z) \int_0^{G_3 B_1(\alpha|Z)} c(\alpha, G_2 B_1(\alpha|Z), t_3|Z) dt_3.\end{aligned}$$

Lemma 2 therefore establishes nonparametric identification of an integral function of the valuation function over a set of signal variables $(\alpha_1, \alpha_2, \alpha_3) = (\alpha_1, G_2 B_1(\alpha_1|Z), G_3 B_1(\alpha_1|Z))$.

As for the two bidder case, this may not be useful for most applications without further restriction on the valuation function. Somaini (2018) derives some identification results under covariate exclusion.

3.2.3 Revisited Wilson model

On the other hand, the revisited Wilson model is an example of specification that can be easily identified from Lemma 2. Indeed (2.3) and the expressions of $U_1(\alpha|Z)$ derived above imply

$$\lim_{Z_1 \rightarrow +\infty} U_1(\alpha|Z) = \gamma_0(\alpha)$$

because $Z_1 = +\infty$ means that bidder 1 is perfectly informed about the value of the good. This is sufficient to recover identification of this specification.

3.3 Identification of the mixed signal valuation function

The mixed signal valuation specification (2.2) can be identified using a three step procedure. First an initial or terminal value for the slope functions $\gamma_{ij}(\cdot)$ is identified. Second, the function $\Phi_i(\cdot)$ is identified. Third, thanks to the rank condition I, the slope functions are then determined as solving a differential, or an integro-differential, equation. Identification of the slope functions holds over the full set $[0, 1]^n$ of signals, as suitable for many counterfactual applications. However the identification procedure implementation importantly differs depending whether there are two bidders or more, especially in the first step and in the choice of identifying an initial or a terminal value for the slope functions.

3.3.1 Two bidder case

Suppose $n = 2$ and let bidder 1 $\Phi_1(\cdot)$ and $(\gamma_{11}(\cdot), \gamma_{12}(\cdot))$ be the parameters of interest. Hence Lemma 2 and (3.5) show that

$$U_1(\alpha|Z) = \Phi_1[Z'_1 \gamma_{11}(\alpha), Z'_2 \gamma_{12}[G_2 B_1(\alpha|Z)]] \quad (3.7)$$

is identified. The considered next step is the identification of a terminal value for $(\gamma_{11}(\cdot), \gamma_{12}(\cdot))$.

Step 1: identification of \mathcal{I} and $(\gamma_{11}(1), \gamma_{12}(1))$. As $G_2 B_1(1|Z) = 1$ for all Z by the terminal condition of Assumption S-(ii) and Lemma 1-(ii), setting $\alpha = 1$ in (3.7) yields the identity

$$U_1(1|Z) = \Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(1))$$

and $\Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(1))$ is therefore identified. As all $\gamma_{1j}(1)$ are not 0 under Assumption G-(ii), Assumption P ensures that j does not belong to \mathcal{I} if and only if

$$\partial_{Z_k} [U_1(1|Z)] = \frac{\partial \Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(1))}{\partial x_j} \gamma_{1j}(1) = 0 \text{ for all } Z \text{ in } \mathcal{Z}.$$

This implies that $\mathcal{I} = \left\{ j; \frac{\partial \Phi_1(\cdot, \cdot)}{\partial x_j} \neq 0 \right\}$ is identified. As

$$\lim_{Z \rightarrow 0} \partial_{Z_j} U_1(1|Z) = \frac{\partial \Phi_1(0, 0)}{\partial x_j} \gamma_{1j}(1)$$

for a smooth $\Phi_1(\cdot)$ satisfying Assumption P, using the normalization (2.5) shows that $\gamma_{1j}(1)$ is identified for all j in \mathcal{I} .

Step 2: identification of $\Phi_1(\cdot)$. Consider $x = (x_1, x_3)$ in \mathbb{R}_{+*}^2 . For k in the identified \mathcal{I} , there is a Z_k in \mathbb{R}_{+*}^D such that $x_k = Z'_k \gamma_{1k}(1)$, recalling that $\gamma_{1k}(1)$ has been identified in the preceding step. When k does not belong to \mathcal{I} , choose an arbitrary Z_k in \mathbb{R}_{+*}^D . It then holds for such choice of Z_1 and Z_2

$$\Phi_1(x_1, x_2) = \Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(1))$$

so that $\Phi_1(\cdot)$ is identified over \mathbb{R}_{+*}^2 . Under Assumption P, continuity of $\Phi_1(\cdot)$ ensures it is identified over \mathbb{R}_+^2 .

Step 3: identification of $(\gamma_{11}(\cdot), \gamma_{12}(\cdot))$. Suppose first the private value case $\mathcal{I} = \{1\}$, ie $\Phi_1(x_1, x_2) = \Phi_1(x_1)$. Then monotonicity in Assumption P and (3.7) show that $Z'_1 \gamma_1(\cdot) = \Phi_1^{-1}[U(\cdot|Z_1, Z_2)]$ for any (Z_1, Z_2) in \mathcal{Z} . If $\mathcal{I} = \{2\}$, ie bidder 1 is uninformed, $\gamma_2[G_2 B_1(\alpha|Z)]$ is similarly identified, which ensures that $\gamma_2(\cdot)$ as the identified $G_2 B_1(\cdot|Z)$ is one to one by Lemma 1-(ii) under Assumption S-(iv).

Consider now the case where $\mathcal{I} = \{1, 2\}$. Observe that, since $g_2 b_1(\cdot|Z) > 0$ by Assumption S-(iv) and Lemma 1-(ii),

$$\begin{aligned} \partial_{Z_2} \{ \gamma_{12} [G_2 B_1(\alpha|Z)] \} &= \gamma_{12}^{(1)} [G_2 B_1(\alpha|Z)] \partial_{Z_2} G_2 B_1(\alpha|Z) \\ &= \gamma_{12}^{(1)} [G_2 B_1(\alpha|Z)] g_2 b_1(\alpha|Z) \frac{\partial_{Z_2} G_2 B_1(\alpha|Z)}{g_2 b_1(\alpha|Z)} \\ &= \frac{\partial \{ \gamma_{12} [G_2 B_1(\alpha|Z)] \}}{\partial \alpha} \frac{\partial_{Z_2} G_2 B_1(\alpha|Z)}{g_2 b_1(\alpha|Z)}. \end{aligned} \quad (3.8)$$

