

# 1 Highlights

## 2 **Integrated modelling of insect population dynamics at two temporal scales**

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- 5 • We model population decline of the endangered beetle *Iberodorcadion fuliginator*.
- 6 • Population size is modelled at two temporal scales for a two-year life cycle.
- 7 • Integrated population modelling enables true abundance estimation.
- 8 • The models include productivity, phenology, survival and detection parameters.
- 9 • Our model can improve ecological understanding for rare species with limited data.

# Integrated modelling of insect population dynamics at two temporal scales

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## Abstract

Population size of species with birth-pulse life-cycles varies both within and between seasons, but most population dynamics models assume that a population can be characterised adequately by a single number within a season. However, within-season dynamics can sometimes be too substantial to be ignored when modelling dynamics between seasons. Typical examples are insect populations or migratory animals. Numerous models for only between-season dynamics exist, but very few have combined dynamics at both temporal scales.

In a new approach, we extend appreciably the models of Dennis et al (2016b): we show how to adapt them for a generation time  $>1$  year and fit an integrated population model for multiple data types, by maximising a joint likelihood for population counts of unmarked individuals and capture-recapture data from a study with marked individuals. We illustrate the approach using annual monitoring data for the endangered flightless beetle *Iberodorcadion fuliginator* from 18 populations in the Upper Rhine Valley for 1998–2016, with a 2-year life cycle. Standard likelihood methods are used for model fitting and comparison, and a concentrated (profile) likelihood approach provides computational efficiency.

Additional information from the capture-recapture data makes the population model more robust and, importantly, enables true, rather than relative, abundance to be estimated. A dynamic stopover model provides estimates of both survival and phenology parameters within a season, and also of productivity between seasons. For *I. fuliginator*, we demonstrate

39 a population decline since 1998 and how this links with productivity, which is affected by  
40 temperature. A delayed mean emergence date in recent years is also shown.

A main point of interest is the focus on the two temporal scales at which perhaps most animal populations vary: in the short-term, a population is seldom truly closed within a single season, and in the long term (between seasons) it never is. Hence our models may serve as a template for a general description of population dynamics in many species. This includes rare species with limited data sets, for which there is a general lack of population dynamic models, yet conservation actions may greatly benefit from this kind of models.

41 *Keywords:* Beetle, Endangered, *Iberodorcadion fuliginator*, integrated population model,  
42 Multi-scale population dynamics, Population model

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## 43 1. Introduction

44 Most models of population dynamics assume a study species with a birth-pulse life-cycle  
45 in a seasonal environment, i.e., a species that reproduces during a particular time of the  
46 year, typically in the spring or summer in temperate or cold latitudes. A discrete-time  
47 model with autoregressive representation of population dynamics is then typically chosen,  
48 where the state of a population at time  $t + 1$  is expressed as a function of its state at  
49 time  $t$ , including parameters that describe the state transition rates between seasons, e.g.,  
50 demographic or growth rate parameters. Especially for large animals, such as most birds  
51 and mammals, it is assumed that the state (typically abundance  $N$ , which may be stratified  
52 by age or other classification factors), can be characterised by a single number (or a vector of  
53 such numbers) at time  $t$ . Matrix projection models are the typical example of such models  
54 (Caswell, 2001) and have proved to be extremely powerful for modelling population dynamics  
55 between seasons. Moreover,  $N$  may be estimated using adequate data such that imperfect  
56 detection can be accounted for, e.g. distance or capture-recapture sampling (McCrea and  
57 Morgan, 2014; Buckland et al., 2015; Böhning et al., 2017). The literature on population  
58 dynamics across seasons is extensive (e.g. Koons et al., 2017).

59 However, many situations exist where the abundance of a population at time  $t$  cannot  
60 easily be characterised because the population is open within a season and there may be

61 a constant flux of individuals through the area defining a population. An estimate of  $N$   
62 then comprises all individuals that enter and leave the area within a season. Examples  
63 are provided by migratory animals at stopover sites, reptiles and pond-breeding amphibians  
64 (Matechou et al., 2016), or conceivably migratory wildlife at any observation point (e.g.,  
65 whales or salmon along a stretch of shore or river, respectively): abundance within a season  
66 is then governed by the rates at which new animals arrive, stay and eventually depart again.  
67 Another example, which provides the motivation for the present paper, is provided by the  
68 imago stage of insects, many of which exhibit typical “phenological curves” within a season.  
69 The modelling of population dynamics for species with such pronounced short-term dynamics  
70 presents a challenge, because the changes in numbers must be described at two temporal  
71 scales: not only between seasons but also within each season.

72 Previous population dynamics modelling within seasons involves stopover models (e.g.  
73 Schaub et al., 2001; Matechou et al., 2014) and phenological curves. The seminal Manly-  
74 Zonneveld (MZ) model describes numbers within a season as a function of abundance, mean  
75 and spread of emergence date, and a constant survival probability (Manly, 1974; Zonneveld,  
76 1991). This model was generalised to species with multiple generations within a season by  
77 Matechou et al. (2014) and Dennis et al. (2016b, henceforth DMFRB). Both approaches  
78 describe the trajectory of an observable population from zero to some maximum and back  
79 to zero again within one season. In stopover models, gains and losses for the population of  
80 staging animals are represented predominantly by arrival and departure, while for one insect  
81 generation, they are mostly represented by rates of birth/emergence and death.

82 DMFRB developed a multi-scale population dynamics model for univoltine and bivoltine  
83 butterfly species (i.e., with generation time  $< 1$  year). We extend their model in two  
84 important ways: we adapt the model to a biennial life-cycle, where annual cohorts are es-  
85 sentially demographically closed and there are distinct generations from odd and even years,  
86 and we fit multi-scale population dynamics models as an integrated population model (IPM;  
87 Besbeas et al., 2002; Schaub and Abadi, 2011) by jointly fitting them to two data types: a  
88 multivariate time-series of counts of unmarked individuals and a capture-recapture data set

89 from marked animals.

90 Our motivating example is an ongoing, long-term population study on the endangered,  
91 flightless beetle *Iberodorcadion fuliginator* at the Southern end of the Upper Rhine valley. As  
92 well as being important in itself for an improved understanding for this conservation flagship  
93 species, the analyses of this data set illustrate how to meet the challenges of modelling long  
94 time series of data on rare species and result in definite conclusions.

## 95 **2. Material and Methods**

### 96 *2.1. Study species and area*

97 The beetle *I. fuliginator* has a life cycle of 2 years (Baur et al., 1997). Females deposit  
98 their eggs in stems of grass, preferably *Bromus erectus*, their main larval host plant, in late  
99 March through to May. The larvae hatch in May or June, feed on grass roots and pupate  
100 after c.14 months (including one hibernation in a late larval stage). Imagos (14–17 mm body  
101 length) eclose after 2–3 weeks in July or August, but rest in the soil until the end of the  
102 second hibernation. Depending on weather conditions, imagos emerge from the soil in March  
103 or April and are sexually active for c.1 month before they die.