Differentiating $U_1(\alpha|Z)$ with respect to α and Z_2 then gives

$$\begin{aligned} \frac{\partial \Phi_1}{\partial x_1} [\gamma_{11}(\alpha) Z_1, \gamma_{12} [G_2 B_1(\alpha|Z)] Z_2] Z_1 \frac{d\gamma_{11}(\alpha)}{d\alpha} \\ + \frac{\partial \Phi_1}{\partial x_2} [\gamma_{11}(\alpha) Z_1, \gamma_{12} [G_2 B_1(\alpha|Z)] Z_2] Z_2 \frac{\partial \{ \gamma_{12} [G_2 B_1(\alpha|Z)] \}}{\partial \alpha} = \frac{\partial U_1(\alpha|Z)}{\partial \alpha}, \end{aligned}$$

$$\begin{aligned} \frac{\partial \Phi_1}{\partial x_2} [\gamma_{11}(\alpha) Z_1, \gamma_{12} [G_2 B_1(\alpha|Z)] Z_2] \gamma_{12} [G_2 B_1(\alpha|Z)] \\ + \frac{\partial \Phi_1}{\partial x_2} [\gamma_{11}(\alpha) Z_1, \gamma_{12} [G_2 B_1(\alpha|Z)] Z_2] Z_2 \frac{\partial_{Z_2} G_2 B_1(\alpha|Z)}{g_2 b_1(\alpha|Z)} \frac{\partial \{ \gamma_{12} [G_2 B_1(\alpha|Z)] \}}{\partial \alpha} = \partial_{Z_2} U_1(\alpha|Z) \end{aligned}$$

which shows that $\Gamma_1(\alpha|Z) = [\gamma_{11}(\alpha), \gamma_{12} [G_2 B_1(\alpha|Z)]]'$ are the solution of a 2×2 system of differential equations with the terminal condition $\Gamma_1(1|Z) = [1, 1]'$. Standard uniqueness of the solution of such differential systems would then ensure that $\Gamma_1(\cdot|Z)$, and then $[\gamma_{11}(\cdot), \gamma_{12}(\cdot)]$, is identified. Unfortunately, this argument cannot be applied here because the item $\partial_{Z_2} G_2 B_1(\alpha|Z)$, which appears in front of $\gamma_{12}^{(1)}(\cdot)$ in the differential system, vanishes when $\alpha = 1, 0$ due to the terminal and initial bidding strategy conditions in Assumption S-(ii,iii) and Lemma 1, which identifies strategy and bid quantile functions. This issue is addressed in the proof of the next Theorem in the Appendix.⁷ Theorem 3 summarizes the identification result.

⁷ As noted by a Referee, taking Z_2 and Z_1 equal to 0 would give, respectively

$$\begin{aligned} Z_1' \gamma_{11}(\alpha) &= \Phi_1^{-1|x_1} [U_1(\alpha|Z_1, 0), 0], \\ Z_2' \gamma_{12}(\alpha) &= \Phi_1^{-1|x_2} [0, U_1((G_2 B_1(\alpha|0, Z_2))|0, Z_2)], \end{aligned}$$

where $\Phi_1^{-1|x_1}(y, \cdot)$ is the inverse of $x_2 \mapsto \Phi_1(y, x_2)$ and $\Phi_1^{-1|x_2}(\cdot, y)$ is similarly defined. Hence $\gamma_{11}(\cdot)$ and $\gamma_{12}(\cdot)$ would be identified. This may be however difficult to implement for Bayesian Nash Equilibrium bids.

Theorem 3 *Suppose Assumptions A, I, G with the terminal condition G-(i), P and Z hold and that $n = 2$. Then, up to a normalization of $\Phi_i(\cdot, \cdot)$ and $(\gamma_{11}(\cdot), \gamma_{12}(\cdot))$ as (2.5):*

- (i). *The set \mathcal{I} of active signals defined in (2.4) is identified;*
- (ii). *The function $\Phi_i(x_1, x_2)$ is identified over \mathbb{R}_+^2 ;*
- (iii). *The slope functions $\gamma_{ij}(\cdot)$ are identified for all j in \mathcal{I} .*

Proof of Theorem 3: see Appendix.

Note that identification of the slope makes use of values of Z in the vicinity of 0, plus an arbitrary non vanishing Z , so that the slopes are overidentified. This identification procedure also works when bidder i makes dominated bids below a threshold $\underline{\alpha}_i(Z)$, which is identified by the probability of observing such bids, as it is sufficient to solve the differential system over $[\underline{\alpha}_i(Z), 1]$. Identification of the slope would then hold over $[\inf_Z \underline{\alpha}_i(Z), 1]$.

In the two bidder case, identification is based upon the terminal strategy condition S-(iii), which is quite satisfactory here as it is based on a well established result of Lizzeri and Persico (2000) when bids are drawn from a Bayesian Nash Equilibrium with valuation functions from the mixed signal specification. It implies that the initial slope values are unconstrained by Assumption G. Hence both conditions BNE-(i) and (ii) can be used to ensure that the initial strategy condition S-(ii) holds with Bayesian Nash Equilibrium bids.

3.3.2 More than two bidders

We first explain why using, as in the two bidder case, the terminal value of $U_1(\cdot|Z)$ for identification purpose becomes difficult when the number of bidders is larger. For the sake of discussion brevity, assume $n = 3$, the case of a higher number of bidders being similar,

For instance, in the private value case with bidder 2 value $Z'_2\gamma_{22}(A_2)$, the bidding strategies $B_1(\cdot|Z)$ and $B_2(\cdot|Z)$ may have degenerate limits, if any, when Z_2 goes to 0, because the fact that bidder 2 value goes to 0 is also known to bidder 1. As shown by (3.7), it follows that establishing the existence of $U_1(\alpha|Z_1, 0)$, $U_1((G_2B_1(\alpha|0, Z_2))|0, Z_2)$, or even $\lim_{Z_1 \downarrow 0} U_1(\alpha|Z)$, $\lim_{Z_2 \downarrow 0} U_1((G_2B_1(\alpha|Z))|Z)$, may be difficult.

and take $i = 1$. Let $W_1(\alpha|Z) = \frac{\partial \bar{V}_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha}$ be the function in (3.6), so that $U_1(\alpha|Z) = W_1(\alpha|Z) / \left(\frac{\partial \omega_1(a|\alpha, Z)}{\partial a} \Big|_{a=\alpha} \right)$. For $\alpha = 1$, it holds under the terminal strategy condition in Assumption S-(ii)

$$W_1(1|Z) = g_3 b_1(1|Z) \int_0^1 \Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(t_2), Z'_3 \gamma_{13}(1)) c(t_2 | A_1 = 1, A_3 = 1, Z) dt_2 \\ + g_2 b_1(1|Z) \int_0^1 \Phi_1(Z'_1 \gamma_{11}(1), Z'_2 \gamma_{12}(1), Z'_3 \gamma_{13}(t_3)) c(t_3 | A_1 = 1, A_2 = 1, Z) dt_3.$$

Hence $W_1(1|Z)$ now depends upon the whole slope functions $\gamma_{12}(\cdot)$ and $\gamma_{13}(\cdot)$, while only the slope terminal values were involved in the two bidder case. Using the terminal value of $U_1(\cdot|Z)$ for identification purpose does not seem feasible and we use instead the common initial strategy condition of Assumption S-(ii).⁸

It is first shown in the proof of Theorem 4 that

$$U_i(0|Z) = \Phi_i[Z'_1 \gamma_{i1}(0), \dots, Z'_n \gamma_{in}(0)], \quad (3.9)$$

which is identified by Equation (3.4) in Lemma 2. When all the $\gamma_{ij}(0)$, j in \mathcal{I} , differ from 0 as assumed in Assumption G-(ii), arguing as in the Step 1 of the two bidder case permits to identify \mathcal{I} and those $\gamma_{ij}(0)$. Repeating Step 2 of the two bidder case then yields that $\Phi_i(\cdot)$ is identified.