104 Beetle populations were studied near the Swiss city of Basel (47.56°N, 7.58°E), in France,  
105 Germany and Switzerland. The maximum extent of the study area defined by the locations  
106 of the populations is about 16 km in North-South and about 12 km in East-West directions.  
107 See Baur et al. (1997, 2002, 2005) and Table S1 in the Supporting Information for features  
108 of the study populations. We use ‘site’ and ‘population’ synonymously.

### 109 *2.2. Field methods*

110 We use data from three field studies: (1) repeated counts of adult beetles in 18 popu-  
111 lations from 19 years, (2) intensive, single-year capture-recapture studies in three of these  
112 populations, and (3) soil temperature measured over 16 years in Birsfelden, Switzerland  
113 (B. Baur, unpublished). Data associated with this analysis can be found here [https:](https://doi.org/10.6084/m9.figshare.7740254.v1)  
114 [//doi.org/10.6084/m9.figshare.7740254.v1](https://doi.org/10.6084/m9.figshare.7740254.v1).

115 *2.2.1. Population counts*

116 After the 1990s, 18 populations were found in the study area (see Baur et al. 2002),  
117 and are summarised in Table S1 of the Supporting Information. For two populations (Basel  
118 and Allschwil) count data were available from 1998 and for the remainder only from 2001  
119 onwards (up to 2016). Populations were surveyed repeatedly during each activity period  
120 of *I. fuliginator* (March-May), with typically 4–8 intensive surveys each lasting for up to  
121 several hours and sometimes involving several people. In most populations, total search  
122 time was 240 minutes per year and survey durations took an average of 40 minutes (range  
123 1–260 minutes).

124 *2.2.2. Capture-recapture study*

125 Data from intensive capture-recapture studies were available from three sites in two  
126 different years (Baur et al., 2005). In total 345 beetles were marked uniquely using coloured  
127 nail varnish, and recaptured during 20 daily occasions at site Basel (1st April - 22nd May  
128 1988). Between 19th April and 7th June 2000, 433 beetles were marked/recaptured at site  
129 Istein during 27 days and 102 beetles at site Huttingen during 21 days. On each day the  
130 study sites were carefully searched for *I. fuliginator* for several hours and survey duration  
131 (person-hours) was recorded as a measure of effort. Survey durations ranged from 1.7–8.3  
132 hours (mean 6.1) in Basel, from 3.0–16.0 hours (mean 9.5) in Istein and from 3.5–9.3 hours  
133 (mean 6.5) in Huttingen. Capture-recapture proceeded as described in Baur et al. (2005).  
134 Note that throughout we estimate apparent survival, due to possible movement of beetles  
135 outside survey areas.

136 *2.2.3. Temperature covariates: Heat load at each site, and sum of effective temperatures*  
137 *(SET)*

138 The development time of *I. fuliginator* depends on soil temperature, which can be ex-  
139 pressed as the sum of effective temperatures (SET), which is the sum of the temperature  
140 above the lower developmental threshold (LDT), the temperature below which there is no  
141 development.

142 We use measures of between-site (equivalent to between-population) and between-year  
 143 variation in soil temperature. As a proxy for between-site differences in mean soil tempera-  
 144 ture, we calculated the mean heat load (HL) for each site using the model of McCune and  
 145 Keon (2002), which incorporates topographical variables (aspect, inclination) and latitude.

146 For between-year variation in soil temperature, we used soil temperature measurements  
 147 at a depth of 5 cm, which corresponds to the depth at which the larvae live, in a patch of  
 148 nutrient-poor grassland in Birsfelden, about 5 km from the nearest population in our study  
 149 (Basel). Soil temperature was recorded at intervals of 3 h over 16 years (2001–2016) using  
 150 Tinytalk temperature loggers (GeminiData Loggers, Chichester, UK). In the analyses, we  
 151 used mean soil temperature per day obtained from six measurements. In model fitting we use  
 152 degree-days (DD; one value for each year, taking the same value for all sites) as a measure  
 153 of cumulative soil temperature - these are the summation of temperature differences over  
 154 time, which capture both extremity and duration of higher temperatures. However, for *I.*  
 155 *fuliginator* the LDT is unknown, hence we calculated DD for 11 different LDT values (7–17  
 156 °C) and each time fitted our model to then determine which LDT value provides the best  
 157 explanation of the observed data, in terms of predictive power, using Akaike’s information  
 158 criterion (AIC) - see Section 2.8.

159 We also use the daily mean temperature at Basel (TEMP) from 1998 to 2016 to describe  
 160 detection probability (M. Baumann, Meteorological Office of Basel, Switzerland).

### 161 2.3. The dynamic model and productivity parameters

162 We extend a dynamic model which was originally designed for butterflies (DMFRB). We  
 163 denote the counts by  $\{y_{i,j,k}\}$ , taken on site  $i$ , during visit  $j$ , and year  $k$ , assuming that data  
 164 are collected for  $S$  sites, each visited on  $\leq T$  occasions, across  $K$  successive years. Each  
 165 count can be treated as the realisation of an independent random variable from a Poisson  
 166 distribution with expectation  $\lambda_{i,j,k}$ . We assume independence since the counts were taken  
 167 far apart in time and space. The likelihood then has the form

$$L_S(\boldsymbol{\rho}, \mathbf{a}, \mathbf{p}, \mathbf{N}; \mathbf{y}) = \prod_{i=1}^S \prod_{j=1}^T \prod_{k=1}^K \frac{\exp(-\lambda_{i,j,k}) \lambda_{i,j,k}^{y_{i,j,k}}}{y_{i,j,k}!}. \quad (1)$$

168 We use boldface to indicate vectors and matrices, and we describe the model parameters  
 169 below. For a general model we let

$$\lambda_{i,j,k} = N_{i,k} p_{i,j,k} a_{i,j,k}, \quad (2)$$

170 where

- 171 •  $N_{i,k}$  denotes abundance (= number of individuals ever alive) at site  $i$  in year  $k$ ,
- 172 •  $p_{i,j,k}$  is the detection probability for visit  $j$ , at site  $i$  in year  $k$ ,
- 173 •  $a_{i,j,k}$  is a unimodal function that describes the within-season variation of abundance.

174 Equation 2 contains detection probabilities, which did not feature in the models of DM-  
 175 FRB. In principle such parameters can be estimated from count data alone, making use of  
 176 covariate regressions (Matechou et al., 2014). However this can be difficult in practice, due  
 177 to the limited amount of information (Knape and Korner 2015). Thus we only introduce  
 178 detection probabilities when an integrated analysis is performed; where the model is ap-  
 179 plied to count data alone detection probabilities are not identifiable and are subsumed into  
 180  $\{N_{i,k}\}$ , which is therefore a measure of relative abundance, i.e., the product of  $N$  and  $p$ , as  
 181 in DMFRB.