Identifying the slope functions $\gamma_{ij}(\cdot)$ is slightly more complicated than in Step 3 of the two bidder case. Differentiating the identified $U_i(\alpha|Z)$ with respect to the signal shifters Z_j , $j \neq i$ now gives an integro-differential system. The proof of Theorem 4, which summarizes our identification result for $n \geq 3$, establishes uniqueness of its solution.

Theorem 4 *Suppose Assumptions A, I, G with the initial condition G-(ii), P and Z hold. Then, up to a normalization of $\Phi_i(\cdot, \dots, \cdot)$ and $(\gamma_{11}(\cdot), \dots, \gamma_{1n}(\cdot))$ as (2.5):*

⁸Letting Z goes to 0 allows to identify $(\lim_{Z \downarrow 0} g_3 b_1(1|Z)) \int_0^1 \gamma_{12}(t) c(t | A_1 = 1, A_3 = 1, 0) dt + (\lim_{Z \downarrow 0} g_2 b_1(1|Z)) \gamma_{12}(1)$ and a similar functional of $\gamma_{13}(\cdot)$, which can be used instead of the first order condition. We did not attempt to implement this approach, which is not straightforward, due to the fact that the limits of $g_j b_1(1|z)$, $j = 2, 3$, when Z goes to 0 may not be well defined as discussed in footnote 7 for the limits of $G_j B_1(1|z)$.

- (i). The set \mathcal{I} of active signals defined in (2.4) is identified;
- (ii). The function $\Phi_i(x_1, \dots, x_n)$ is identified over \mathbb{R}_+^n ;
- (iii). The slope functions $\gamma_{ij}(\cdot)$ are identified for all j in \mathcal{I} .

Proof of Theorem 4: see Appendix.

Theorem 4 also applies to the two bidder case, but relies more importantly on the initial strategy condition in Assumption S-(ii), which is less natural than the terminal one S-(iii) derived in Lizzeri and Persico (2000). Because identification relies on the initial value $U_i(0|Z)$ instead of $U_i(1|Z)$ used for the two bidder case, Theorem 4 makes use of the initial slope Assumption G-(ii), which imposes that $\gamma_{ij}(0)$ must differ from 0 for all j of \mathcal{I} . This has important consequences for Bayesian Nash Equilibrium bids as only the common $\Phi_i(\cdot)$ and initial slope restrictions of Condition BNE-(ii) can be used.⁹ This reduces the degrees of bidder asymmetry permitted by the mixed signal specification, as the only possible cause of asymmetry is now given by distinct slopes $\gamma_{ij}(\alpha)$ for $\alpha > 0$. As many studies assume that $\Phi_i(x_1, \dots, x_n) = x_1 + \dots + x_n$ as in Somaini (2018) and because the slopes $\gamma_{ij}(\cdot)$ can be very small, this may nevertheless be flexible enough for many applications.

4 Estimation strategy

The identification proof is constructive and can be directly used for estimation, although more suitable procedures can be proposed, as a procedure similar to the one introduced by

⁹ A conjecture that would allow to use Condition BNE-(i), which allows for more asymmetric functions $\Phi_i(\cdot)$, is that under Assumption G-(i) which states that $\gamma_{ij}(0) = 0$ for all i, j , all the strategies $s_i(\tau_i \alpha | Z / \alpha)$ converge when α goes to 0 because the corresponding valuation functions satisfy

$$\lim_{\alpha \downarrow 0} \Phi_i \left(\frac{Z'_1 \gamma_{i1}(\tau_1 \alpha)}{\alpha}, \dots, \frac{Z'_n \gamma_{in}(\tau_n \alpha)}{\alpha} \right) = \Phi_i \left(Z'_1 \gamma_{i1}^{(1)}(0) \tau_1, \dots, Z'_n \gamma_{in}^{(1)}(0) \tau_n \right).$$

Setting the τ_i to 1 will then allows to identify $\Phi_i(\cdot)$ as the $\gamma_{i1}^{(1)}(0)$ do not vanish and can be identified using $Z \rightarrow 0$ and (2.5). Establishing this conjecture is however out of the scope of the present paper.

Botosaru (2019) for a duration model with unobserved heterogeneity. Consider for the sake of brevity the two bidder case. The first stage consists in an estimation of $U_1(\alpha|Z)$ based on (3.4) in Lemma 2

$$\widehat{U}_1(\alpha|Z) = \widehat{B}_1(\alpha|Z) + \widehat{B}_1^{(1)}(\alpha|Z) \widehat{\Omega}_1(\alpha|Z)$$

where the quantile derivative estimator can be obtained using Gimenes and Guerre (2019). Recall now that $U_1(\alpha|Z) = \Phi_1[\gamma_{11}(\alpha)Z_1, \gamma_{12}[G_2B_1(\alpha|Z)]Z_2]$ by (3.7), which could be estimated using

$$\Phi_1\left[\gamma_{11}(\alpha)Z_1, \gamma_{12}\left[\widehat{G}_2\widehat{B}_1(\alpha|Z)\right]Z_2\right].$$

The second stage of the procedure matches the above with $\widehat{U}_1(\alpha|Z)$ to produce an estimator of $\Phi_1(\cdot)$, $\gamma_{11}(\cdot)$ and $\gamma_{12}(\cdot)$

$$\begin{aligned} & \left[\widehat{\Phi}_1(\cdot), \widehat{\gamma}_{11}(\cdot), \widehat{\gamma}_{12}(\cdot)\right] \\ & = \arg \min_{\Phi, \gamma_1, \gamma_2} \int \left\{ \int_0^1 \left(\widehat{U}_1(\alpha|Z) - \Phi\left[\gamma_1(\alpha)Z_1, \gamma_2\left[\widehat{G}_2\widehat{B}_1(\alpha|Z)\right]Z_2\right]\right)^2 d\alpha \right\} dZ \end{aligned}$$

where the minimization is performed over a sieve for $\gamma_1(\cdot)$, $\gamma_2(\cdot)$ and $\Phi(\cdot)$, or over a simpler set of functions $\Phi(\cdot)$, such as the additive of maximum functions of the two first examples. Up to the estimation $\widehat{G}_2\widehat{B}_1(\cdot|\cdot)$, these estimators can be studied as in Botosaru (2019).