182 The framework of the DMFRB model allows two approaches for describing within-season  
 183 variation in abundance: a phenomenological approach, which fits one or more Gaussian  
 184 curves directly, or a mechanistic stopover approach which fits a birth/death population  
 185 model and explicitly models the pattern of emergence using one or more Gaussian curves.  
 186 Here we focus on a mechanistic approach. These models provide alternative forms for the  
 187  $\{a_{i,j,k}\}$  of Equation 2. Inserting the expression of Equation 2 into Equation 1 provides the  
 188 likelihood for the survey data,  $L_S$ , with additional parameters,  $\boldsymbol{\rho}$  and those of  $\mathbf{a}$ , to be  
 189 described below. Results, not shown here, from adopting the alternative, phenomenological  
 190 models (see DMFRB) for our data set are in good agreement with those that we present.

191 To account for a two-year life cycle we let

$$N_{i,k} = \rho_{i,k-2} N_{i,k-2}. \quad (3)$$



Here, the abundance in a given year depends on the product of the abundance from two years previously and the productivity across the two intermediate years, which is described by the single parameter  $\rho_{i,k-2}$ . Hence from Equation 2,

$$\lambda_{i,j,1} = N_{i,1}p_{i,j,1}a_{i,j,1}$$

and

$$\lambda_{i,j,2} = N_{i,2}p_{i,j,2}a_{i,j,2},$$

192 and for  $k > 2$ , by iterating the relationships of Equation 3, we obtain for Equation 2

$$\lambda_{i,j,k} = N_{i,k}p_{i,j,k}a_{i,j,k} = \begin{cases} \left( N_{i,1} \prod_{m=1}^{(k-1)/2} \rho_{i,2m-1} \right) p_{i,j,k}a_{i,j,k} & \text{if year } k \text{ is odd,} \\ \left( N_{i,2} \prod_{m=1}^{(k-2)/2} \rho_{i,2m} \right) p_{i,j,k}a_{i,j,k} & \text{if year } k \text{ is even.} \end{cases} \quad (4)$$

193 Equation 3 expresses a simple deterministic relationship and the corresponding stochastic  
194 formulation could be modelled in terms of a hidden Markov model (Besbeas and Morgan,  
195 2020). We have investigated both types of model, and found little difference in their results  
196 when applied to monitoring data for butterflies in models such as in DMFRB, and so we  
197 adopt the simpler model here.

198 We use the total of the estimates,  $\hat{N}_{i,k}$ , of the site parameters,  $N_{i,k}$ , as a measure of  
199 overall abundance,  $G_k = \sum_i \hat{N}_{i,k}$ , for each year  $k$ .

#### 200 *2.4. Describing seasonality using a stopover model*

201 We specify  $\{a_{i,j,k}\}$  using a stopover model, which builds survival into the models by  
202 introducing additional parameters, including the mean emergence times of adults. These  
203 phenological parameters are typically unknown, and of interest in their own right as descrip-  
204 tors of a specific, key point in a species' life-cycle and thus potentially useful indicators of  
205 phenological change. The approach is based upon the stopover model of Matechou et al.  
206 (2014), which DMFRB extended to the analysis of data from multiple years, introducing  
207 and estimating productivity parameters.

208 The expected number of individuals counted at site  $i$  at time  $t_{i,j,k}$  in year  $k$  is given as

$$\lambda_{i,j,k} = N_{i,k} p_{i,j,k} a_{i,j,k} = N_{i,k} p_{i,j,k} \left\{ \sum_{d=1}^j \beta_{i,d-1,k} \left( \prod_{m=d}^{j-1} \phi_{i,m,k} \right) \right\}, \quad (5)$$

209 where the index  $d = 1, \dots, j$ , indicates the possible times of emergence for an individual  
 210 detected on visit  $j$ . We define  $\phi_{i,m,k}$  as the probability that an individual that is present at  
 211 site  $i$  at visit  $m$  in year  $k$  will remain at that site until visit  $m + 1$ . The  $\beta_{i,d-1,k}$  describe the  
 212 proportions of  $N_{i,k}$  emerging at site  $i$  and visit  $d$  in year  $k$ , such that  $\sum_{d=1}^T \beta_{i,d-1,k} = 1$ , for  
 213 each site  $i$  and year  $k$ . In order that this emergence pattern has the right shape for univoltine  
 214 data, we set

$$\beta_{i,d-1,k} = F_{i,k}(t_{i,d,k}) - F_{i,k}(t_{i,d-1,k}), \quad (6)$$

215 where  $F_{i,k}(t_{i,d,k}) = P(X \leq t_{i,d,k})$  for  $X \sim N(\mu_{i,k}, \sigma_{i,k}^2)$ ,  $\mu_{i,k}$  is the mean date of emergence  
 216 and  $\sigma_{i,k}^2$  is the associated variance, which represents the spread of the emergence period.  
 217 Thus the  $\beta$ 's are appropriate areas under a Gaussian curve, which ensures that they have  
 218 the correct shape, starting small, rising to a maximum over time and then reducing to zero as  
 219 time increases within a season. For each  $i$  and  $k$ ,  $\beta_{i,0,k} = F_{i,k}(1)$  and  $\beta_{i,T-1,k} = 1 - F_{i,k}(T-1)$ .

## 220 2.5. Obtaining maximum likelihood parameter estimates by concentrated likelihood

221 We obtain maximum likelihood parameter estimates for these models via a concentrated  
 222 (profile) likelihood approach (see DMFRB). The approach reduces the dimensions of the  
 223 likelihood by optimising with respect to parameters relating only to  $\boldsymbol{\rho}$  and  $\mathbf{a}$ , providing  
 224 computational efficiency.

225 We set out to maximise the likelihood of Equation 1 by first forming its first-order  
 226 derivatives with respect to the individual parameters. When that is done, and the resulting  
 227 equations are all set equal to zero in search of a maximum, we find that the initial site  
 228 parameters can be written as a function of the data and other parameters, as

$$N_{i,1} = \sum_{j=1}^T \frac{\sum_{k=1}^{(V-1)/2} y_{i,j,2m-1}}{a_{i,j,1} + \sum_{k=1}^{(V-1)/2} a_{i,j,2k+1} \prod_{m=1}^k \rho_{i,2m-1}}, \quad (7)$$

229 and

$$N_{i,2} = \sum_{j=1}^T \frac{\sum_{k=1}^{(V-2)/2} y_{i,j,2k}}{a_{i,j,2} + \sum_{k=1}^{(V-2)/2} a_{i,j,2k} \prod_{m=1}^k \rho_{i,2m}}. \quad (8)$$

230 Substituting the expressions of (7) and (8) into the likelihood, we can optimise with respect  
231 to parameters relating only to  $\boldsymbol{\rho}$  and  $\mathbf{a}$ .

232 After the model is fitted, estimates of  $\{N_{i,1}\}$  and  $\{N_{i,2}\}$  can be obtained by inserting  $\hat{\boldsymbol{\rho}}$   
233 and  $\hat{\mathbf{a}}$  in Equations 7 and 8, and  $\{N_{i,k}\}$  for  $k > 2$  are derived from Equation 4. This approach  
234 appreciably speeds up the likelihood optimisation. The performance of the dynamic model,  
235 adapted to account for a biennial life-cycle, was checked and verified using simulated data  
236 (results not shown here). This demonstrates the generality of the concentrated likelihood  
237 approach and its potential to be used for taxa with several years in different states.

238 The likelihood is maximised using the `optim` numerical optimisation function in R (R  
239 Core Team, 2018). Standard errors were obtained from the inverse of the Hessian matrix  
240 at the likelihood maxima, and transformed using the Delta method (Morgan, 2009, p.123),  
241 where appropriate link functions were used.

## 242 *2.6. Capture-recapture modelling*

243 Parameter estimates for apparent daily survival,  $\phi$ , and detection probability,  $p$ , were  
244 obtained from the capture-recapture (CR) data for the Cormack-Jolly-Seber model (see  
245 McCrea and Morgan 2014, p.70), using the `marked` package in R (Laake et al., 2013). Separate  
246 likelihoods were formed and maximised for the data from each of the three sites. We estimate  
247  $\phi$  as time-independent throughout, and take  $p$  to vary logistically with survey duration. We  
248 note that Baur et al. (2005) used a Jolly-Seber model to estimate survival using the same  
249 data, and also estimate population size for the years 1988 and 2000, for particular sites. The  
250 component likelihood,  $L_M$ , is given by McCrea and Morgan (2014, p.70).

## 251 *2.7. Integrated population modelling*

252 Integrated population modelling was initially proposed in the area of fisheries science (see  
253 McCrea and Morgan, 2014, p.227). The approach of this paper was proposed by Besbeas  
254 et al. (2002). By modelling independent time-series of counts and capture-recapture data  
255 through a joint likelihood, which is the product of likelihoods for each component data set,  
256 we are able to combine data from different sources on different aspects of the same species

257 in a single analysis. Common model parameters are thereby estimated more precisely than  
258 would otherwise be the case, and a single analysis replaces piecemeal, separate analyses. In  
259 general terms, this improves the understanding of the species' ecology. In particular, as we  
260 shall see, it may be possible through an integrated analysis to estimate model parameter(s)  
261 that would not have been otherwise possible due to confounding. The approach of IPM is  
262 now widely adopted, and the area remains one of active research; see for example, Matechou  
263 et al. (2013), Besbeas and Morgan (2019) and Schaub and Kéry (2021).

264 We assume that the capture-recapture and count data sets are independent. Conse-  
265 quently, for IPM likelihoods are formed for the separate data sets, and then multiplied  
266 together to form a single joint likelihood, which is maximised to obtain maximum-likelihood  
267 estimates of all model parameters that are informed from both the count and CR data simul-  
268 taneously. The capture-recapture modelling directly informs probabilities of daily survival  
269 and detection, which improves estimation of survival in the model for the count data. More-  
270 over, the IPM formulation enables us to estimate absolute, rather than relative abundance.

271 The concentrated-likelihood approach is also used for the joint likelihood,  $L_J$ . Here we  
272 have three capture-recapture likelihoods and one count likelihood, and the joint likelihood  
273 has the form

$$L_J = L_{M_1} L_{M_2} L_{M_3} L_S,$$

274 where  $L_S$  is given in Equation 1 and  $L_{M_i}$  is the likelihood for the  $i^{th}$  capture-recapture  
275 data set. The first three components are functions of  $\phi$  and  $p$  parameters only, while the  
276 last is a function of all the model parameters. Because the capture-recapture likelihoods  
277 were obtained using the `marked` package in `R`, it is convenient to adopt the approach of  
278 Besbeas et al. (2003) to construct an approximate likelihood in each case, using a multivariate  
279 normal approximation with  $\phi$  and  $p$  parameters that are common for the data sets. Each  
280 approximate likelihood was based upon the maximum-likelihood estimates from Table S2 in  
281 the Supporting Information, and associated estimates of variance and covariance obtained  
282 from the inverse Hessian matrix at the likelihood maxima.

283 2.8. Model selection

284 We fitted and compared a fairly large number of models to test biological hypotheses  
285 about the beetle and to identify model structure that ‘best’ describes its population dy-  
286 namics. Following preliminary analysis of the count and capture-recapture data separately  
287 (see Supporting Information), we apply the integrated modelling approach, firstly with year-  
288 dependent productivity,  $\rho$ , either constant or year-dependent mean emergence date  $\mu$ , with  
289 detection probability,  $p$ , varying with survey duration (DUR) and all other parameters kept  
290 constant.

291 Prior to performing model selection for additional covariates, an optimal lower develop-  
292 mental threshold (LDT for *I. fuliginator* was chosen as follows. The integrated model was  
293 fitted with productivity,  $\rho$ , varying only with degree days (DD) for multiple values of LDT  
294 (see Section 2.2.3), and the optimal LDT chosen based on the model with lowest AIC. For  
295 this purpose both  $\mu$  and  $\sigma$  were considered constant, and detection probability  $p$  varied with  
296 survey duration.

297 The incorporation of additional covariates (including degree-days, DD, with optimal LDT  
298 now estimated), to describe productivity and detection probability was then explored, by  
299 fitting all model combinations and comparison via AIC. For computational efficiency, model  
300 selection was applied to models with constant rather than year-dependent mean emergence  
301 date,  $\mu$ . Productivity,  $\rho$ , was modelled as a logistic function of site heat load (HL) and/or  
302 DD, as well as year effects (YEAR). For detection probability,  $p$ , survey duration (DUR)  
303 and temperature (TEMP) were considered, as well as quadratic effects for temperature,  
304 again on the logistic scale. Here temperature was the daily mean temperature in Basel  
305 (described in Section 2.2.3). Throughout we assume the spread of emergence date,  $\sigma$ , to be  
306 constant across site and year, since models with year-variation in both  $\sigma$  and  $\mu$  will have  
307 many parameters to estimate, which is likely to be very time consuming and potentially  
308 problematic to fit. Following model selection, the top model was refitted but with year-  
309 dependent mean emergence date,  $\mu$ .

### 310 3. Results

#### 311 3.1. Integrated modelling

312 We first fit two integrated models to the count and capture-recapture data that assume  
313 either a constant or a year-varying mean emergence date  $\mu$ , but both assume spread of  
314 emergence  $\sigma$  and apparent survival  $\phi$  to be constant, detection parameter  $p$  to vary with  
315 survey duration in a linear-logistic manner, and productivity  $\rho$  to be year-varying (Table 1,  
316 a and b). Comparison with estimates from the analysis of count data alone (Table 2) shows  
317 increased precision from the integrated modelling, as expected. The model with year-varying  
318  $\mu$  produces an appreciably lower AIC, although there was minimal effect on the other model  
319 parameter estimates, except for  $\sigma$ . Estimates of productivity  $\rho$  and mean emergence date  $\mu$   
320 for each year from model b) are shown in Figures S2 and S3 of the Supporting Information  
321 and of the population size measure,  $G$ , from various integrated models in Figure S4 of the  
322 Supporting Information.