Practical computation of these estimators can be done in the following iterative way

$$\widehat{\Phi}_{1,k+1}(\cdot) = \arg \min_{\Phi_1} \int \left\{ \int_0^1 \left(\widehat{U}_1(\alpha|Z) - \Phi_1\left[\widehat{\gamma}_{11,k}(\alpha)Z_1, \widehat{\gamma}_{12,k}\left[\widehat{G}_2\widehat{B}_1(\alpha|Z)\right]Z_2\right]\right)^2 d\alpha \right\} dZ,$$

$$\begin{aligned} & \left[\widehat{\gamma}_{11,k+1}(\cdot), \widehat{\gamma}_{12,k+1}(\cdot)\right] \\ & = \arg \min_{\gamma_1, \gamma_2} \int \left\{ \int_0^1 \left(\widehat{U}_1(\alpha|Z) - \widehat{\Phi}_{1,k+1}\left[\gamma_1(\alpha)Z_1, \gamma_2\left[\widehat{G}_2\widehat{B}_1(\alpha|Z)\right]Z_2\right]\right)^2 d\alpha \right\} dZ. \quad (4.1) \end{aligned}$$

Alternatively to (4.1), $\widehat{\gamma}_{11,k+1}(\cdot)$ and $\widehat{\gamma}_{12,k+1}(\cdot)$ can be obtained by solving the differential system in Section 3.3.1 using $\widehat{\Phi}_{1,k+1}(\cdot)$ in place of $\Phi_1(\cdot)$. The stopping criterion must take into account that $\Phi_1(x_1, x_2)$ may depend only upon x_1 or x_2 . For instance, in the private value case $\Phi_1(x_1, x_2) = \Phi_1(x_1)$, the valuation function is $\Phi_1[\gamma_{11}(\alpha)Z_1]$ and $\gamma_{12}(\cdot)$ is not

identified. If this holds, $\widehat{\gamma}_{12,k}(\cdot)$ may not converge when k grows. This can be addressed by dropping out of the minimization the corresponding slope when the sieve coefficients of $\widehat{\Phi}_{1,k}(x_1, x_2)$ shows that this function may not depend upon x_1 or x_2 .

5 Conclusion

The present paper considers a nonparametric interdependent value model which is shown to be identified from first-price auction best response bids. The model is derived from Milgrom and Weber (1982) and assumes that the bidder signal depends upon some observed bidder characteristics, which variations are key to obtain identification. Compared to other approaches of the literature, this specification does not rely on functional restrictions difficult to maintain or to test and delivers valuation functions that can be computed for all possible signal values. The latter allows to implement various counterfactuals, such as expected revenue computation for alternative auction scenarii. Most of the conditions ensuring identification are testable. The considered interdependent value model is overidentified, so that specification testing is possible.

While the proposed approach assumes that the bidder private signal and information shifter are combined using a linear index structure, we believe that the identification procedure is general enough to tackle various other functional forms. The linear index may also be viewed as a nonparametric approximation of a function combining private signals and information shifter. Unobserved bidder heterogeneity would also deserve further research, investigating for instance implementations of nonparametric deconvolution techniques as in Li et al. (2000) or Krasnokutskaya (2011), the approach of Compiani et al. (2018) and Haile and Kitamura (2018), or parametric specifications.

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Appendix: Proofs of the results

A.1 Proof of Lemma 1

As $B_j = s_j(A_j; Z)$ where $s_j(\cdot; Z)$ is strictly increasing under Assumption S-(ii) and because A_j is a $\mathcal{U}_{[0,1]}$ random variable, it holds for all b in $[s_j(0; Z), s_j(1; Z)]$

$$\begin{aligned} G_j(b|Z) &= \mathbb{P}(B_j \leq b|Z) = \mathbb{P}[s_j(A_j; Z) \leq b|Z] = \mathbb{P}[A_j \leq s_j^{-1}(b; Z)|Z] \\ &= s_j^{-1}(b; Z). \end{aligned}$$

Hence $G_j(B_j|Z) = s_j^{-1}[s_j(A_j; Z); Z] = A_j$ and $B_j(\cdot|Z) = G_j^{-1}(\cdot|Z) = s_j(\cdot; Z)$, which establish (i) and (ii). (iii) follows from

$$\omega(a|\alpha, Z) = \mathbb{P}\left[s_i(a; Z) > \max_{1 \leq j \neq i \leq n} B_j \mid A_i = \alpha, Z\right]$$

and $s_i(\cdot; Z) = B_i(\cdot|Z)$. □

A.2 Proof of Theorems 3 and 4

In this proof, we assume $i = 1$ without loss of generality and remove the corresponding index for the sake of brevity. In what follows $|\cdot|$ stands for the Euclidean norm of a vector or the absolute value of a real number. C denotes a constant that may vary from line to line.

A.2.1 The two bidder case: proof of Theorem 3

We detail here the proof of Step 3 in Section 3.3.1. Recall it was shown in Section 3.3.1 that $\Phi(\cdot)$ is identified over \mathbb{R}_+^2 from

$$U(\alpha|Z) = \Phi[Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2(G_2 B_1(\alpha|Z))]$$

which is also identified, as $\gamma_1(1)$ and $\gamma_2(1)$. We now show that $\gamma_1(\cdot)$ and $\gamma_2(\cdot)$ are identified.

Differentiating $U(\alpha|Z)$ with respect to α gives

$$\begin{aligned} & \frac{\partial \Phi}{\partial x_1} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]] \frac{d\{Z'_1 \gamma_1(\alpha)\}}{d\alpha} \\ & + \frac{\partial \Phi}{\partial x_2} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]] \frac{\partial \{Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]\}}{\partial \alpha} = \frac{\partial U(\alpha|Z)}{\partial \alpha}. \end{aligned}$$

Differentiating with respect to the entry Z_{2d} gives, by (3.8),

$$\begin{aligned} & \frac{\partial \Phi}{\partial x_2} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)] Z_2] \times \gamma_{2d} [G_2 B_1(\alpha|Z)] \\ & + \frac{\partial \Phi}{\partial x_2} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]] \frac{\frac{\partial G_2 B_1(\alpha|Z)}{\partial Z_{2d}}}{g_2 b_1(\alpha|Z)} \frac{\partial \{Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]\}}{\partial \alpha} = \frac{\partial U(\alpha|Z)}{\partial Z_{2d}} \end{aligned}$$

which implies, for the column Gradient vector $\partial_{Z_2} U(\alpha|Z) = \left[\frac{\partial U(\alpha|Z)}{\partial Z_{2d}} \right]_{d=1, \dots, D}'$,

$$\begin{aligned} & \frac{\partial \Phi}{\partial x_2} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)] Z_2] \times Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)] \\ & + \frac{\partial \Phi}{\partial x_2} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]] \frac{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)}{g_2 b_1(\alpha|Z)} \frac{\partial \{Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]\}}{\partial \alpha} = Z'_2 \partial_{Z_2} U(\alpha|Z) \end{aligned}$$