323 Peak emergence date,  $\mu$ , was estimated later under the integrated model than from the  
324 analysis of the count data alone, but estimates of  $\sigma$  were similar, and both parameters were  
325 estimated with increased precision (comparing Tables 1a and 2). The integrated models also  
326 produce a lower estimate for  $\phi$ , compared with the estimates in Table 2, which we attribute  
327 to the role played by detection probability  $p$  in the integrated analysis, and its dependence  
328 upon survey duration.

329 Standard errors for all model parameters were at least halved in the integrated analysis,  
330 compared to a simpler model for the count data alone, illustrating one of the benefits of this  
331 modelling approach.

#### 332 3.2. Incorporation of additional covariates

333 Models without the year effect for productivity were fitted first, to compare 11 threshold  
334 values for the degree-days covariate. A threshold of 15 degrees C was chosen by AIC, so this  
335 value was used in the full model comparison, which included the models where productivity  
336 can vary with year as well as degree-days. Although differences in AIC thresholds between

Table 1: Parameter estimates and associated standard errors (SE) for four integrated models, where  $n$  denotes the number of parameters estimated for each model. In all models, survival  $\phi$  and the spread of the emergence period  $\sigma$  are constant, and detection probability  $p$  varies logistically with survey duration, where  $p_{int}$  and  $p_{DUR}$  are the intercept and slope parameters, and  $\bar{p}$  is the mean estimate of  $p$  across durations. In models (a) and (b) productivity  $\rho$  varies only with year, whereas in models (c) and (d), following model selection (see Table 3),  $\rho$  varies with year and site heat load, where  $\rho_{HL}$  represents the slope parameter. Mean emergence date  $\mu$  is constant in models (a) and (c), but year-dependent in models (b) and (d). Year-dependent parameter estimates (for  $\rho$  and  $\mu$ ) are not given but are displayed in plots for selected models.

	a)		b)		c)		d)	
$n$	22		40		23		41	
AIC	5211.0		5024.3		5183.4		4984.9	
Parameter	Estimate	SE	Estimate	SE	Estimate	SE	Estimate	SE
$\rho_{HL}$					1.0794	0.1980	1.2902	0.2037
$\mu$	79.0181	3.5847	year-varying		77.7021	3.3293	year-varying	
$\sigma$	33.9607	3.1798	22.4269	1.6104	32.7917	3.0024	22.5838	1.6480
$\phi$	0.8793	0.0088	0.8757	0.0089	0.8787	0.0088	0.8778	0.0089
$p_{int}$	-3.0601	0.1567	-3.0628	0.1575	-3.0019	0.1566	-3.0073	0.1565
$p_{DUR}$	0.1062	0.0167	0.1082	0.0167	0.0996	0.0167	0.1008	0.0167
$\bar{p}$	0.0479		0.0479		0.0504		0.0502	

337 14 and 16 degrees C were less than 2, results were ultimately not influenced by the choice of  
338 threshold.

339 We consequently fit integrated dynamic models for a total of 28 covariate combinations,  
340 however, eight cases resulted in some very large standard error estimates. In these latter  
341 cases, all were models where productivity varied with at least year and degree-days (for which  
342 the Pearson's correlation coefficient was approximately 0.6), and they showed a minimum  
343 eigenvalue of the Hessian that was close to zero, suggesting that not all parameters were  
344 individually estimable. This finding was replicated for alternative thresholds for the degree-  
345 days covariate. The top 10 of the 20 remaining models are shown in Table 3.

346 The model with lowest AIC had 23 parameters and year-varying productivity that also

Table 2: Parameter estimates (with standard errors, SE) for the dynamic model fitted to the count data alone with constant (i) and time-varying mean emergence date  $\mu$  (ii); the number of parameters is denoted by  $n$ .  $\sigma$  represents the standard deviation of the emergence period. Annual estimates of productivity  $\rho$ , overall abundance  $G$  and time-varying  $\mu$  are provided in Figure S1 of the Supporting Information.

	i)		ii)	
n	20		38	
AIC	5155.2		4972.0	
Parameter	Estimate	SE	Estimate	SE
$\mu$	65.09	14.09	time-varying	
$\sigma$	34.75	5.83	21.93	1.72
$\phi$	0.98	0.03	0.90	0.04

Table 3: Range of models fitted with covariates, with associated AIC and  $\Delta$ AIC values. The formulae describe the formulation for productivity,  $\rho$ , and detection probability,  $p$ , respectively. This is a truncated table of the models with the ten smallest AIC values. Mean emergence date  $\mu$  and spread of the emergence period  $\sigma$  were assumed to be constant in all models.  $n$  is the number of parameters estimated and D is the estimated scaled deviance. HL denotes heat load, DD indicates degree-day, DUR indicates survey duration, and TEMP is a measure of daily mean temperature in Basel.

Model	$n$	D	AIC	$\Delta$ AIC
$\rho \sim \text{YEAR} + \text{HL}, p \sim \text{DUR}$	23	1.615	5183.4	0.0
$\rho \sim \text{YEAR} + \text{HL}, p \sim \text{DUR} + \text{TEMP}$	24	1.614	5191.5	8.1
$\rho \sim \text{YEAR} + \text{HL}, p \sim \text{TEMP}$	23	1.634	5198.8	15.4
$\rho \sim \text{YEAR} + \text{HL}, p \sim \text{DUR} + \text{TEMP} + \text{I}(\text{TEMP}^2)$	25	1.616	5200.1	16.8
$\rho \sim \text{YEAR}, p \sim \text{DUR}$	22	1.627	5211.0	27.6
$\rho \sim \text{YEAR}, p \sim \text{DUR} + \text{TEMP}$	23	1.626	5219.1	35.7
$\rho \sim \text{YEAR}, p \sim \text{DUR} + \text{TEMP} + \text{I}(\text{TEMP}^2)$	24	1.628	5228.9	45.5
$\rho \sim \text{YEAR}, p \sim \text{TEMP}$	22	1.650	5231.1	47.7
$\rho \sim \text{HL} + \text{DD}, p \sim \text{DUR}$	8	1.868	5719.8	536.4
$\rho \sim \text{HL} + \text{DD}, p \sim \text{DUR} + \text{TEMP}$	9	1.866	5726.1	542.7



347 varied with site heat load, and detection varying with survey duration. Inspection of the  
348 second best model showed the addition of temperature for detection was not needed. Refit-  
349 ting the top model in Table 3 but with year-varying (rather than constant) mean emergence  
350 date  $\mu$  greatly reduced the AIC to 4984.9, with 41 parameters. The scaled deviances of these  
351 models were 1.62 and 1.52, respectively, suggesting adequate descriptions of the data, albeit  
352 with a moderate amount of overdispersion relative to the basic Poisson model assumed. For  
353 estimates of the year-constant parameters see Table 1c) and d). Differences between param-  
354 eter estimates for the models with and without the site heat load parameter were minimal  
355 (Table 1).