Define now

$$\Gamma(\alpha|Z) = [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]]'$$

and for

$$\frac{\partial \Phi}{\partial x_j} [\Gamma](\alpha|Z) = \frac{\partial \Phi}{\partial x_j} [Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2 [G_2 B_1(\alpha|Z)]]$$

consider the 2×2 matrices

$$\begin{aligned} \mathbf{D}[\Phi, \Gamma](\alpha|Z) &= \begin{bmatrix} \frac{\partial \Phi}{\partial x_1} [\Gamma](\alpha|Z) & 0 \\ 0 & \frac{\partial \Phi}{\partial x_2} [\Gamma](\alpha|Z) \end{bmatrix}, \\ \mathbf{G}_2(\alpha|Z) &= \begin{bmatrix} 1 & 1 \\ 0 & \frac{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)}{g_2 b_1(\alpha|Z)} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{\alpha(1-\alpha)}{g_2 b_1(\alpha|Z)} \end{bmatrix} \times \begin{bmatrix} 1 & 1 \\ 0 & \frac{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)}{\alpha(1-\alpha)} \end{bmatrix} \end{aligned}$$

so that Assumptions I and S-(iv) with Lemma 1-(ii) ensure that $\mathbf{G}_2(\alpha|Z)$ has an inverse when α belongs to $(0, 1)$ with

$$\mathbf{G}_2^{-1}(\alpha|Z) = \begin{bmatrix} 1 & -\frac{g_2 b_1(\alpha|Z)}{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)} \\ 0 & \frac{g_2 b_1(\alpha|Z)}{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)} \end{bmatrix} = \begin{bmatrix} 1 & -\frac{\alpha(1-\alpha)}{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)} \\ 0 & \frac{\alpha(1-\alpha)}{Z'_2 \partial_{Z_2} G_2 B_1(\alpha|Z)} \end{bmatrix} \times \begin{bmatrix} 1 & 0 \\ 0 & \frac{g_2 b_1(\alpha|Z)}{\alpha(1-\alpha)} \end{bmatrix}.$$

Observe that $\mathbf{D} [\Phi, \Gamma] (\alpha|Z)$ has an inverse for all (α, Z) by Assumption P, while Assumption I gives that $\mathbf{G}_2 (\alpha|Z)$ diverges with the order $1/(1 - \alpha)$ when α goes to 1. Define also the vector

$$\Psi [\Phi, \Gamma] (\alpha|Z) = \begin{bmatrix} \partial_{Z_2} U (\alpha|Z) \\ g_2 b_1 (\alpha|Z) \left\{ Z_2' \partial_{Z_2} U (\alpha|Z) - \frac{\partial \Phi}{\partial x_2} [\Gamma] (\alpha|Z) Z_2' \gamma_2 [G_2 B_1 (\alpha|Z)] \right\} \end{bmatrix}.$$

Then the differential system above writes $\mathbf{G}_2 (\alpha|Z) \mathbf{D} [\Phi, \Gamma] (\alpha|Z) \Gamma^{(1)} (\alpha|Z) = \Psi [\Phi, \Gamma] (\alpha|Z)$, so that $\Gamma (\cdot|Z)$ must solve

$$\Gamma^{(1)} (\alpha|Z) = \{\mathbf{G}_2 (\alpha|Z) \mathbf{D} [\Phi, \Gamma] (\alpha|Z)\}^{-1} \Psi [\Phi, \Gamma] (\alpha|Z) \quad (\text{A.1})$$

over $(0, 1)$. As the LHS is continuous over $[0, 1]$, so must be the RHS. Hence the differential system (A.1) holds over $[0, 1]$ with a known terminal value $\Gamma (1|Z)$ by Assumption S-(iii).

Suppose now that a continuously differentiable $\tilde{\Gamma} (\alpha|Z) = [Z_1' \tilde{\gamma}_1 (\alpha), Z_2' \tilde{\gamma}_2 [G_2 B_1 (\alpha|Z)]]'$ also solves the differential system (A.1) with the terminal condition $\tilde{\Gamma} (1|Z) = \Gamma (1|Z)$. Then (A.1) gives

$$\begin{aligned} \tilde{\Gamma}^{(1)} (\alpha|Z) - \Gamma^{(1)} (\alpha|Z) &= \left\{ \mathbf{G}_2 (\alpha|Z) \mathbf{D} [\Phi, \tilde{\Gamma}] (\alpha|Z) \right\}^{-1} \Psi [\Phi, \tilde{\Gamma}] (\alpha|Z) \\ &\quad - \left\{ \mathbf{G}_2 (\alpha|Z) \mathbf{D} [\Phi, \Gamma] (\alpha|Z) \right\}^{-1} \Psi [\Phi, \Gamma] (\alpha|Z). \end{aligned} \quad (\text{A.2})$$

Let $|\cdot|$ be the Euclidean norm and set, for a fixed Z , $\Delta (\alpha) = \tilde{\Gamma} (\alpha|Z) - \Gamma (\alpha|Z)$. Note that $\Delta (\cdot)$ is continuously differentiable with $\Delta (1) = 0$, so that there exists a $\lambda > 0$ such that for all α

$$|\Delta (\alpha)| \leq \lambda (1 - \alpha).$$

Since the partial derivatives of $\Phi (\cdot)$ are Lipschitz by Assumption P, the expression of $\mathbf{G}_2^{-1} (\alpha|Z)$ and Assumption I imply by (A.2), for all α in $[0, 1]$,

$$|\Delta^{(1)} (\alpha)| \leq \frac{C}{1 - \alpha} |\Delta (\alpha)|.$$

Hence for all $\epsilon > 0$ small enough, (A.2) gives

$$|\Delta^{(1)} (\alpha)| \leq \mathbb{I} (\alpha \leq 1 - \epsilon) \frac{C}{\epsilon} |\Delta (\alpha)| + \mathbb{I} (1 - \epsilon < \alpha \leq 1) \lambda. \quad (\text{A.3})$$

It follows from (A.3) that

$$|\Delta^{(1)}(\alpha)| \leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \frac{C}{\epsilon} (1 - \alpha) + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda$$

and then, since $\Delta(1) = 0$,

$$\begin{aligned} |\Delta(\alpha)| &= \left| \int_{\alpha}^1 \Delta^{(1)}(t) dt \right| \leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \frac{C}{\epsilon} \frac{(1 - \alpha)^2}{2} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda (1 - \alpha) \\ &\leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \frac{C}{\epsilon} \frac{(1 - \alpha)^2}{2} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda \epsilon. \end{aligned}$$

Substituting in (A.3) shows that

$$|\Delta^{(1)}(\alpha)| \leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \left(\frac{C}{\epsilon} \right)^2 \frac{(1 - \alpha)^2}{2} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda.$$

An additional iteration shows that

$$\begin{aligned} |\Delta(\alpha)| &\leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \left(\frac{C}{\epsilon} \right)^2 \frac{(1 - \alpha)^3}{3!} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda \epsilon, \\ |\Delta^{(1)}(\alpha)| &\leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \left(\frac{C}{\epsilon} \right)^3 \frac{(1 - \alpha)^3}{3!} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda. \end{aligned}$$

Iterating then gives, for any integer number $p \geq 2$, any $\epsilon > 0$ small enough and all α of $[0, 1]$,

$$|\Delta(\alpha)| \leq \mathbb{I}(\alpha \leq 1 - \epsilon) \lambda \frac{\epsilon}{C} \left(\frac{C}{\epsilon} \right)^p \frac{(1 - \alpha)^p}{p!} + \mathbb{I}(1 - \epsilon < \alpha \leq 1) \lambda \epsilon$$

As $\lim_{p \uparrow \infty} \left(\frac{C}{\epsilon} \right)^p \frac{(1 - \alpha)^p}{p!} = 0$, it follows that for all α in $[0, 1]$, $|\Delta(\alpha)| \leq \lambda \epsilon$ for all $\epsilon > 0$, which implies $\Delta(\cdot) = 0$ over $[0, 1]$. Then Assumption S and Lemma 1-(ii) imply that $\tilde{\gamma}_1(\cdot) = \gamma_1(\cdot)$ and $\tilde{\gamma}_2(\cdot) = \gamma_2(\cdot)$. Hence the slope $[\gamma_1(\cdot), \gamma_2(\cdot)]$ is identified. This ends the proof of the Theorem. \square

A.2.2 More than two bidders: proof of Theorem 4

For the sake of notation, assume $n = 3$, the case of a larger number of bidders being similar, and set $i = 1$.

Identification of $\Phi(\cdot)$ and $\gamma_j(0)$, j in \mathcal{I} . Let

$$W(\alpha|Z) = \left. \frac{\partial \bar{V}_1(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}$$

be the function in (3.6), which is

$$\begin{aligned} W(\alpha|Z) &= g_3 b_1(\alpha|Z) \int_0^{G_2 B_1(\alpha|Z)} \Phi[Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2(t_2), Z'_3 \gamma_3[G_3 B_1(\alpha|Z)]] c(t_2|\alpha, Z) dt_2 \\ &+ g_2 b_1(\alpha|Z) \int_0^{G_3 B_1(\alpha|Z)} \Phi[Z'_1 \gamma_1(\alpha), Z'_2 \gamma_2[G_2 B_1(\alpha|Z)], Z'_3 \gamma_3(t_3)] c(t_3|\alpha, Z) dt_3 \end{aligned}$$

setting $c(t_i|\alpha, Z) = c(t_i|A_1 = \alpha, A_j = G_j B_1(\alpha|Z), Z)$ where (i, j) is $(2, 3)$ or $(3, 2)$. With this notation

$$\begin{aligned} \left. \frac{\partial \omega(a|\alpha, Z)}{\partial a} \right|_{a=\alpha} &= g_3 b_1(\alpha|Z) \int_0^{G_2 B_1(\alpha|Z)} c(t_2|\alpha, Z) dt_2 \\ &+ g_2 b_1(\alpha|Z) \int_0^{G_3 B_1(\alpha|Z)} c(t_3|\alpha, Z) dt_3, \\ U_1(\alpha|Z) &= \frac{W(\alpha|Z)}{\left. \frac{\partial \omega(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}}. \end{aligned}$$

This implies by the initial bid condition in Assumption S-(ii) and by S-(iv),

$$U_1(0|Z) = \lim_{\alpha \downarrow 0} \frac{W(\alpha|Z)}{\left. \frac{\partial \omega(a|\alpha, Z)}{\partial a} \right|_{a=\alpha}} = \Phi[Z'_1 \gamma_1(0), Z'_2 \gamma_2(0), Z'_3 \gamma_3(0)].$$

This identifies the set \mathcal{I} of active signals and the corresponding $\gamma_j(0)$ through the partial derivatives $\partial_{Z_j} U_1(0|Z)$, Assumption G-(ii), Assumption P and using the normalization condition $\frac{\partial}{\partial x_j} \Phi(0, 0, 0) = 1$. Assumptions Z and G-(ii) ensures it is possible to find Z_1, Z_2 and Z_3 such that $(Z'_1 \gamma_1(0), Z'_2 \gamma_2(0), Z'_3 \gamma_3(0)) = (x_1, x_2, x_3)$ for any (x_1, x_2, x_3) in \mathbb{R}_{+*}^3 . This shows that $U_1(0|Z)$ identifies $\Phi(\cdot)$ over \mathbb{R}_+^3 by continuity.

Identification of $\gamma_j(\cdot)$, j in \mathcal{I} . Suppose all the signals are active, $\mathcal{I} = \{1, 2, 3\}$, the other cases being similar. As for the two bidder case, the proof proceeds by finding an integro-differential system which unique solution is $(\gamma_1(\cdot), \gamma_2(\cdot), \gamma_3(\cdot))$. Set

$$\Gamma(\alpha|Z) = [\gamma_1(\alpha), \gamma_2[G_2 B_1(\alpha|Z)], \gamma_3[G_3 B_1(\alpha|Z)]]'.$$

Differentiating $W(\alpha|Z)$ with respect to α gives

$$\begin{aligned} \mathbf{D}_1[\Phi, \Gamma](\alpha|Z) \frac{d\{Z'_1\gamma_1(\alpha)\}}{d\alpha} + g_2b_1(\alpha|Z) \mathbf{D}_2[\Phi, \Gamma](\alpha|Z) \frac{\partial\{Z'_2\gamma_2[G_2B_1(\alpha|Z)]\}}{\partial\alpha} \\ + g_3b_1(\alpha|Z) \mathbf{D}_3[\Phi, \Gamma](\alpha|Z) \frac{\partial\{Z'_3\gamma_3[G_3B_1(\alpha|Z)]\}}{\partial\alpha} = \Psi_1[\Phi, \Gamma](\alpha|Z) \end{aligned}$$