356 Productivity under model d) varied greatly between years and correlated positively with  
357 site heat load (Figure 1). Estimates of peak emergence date  $\mu$  varied from about 20 to 90  
358 (Figure 2), becoming later by roughly one month over the period studied, but also less vari-  
359 able. The additional site heat load parameter for productivity did not have much influence  
360 on the estimates of  $\mu$  (see Figure S3 of the Supporting Information).

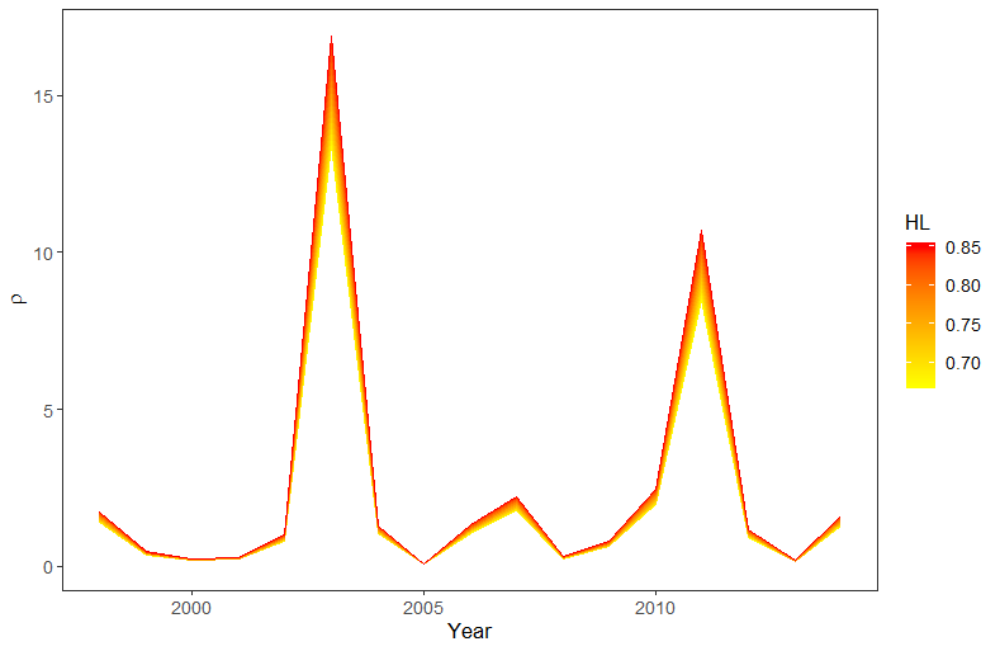


Figure 1: Estimated productivity,  $\rho$ , for each year across the range of site heat load (HL) values from the best-fitting integrated model with year-varying  $\mu$ . Confidence bands are not presented, but Figure S2 of the Supporting Information presents confidence bands for the model where HL is not included.

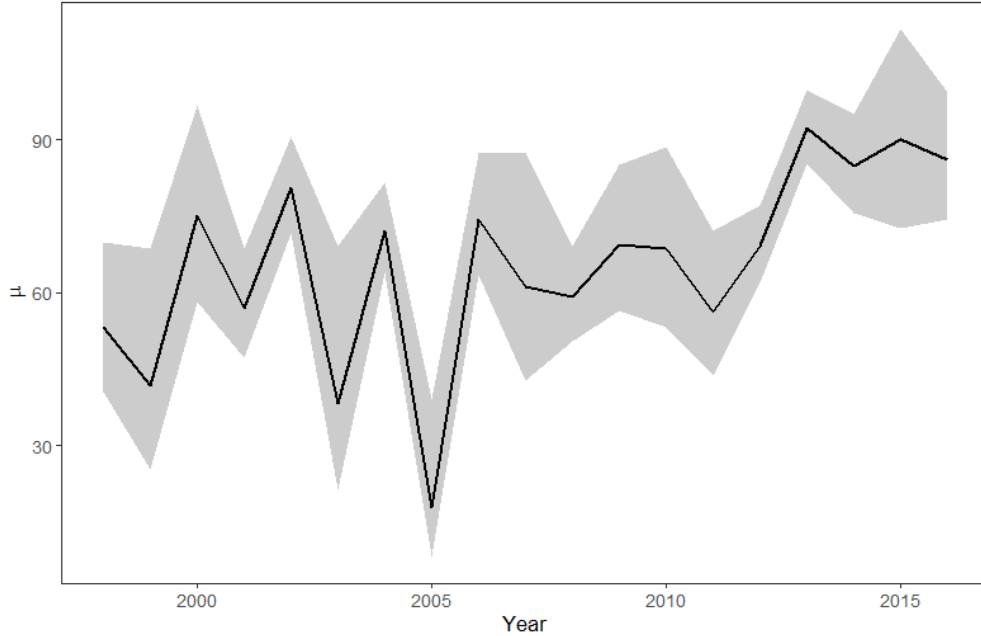


Figure 2: Estimated mean emergence date,  $\mu$ , per year measured in days from the best-fitting integrated model with year-varying  $\mu$ , and associated 95% confidence intervals. Day 60 corresponds to 15 April.

361 Estimates of absolute population size  $G$  under the best-fitting model (d in Table 1) are  
 362 shown in Figure 3 and indicate a downward trend over time. Estimates of  $G$  were similar  
 363 across all four IPMs fitted (see Figure S4 of the Supporting Information), although note  
 364 the difference in scale relative to the model applied to count data alone, where detection  
 365 probability,  $p$ , is not separated from abundance  $N$  and where the latter therefore has a ‘rel-  
 366 ative abundance’ interpretation only (Supporting Information Figure S1c). Low population  
 367 sizes for the odd year populations increase as a consequence of increased productivity values  
 368 shown in Figure 1.

### 369 3.3. Model fit

370 The best-fitting model had a scaled residual deviance of 1.52, suggesting moderate  
 371 overdispersion relative to the Poisson assumption. We investigated this further by fitting the  
 372 best model using one-step of the iterated methods necessary for concentrated likelihood for  
 373 Zero-inflated Poisson (ZIP) and negative-binomial models (Dennis et al., 2016a). This was  
 374 done as a check, as full fitting of these models is computer intensive. Examples considered

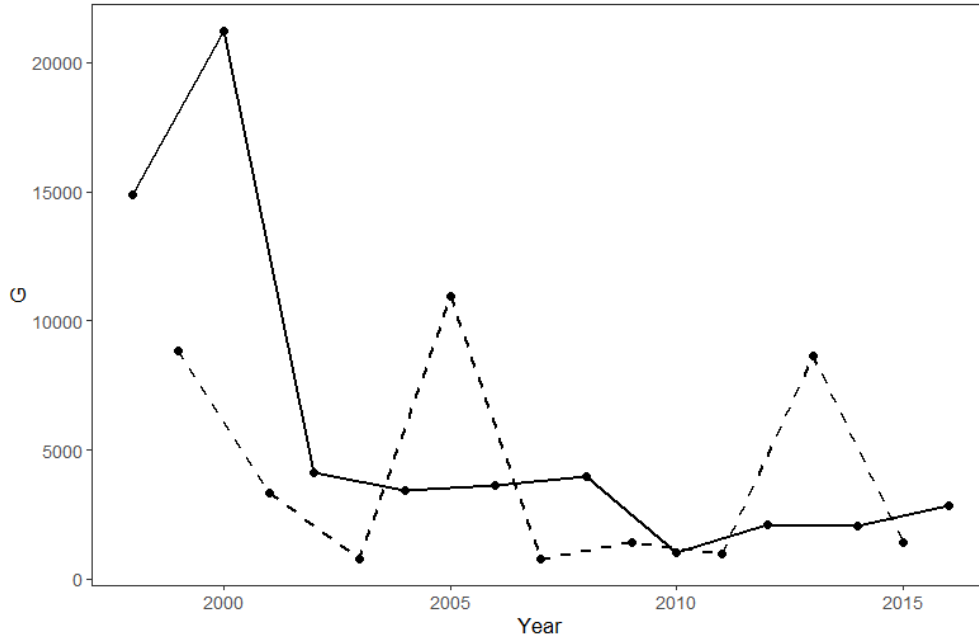


Figure 3: Estimated population size  $G$  (the total number of beetles ever alive across all sites) each year from fitting the best-fitting integrated model with year-varying  $\mu$ . We distinguish between those individuals that are imagos in the first year of the study (even years, solid line) and those that become imagos one year later (odd years, dashed line). Estimated confidence bands are not given, but could be achieved with a computationally expensive bootstrap.

375 in Dennis et al. (2016a) suggested only a small amount of iteration was typically necessary.  
 376 Here the ZIP model decreased the AIC and resulted in a reduced scaled deviance of 1.42,  
 377 whereas the NB model appeared to overfit the data. Comparisons of parameter estimates  
 378 between fitting the Poisson and ZIP models (Figure S5 of the Supporting Information) show  
 379 that the two models yield point estimates that are identical for all practical purposes and  
 380 that only the imprecision is larger under the ZIP-version of the AIC-best model. Similar re-  
 381 sults were obtained for the negative binomial, but with larger standard errors. We conclude  
 382 that the Poisson fit is acceptable, and that changing the distribution does not change our  
 383 conclusions. Quasi-likelihood arguments could be used to increase the standard errors by  
 384 multiplying by the square root of the Poisson scaled deviance (Dennis, 2015), however the  
 385 change is minimal in this case, with standard errors increased by 23%.

## 386 4. Discussion

### 387 4.1. *Modelling population dynamics at two temporal scales*

388 We believe that (temporally) multi-scale population dynamics are common. For example,  
389 many species of insects have generation times that exceed one year, e.g., some dragonflies,  
390 many large beetles and famously cicadas, for all of which the larval stage lasts for more than  
391 one year, while the imagos have life spans of the order of days to weeks. However, the only  
392 relevant models are the open-robust-design (ORD) model of Kendall and Bjorkland (2001),  
393 those of DMFRB, and a further variation on the model of DMFRB which describes data on  
394 bumblebees (Matechou et al., 2018). The ORD model is designed for a classical capture-  
395 recapture study with individually marked animals, where there are primary and secondary  
396 capture occasions, but where closure cannot be assumed among the secondary occasions  
397 within the same primary occasion. Instead, in the ORD model population gains and losses  
398 are modelled both among secondary as well as among primary occasions.

399 In contrast, the models developed by DMFRB can be fitted to simple counts of unmarked  
400 individuals, but they require spatial replication, i.e., multivariate time-series of counts from  
401 replicated sites/populations. While the between-season component of these models is usually  
402 rather simple (e.g., an exponential population model), several formulations are possible for  
403 the within-season dynamics, e.g., purely phenomenological approaches such as a GAM or a  
404 Gaussian curve, or more mechanistic birth/death processes such as the MZ model.

405 Demographic models for insects that contain explicit parameters for the underlying birth/  
406 death processes are very rare, presumably because of the difficulty with which insects can  
407 be studied by capture-recapture. The ability of the MZ-type of models, including those by  
408 DMFRB and the one in this study, to estimate such demographic parameters from simple  
409 counts of unmarked individuals, is a great advantage and should enhance the demographic  
410 modelling of many insect species which can be counted. Moreover, it may be beneficial to  
411 consider whether further information about some of the model parameters can be obtained,  
412 such as by conducting additional, but spatially and temporally restricted, capture-recapture  
413 studies. Such an integrated population model for an insect species has been formulated by

414 Gross et al. (2007), who augment the MZ model with information from a capture-recapture  
415 study. However they do not link the abundance parameters across years by a population  
416 model as we do.

#### 417 *4.2. Biology of I. fuliginator*

418 While we made the assumptions of constancy for both the spread of emergence times ( $\sigma$ )  
419 and apparent survival ( $\phi$ ), we found strong evidence for annual variation of productivity ( $\rho$ )  
420 and mean emergence date ( $\mu$ ), as well as, consequently, total annual population size ( $G$ ).

421 There was considerable annual variation in productivity, and 2003 and 2011 stood out  
422 in particular, as well as 2007 to a lesser degree. These were also the years with the overall  
423 smallest estimated total population sizes. Thus, there seemed to be a stabilizing tendency  
424 in the population dynamics, in that increases were most marked when population sizes were  
425 lowest. This may reflect density-dependence.

426 In the Basel population, the day of first emergence was related to the mean daily tem-  
427 perature for February and March in the years 1985–2000 (Baur et al., 2002). In this study,  
428 there was also annual variation in the estimates of mean emergence date, which spanned  
429 more than two months and seemed to show two phases: with no trend but great year-to-year  
430 fluctuations up until 2006, followed by a much smoother trajectory with an increasing trend  
431 thereafter, where mean emergence date became about one month later in the last decade.  
432 Winter temperatures appear to have increased over this period in the study area (unpub-  
433 lished data) and this delay in appearance may appear counter-intuitive. However, it ties in  
434 with what is known about the physiology of insects with an obligate diapause, and which  
435 typically need a certain amount of cold temperatures to break diapause (W. Blanckenhorn,  
436 pers. comm.). For instance, Stålhandske et al. (2017) found that milder winters lead to  
437 significant delays in the emergence of three out of five species studied and wrote: “the delay-  
438 ing effect of winter warmth has become more pronounced in the last decade, during which  
439 time winter durations have become shorter.” Thus climate change may have counter-intuitive  
440 effects on phenology.