where

$$\begin{aligned} \mathbf{D}_1[\Phi, \Gamma](\alpha|Z) &= g_3b_1(\alpha|Z) \int_0^{G_2B_1(\alpha|Z)} \frac{\partial\Phi}{\partial x_1} [Z'_1\gamma_1(\alpha), Z'_2\gamma_2(t_2), Z'_3\gamma_3[G_3B_1(\alpha|Z)]] c(t_2|\alpha, Z) dt_2 \\ &\quad + g_2b_1(\alpha|Z) \int_0^{G_3B_1(\alpha|Z)} \frac{\partial\Phi}{\partial x_1} [Z'_1\gamma_1(\alpha), Z'_2\gamma_2[G_2B_1(\alpha|Z)], Z'_3\gamma_3(t_3)] c(t_3|\alpha, Z) dt_3, \\ \mathbf{D}_2[\Phi, \Gamma](\alpha|Z) &= \int_0^{G_3B_1(\alpha|Z)} \frac{\partial\Phi}{\partial x_2} [Z'_1\gamma_1(\alpha), Z'_2\gamma_2[G_2B_1(\alpha|Z)], Z'_3\gamma_3(t_3)] c(t_3|\alpha, Z) dt_3, \\ \mathbf{D}_3[\Phi, \Gamma](\alpha|Z) &= \int_0^{G_2B_1(\alpha|Z)} \frac{\partial\Phi}{\partial x_3} [Z'_1\gamma_1(\alpha), Z'_2\gamma_2(t_2), Z'_3\gamma_3[G_3B_1(\alpha|Z)]] c(t_2|\alpha, Z), \end{aligned}$$

and where $\Psi_1[\Phi, \Gamma](\alpha|Z)$ is equal to

$$\begin{aligned} \frac{\partial W(\alpha|Z)}{\partial\alpha} - \frac{\partial g_2b_1(\alpha|Z)}{\partial\alpha} \int_0^{G_3B_1(\alpha|Z)} \Phi [Z'_1\gamma_1(\alpha), Z'_2\gamma_2[G_2B_1(\alpha|Z)], Z'_3\gamma_3(t_3)] c(t_3|\alpha, Z) dt_3 \\ - \frac{\partial g_3b_1(\alpha|Z)}{\partial\alpha} \int_0^{G_2B_1(\alpha|Z)} \Phi [Z'_1\gamma_1(\alpha), Z'_2\gamma_2(t_2), Z'_3\gamma_3[G_3B_1(\alpha|Z)]] c(t_2|\alpha, Z) dt_2 \\ - 2g_2b_1(\alpha|Z) g_3b_1(\alpha|Z) c[G_2B_1(\alpha|Z), G_3B_1(\alpha|Z)|\alpha, Z] \\ \quad \times \Phi [Z'_1\gamma_1(\alpha), Z'_2\gamma_2[G_2B_1(\alpha|Z)], Z'_3\gamma_3[G_3B_1(\alpha|Z)]] \\ - g_2b_1(\alpha|Z) \int_0^{G_3B_1(\alpha|Z)} \Phi [Z'_1\gamma_1(\alpha), Z'_2\gamma_2[G_2B_1(\alpha|Z)], Z'_3\gamma_3(t_3)] \frac{\partial c(t_3|\alpha, Z)}{\partial\alpha} dt_3 \\ - g_3b_1(\alpha|Z) \int_0^{G_2B_1(\alpha|Z)} \Phi [Z'_1\gamma_1(\alpha), Z'_2\gamma_2(t_2), Z'_3\gamma_3[G_3B_1(\alpha|Z)]] \frac{\partial c(t_2|\alpha, Z)}{\partial\alpha} dt_2. \end{aligned}$$

Differentiating $W(\alpha|Z)$ with respect to Z_{2d} gives, by (3.8)

$$\begin{aligned} \mathbf{D}_2[\Phi, \Gamma](\alpha|Z) \frac{1}{g_2b_1(\alpha|Z)} \frac{\partial G_2B_1(\alpha|Z)}{\partial Z_{2d}} \frac{\partial\{Z'_2\gamma_2[G_2B_1(\alpha|Z)]\}}{\partial\alpha} \\ + \mathbf{D}_3[\Phi, \Gamma](\alpha|Z) \frac{1}{g_3b_1(\alpha|Z)} \frac{\partial G_3B_1(\alpha|Z)}{\partial Z_{2d}} \frac{\partial\{Z'_3\gamma_3[G_3B_1(\alpha|Z)]\}}{\partial\alpha} = \psi_{2d}[\Phi, \Gamma](\alpha|Z) \end{aligned}$$

where

$$\begin{aligned}
\psi_{2d} [\Phi, \Gamma] (\alpha|Z) &= \frac{\partial W (\alpha|Z)}{\partial Z_{2d}} \\
&- g_2 b_1 (\alpha|Z) \gamma_{2d} [G_2 B_1 (\alpha|Z)] \int_0^{G_3 B_1 (\alpha|Z)} \Phi_{x_2} [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 [G_2 B_1 (\alpha|Z)], Z'_3 \gamma_3 (t_3)] c (t_3|\alpha, Z) dt_3 \\
&- \frac{\partial g_2 b_1 (\alpha|Z)}{\partial Z_{2d}} \int_0^{G_3 B_1 (\alpha|Z)} \Phi [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 [G_2 B_1 (\alpha|Z)], Z'_3 \gamma_3 (t_3)] c (t_3|\alpha, Z) dt_3 \\
&- \frac{\partial g_3 b_1 (\alpha|Z)}{\partial Z_{2d}} \int_0^{G_2 B_1 (\alpha|Z)} \Phi [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 (t_2), Z'_3 \gamma_3 [G_3 B_1 (\alpha|Z)]] c (t_2|\alpha, Z) dt_2 \\
&- \left(g_2 b_1 (\alpha|Z) \frac{\partial G_3 B_1 (\alpha|Z)}{\partial Z_{2d}} + g_3 b_1 (\alpha|Z) \frac{\partial G_2 B_1 (\alpha|Z)}{\partial Z_{2d}} \right) \\
&\quad \times \Phi [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 [G_2 B_1 (\alpha|Z)], Z'_3 \gamma_3 [G_3 B_1 (\alpha|Z)]] c [G_2 B_1 (\alpha|Z), G_3 B_1 (\alpha|Z) | \alpha] \\
&- g_2 b_1 (\alpha|Z) \int_0^{G_3 B_1 (\alpha|Z)} \Phi [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 [G_2 B_1 (\alpha|Z)], Z'_3 \gamma_3 (t_3)] \frac{\partial c (t_3|\alpha, Z)}{\partial Z_{2d}} dt_3 \\
&- g_3 b_1 (\alpha|Z) \int_0^{G_2 B_1 (\alpha|Z)} \Phi [Z'_1 \gamma_1 (\alpha), Z'_2 \gamma_2 (t_2), Z'_3 \gamma_3 [G_3 B_1 (\alpha|Z)]] \frac{\partial c (t_2|\alpha, Z)}{\partial Z_{2d}} dt_2.
\end{aligned}$$

Multiplying by Z_{2d} and summing then gives, for $\Psi_2 [\Phi, \Gamma] (\alpha|Z) = \sum_{d=1}^D Z_{2d} \psi_{2d} [\Phi, \Gamma] (\alpha|Z)$,

$$\begin{aligned}
\mathbf{D}_2 [\Phi, \Gamma] (\alpha|Z) &\frac{Z'_2 \partial_{Z_2} G_2 B_1 (\alpha|Z)}{g_2 b_1 (\alpha|Z)} \frac{\partial \{Z'_2 \gamma_2 [G_2 B_1 (\alpha|Z)]\}}{\partial \alpha} + \\
\mathbf{D}_3 [\Phi, \Gamma] (\alpha|Z) &\frac{Z'_3 \partial_{Z_3} G_3 B_1 (\alpha|Z)}{g_3 b_1 (\alpha|Z)} \frac{\partial \{Z'_3 \gamma_3 [G_3 B_1 (\alpha|Z)]\}}{\partial \alpha} = \Psi_2 [\Phi, \Gamma] (\alpha|Z)
\end{aligned}$$

A similar equation holds for Z_3 . Let $\mathbf{D} [\Phi, \Gamma] (\alpha|Z)$ be the 3×3 diagonal matrix with entries $\mathbf{D}_k [\Phi, \Gamma] (\alpha|Z)$ and $\Psi [\Phi, \Gamma] (\alpha|Z)$ be the 3×1 vector with entries $\Psi_k [\Phi, \Gamma] (\alpha|Z)$, $k = 1, 2, 3$.

Define

$$\begin{aligned}
\mathbf{G} (\alpha|Z) &= \begin{bmatrix} 1 & g_2 b_1 (\alpha|Z) & g_3 b_1 (\alpha|Z) \\ 0 & \frac{Z'_2 \partial_{Z_2} G_2 B_1 (\alpha|Z)}{g_2 b_1 (\alpha|Z)} & \frac{Z'_3 \partial_{Z_3} G_3 B_1 (\alpha|Z)}{g_3 b_1 (\alpha|Z)} \\ 0 & \frac{Z'_3 \partial_{Z_3} G_2 B_1 (\alpha|Z)}{g_2 b_1 (\alpha|Z)} & \frac{Z'_2 \partial_{Z_2} G_3 B_1 (\alpha|Z)}{g_3 b_1 (\alpha|Z)} \end{bmatrix} \\
&= \begin{bmatrix} 1 & g_2 b_1 (\alpha|Z) & g_3 b_1 (\alpha|Z) \\ 0 & \frac{Z'_2 \partial_{Z_2} G_2 B_1 (\alpha|Z)}{\alpha(1-\alpha)} & \frac{Z'_2 \partial_{Z_2} G_3 B_1 (\alpha|Z)}{\alpha(1-\alpha)} \\ 0 & \frac{Z'_3 \partial_{Z_3} G_2 B_1 (\alpha|Z)}{\alpha(1-\alpha)} & \frac{Z'_3 \partial_{Z_3} G_3 B_1 (\alpha|Z)}{\alpha(1-\alpha)} \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{\alpha(1-\alpha)}{g_2 b_1 (\alpha|Z)} & 0 \\ 0 & 0 & \frac{\alpha(1-\alpha)}{g_3 b_1 (\alpha|Z)} \end{bmatrix}.
\end{aligned}$$

As in the two bidder case, Assumptions I and S-(iv) with Lemma 1-(ii) ensure that $\mathbf{G} (\alpha|Z)$ has an inverse when α belongs to $(0, 1)$ with $\mathbf{G}^{-1} (\alpha|Z)$ of order $1/\alpha$ when α goes to 0.

Observe as well that $\mathbf{D}[\Phi, \Gamma](\alpha|z)$ has an inverse for all α under Assumption I. $\mathbf{G}(\alpha|Z)$ also has an inverse for α in $(0, 1)$ but not if $\alpha = 0$ or $\alpha = 1$. Stacking the equations above together shows that

$$\mathbf{G}(\alpha|Z) \mathbf{D}[\Phi, \Gamma](\alpha|Z) \frac{d}{d\alpha} \Gamma(\alpha|z) = \Psi[\Phi, \Gamma](\alpha|Z)$$

for all α in $[0, 1]$. This also gives for all α in $[0, 1]$

$$\frac{d}{d\alpha} \Gamma(\alpha|Z) = \{\mathbf{G}(\alpha|Z) \mathbf{D}[\Phi, \Gamma](\alpha|Z)\}^{-1} \Psi[\Phi, \Gamma](\alpha|Z)$$

passing at the limit in the RHS for $\alpha = 0$ or 1 .

As above, identification of the slope functions holds provided two continuously differentiable solutions of (A.2.2), $\Gamma(\cdot|Z)$ and $\tilde{\Gamma}(\cdot|Z)$ with $\tilde{\Gamma}(0|Z) = \Gamma(0|Z)$, must be equal. Now it holds

$$\begin{aligned} \frac{d}{d\alpha} \Gamma(\alpha|Z) - \frac{d}{d\alpha} \tilde{\Gamma}(\alpha|Z) &= \{\mathbf{G}(\alpha|Z) \mathbf{D}[\Phi, \Gamma](\alpha|Z)\}^{-1} \Psi[\Phi, \Gamma](\alpha|Z) \\ &\quad - \{\mathbf{G}(\alpha|Z) \mathbf{D}[\Phi, \tilde{\Gamma}](\alpha|Z)\}^{-1} \Psi[\Phi, \tilde{\Gamma}](\alpha|Z) \end{aligned}$$

with $|\mathbf{D}[\Phi, \Gamma](\alpha|Z) - \mathbf{D}[\Phi, \tilde{\Gamma}](\alpha|Z)| \leq C\alpha$ and $|\Psi[\Phi, \Gamma](\alpha|Z) - \Psi[\Phi, \tilde{\Gamma}](\alpha|Z)| \leq C\alpha$ for all α . Set, for a fixed Z , $\Delta(\alpha) = \tilde{\Gamma}(\alpha|Z) - \Gamma(\alpha|Z)$. Note that $\Delta(\cdot)$ is continuously differentiable with $\Delta(0) = 0$, $\Delta(\alpha) = \int_0^\alpha \Delta^{(1)}(t) dt$ and that there exists a $\lambda > 0$ such that for all α

$$|\Delta(\alpha)| \leq \lambda\alpha.$$

It also holds for all α in $[0, 1]$

$$|\Delta^{(1)}(\alpha)| \leq \frac{C}{\alpha} |\Delta(\alpha)|.$$

Hence for all $\epsilon > 0$ small enough, (A.2) gives

$$|\Delta^{(1)}(\alpha)| \leq \mathbb{I}(\alpha \leq \epsilon) \lambda + \mathbb{I}(\epsilon < \alpha \leq 1) \frac{C}{\epsilon} |\Delta(\alpha)|.$$

Arguing as in the two bidder case gives that $\Delta(\cdot) = 0$, which establishes identification of the $\gamma_j(\cdot)$, $j \in \mathcal{I}$. This ends the proof of the Theorem. \square