441 Our models confirmed a serious decline of the beetle total annual abundance over the 19

442 years of study. A simple linear regression of the total annual abundance (in Figure 3) on  
443 year suggested a decline by about 98% (from approximately 9900 individuals to only about  
444 250) which is comparable with findings in Baur et al. (2020), who suggest that habitat  
445 deterioration may be responsible for the decline of this specialised species. Although the  
446 time-series of counts are statistically-speaking short, there appears to be a difference between  
447 the two annual cohorts, with a potentially stronger decline and more even trajectory for the  
448 even-year cohorts whereas, in contrast, the odd-year cohorts hardly appear to exhibit a  
449 long-term trend, but show more pronounced annual fluctuations. The biological reasons  
450 underlying this pattern are unknown, and in particular the reasons for the changes in 2005  
451 and 2013, for example whether these may be linked to particular temperature changes.

452 The covariate modelling identified heat load and year as important effects for productiv-  
453 ity, with much less evidence for degree-days, although this may have been influenced by the  
454 apparent correlation between degree-days and year. As expected, the effect of heat load was  
455 positive. For detection probability, there was a clear positive effect of survey duration, also  
456 as expected. There was limited evidence for alternative covariates given the differences in  
457 AIC for alternative models. Further work could consider the effects of suitable covariates on  
458 other stages of the life cycle of *I. fuliginator* (Suppo et al., 2020).

459 Under simple assumptions of constancy, longevity of imagines of *I. fuliginator* can be  
460 estimated from apparent survival ( $\phi$ ) as  $1/(1 - \phi)$ . Under model (d) in Table 1, this yields  
461 only 8.2 days (SE = 0.6). This species of beetle is a striking example of an insect life-cycle  
462 with an extremely short adult stage compared to the earlier life-stages.

463 Detection probability was very low and estimated at about 0.05 per survey occasion (on  
464 average across the survey durations). This could be an underestimate if the population is not  
465 closed during the count surveys and the counts really refer to some kind of superpopulation.  
466 However, we believe this to be quite unlikely given the limited dispersal distances of the  
467 beetle (Baur et al., 2005), the duration of the sampling periods, the size and configuration of  
468 the habitat patches and also the short longevity of the beetles. Such low values emphasize  
469 the need for estimating detection probability for such insects when true population sizes are

470 needed, for instance, in a population viability analysis (Beissinger and Westphal, 1998).

471 In the Basel population, a flagship for local biodiversity conservation, the last 52 visits  
472 did not detect a single beetle. Even under the unlikely assumption that the population  
473 always consisted of exactly one surviving beetle, the aggregated probability to detect that  
474 beetle at least once (and therefore to ascertain population survival) can be estimated as  
475  $1 - (1 - p)^{52} = 0.93$ . This probability increases to 0.97 if there are always exactly two  
476 independent beetles and to  $> 0.99$  for three or more. Hence, despite the low detection  
477 probability, not observing any beetles during all these surveys strongly suggests there are  
478 none left (McArdle, 1990; Kéry, 2002) and that the Basel population is now sadly extinct.

#### 479 4.3. Avenues for future research

480 Despite the concentrated likelihood and the multivariate normal approximation to the  
481 joint likelihood of the IPM, fitting these models is computer-intensive. We therefore made  
482 some constancy assumptions, including for the spread of the date of emergence ( $\sigma$ ) and ap-  
483 parent survival ( $\phi$ ). Calabrese (2012) shows that inferences under MZ-types of models can be  
484 strongly dependent on the parametric assumptions made about entry and exit probabilities,  
485 especially about the constancy of survival. For instance, Matechou et al. (2014) discovered  
486 that a model with linear and quadratic time effects on survival was best supported by AIC,  
487 and such a structure on  $\phi$  might also be investigated here.

488 We assumed a strict biennial life-cycle of *I. fuliginator* in our study area, which is in  
489 accordance with all published information and also with conventional wisdom among ento-  
490 mologists. Interestingly, recent genetic analyses revealed the absence of any differentiation  
491 between the cohorts from odd and even years (B. Baur, unpubl. data), which might seem  
492 to cast doubt on this important assumption, since it may suggest that individuals achieve  
493 eclosion within one, two or three years. However, findings in population genetics indicate  
494 that one reproducing migrant per generation is enough to prevent genetic differentiation  
495 between populations (Mills and Allendorf, 1996). Hence, it is quite probable that the vast  
496 majority of the beetles do adhere to a biennial life-cycle, thus making our model adequate.  
497 Nevertheless, it would be interesting to extend the modelling of this paper to allow for vari-



498 ation in duration of lifetime and larval polymorphism, which could have relevance for other  
499 species and taxa exhibiting this trait. The possibility of hot and dry conditions affecting the  
500 time to maturity could also be considered further.

501 Further research would be valuable considering the interest and attractions in adding  
502 random effects to account for spatial and temporal correlations, as well as to fit multi-species  
503 versions of the models. Multi-scale spatial models are another avenue for further research,  
504 to describe population dynamics within and between sites (Raffa et al., 2008; Wildemeersch  
505 et al., 2019).

## 506 **5. Conclusions**

507 We believe that population dynamics with more than a single temporal scale is much more  
508 common than previously recognized. Therefore, we consider the chief conceptual interest of  
509 the modelling in this paper, and that in DMFRB, to be the focus on multiple temporal scales  
510 of population dynamics. For cases such as insects or migrating animals it is immediately  
511 obvious that a model is needed which describes population dynamics at two temporal scales.  
512 In butterflies and seasonally migrating animals, the between-season dynamics will typically  
513 be that of a first-order Markov process with respect to time, while in some species with  
514 generation time longer than one year such as some beetles, dragonflies and cicadas, a longer-  
515 range dependency is needed.

516 However, the importance of the kind of model presented here on multi-scale population  
517 dynamics models may transcend the simple examples of insects and migrating animals.  
518 Indeed, it may represent a very general modelling framework that enables one to relax the  
519 typical closure assumption in much of traditional population dynamics modelling and may  
520 be applied to both the dynamics of reproducing populations or that of migratory animals  
521 at staging areas or other points along their journey. Hence, for instance, for breeding birds,  
522 rather than assuming a closed and constant population within what we call a breeding season,  
523 we would model the within-season dynamics of territory establishment and abandonment by  
524 territory holders in a very flexible and general way, or similarly for pond-breeding amphibians  
525 or beach-nesting sea-turtles. Finally, we could envisage beneficial combinations between the

526 models in this paper and DMFRB and the ORD models of Kendall and Bjorkland (2001).  
527 Such potential hybrid models would again fall under the rubric of integrated population  
528 models and provide powerful tools for improved inferences in population dynamics.

## 529 **6. Acknowledgements**

530 Wolf Blanckenhorn made valuable comments on insect physiology. We thank two anony-  
531 mous reviewers for their comments and Takis Besbeas for using hidden Markov models to  
532 check the deterministic approximation of the dynamic models. We thank all colleagues  
533 who have contributed to the beetle surveys over the years and Samuel Zschokke for com-  
534 piling the soil temperature data. Beetle monitoring has received financial support from the  
535 Stadtgärtnerei Basel. Financial support of this study was provided by a grant from the Swiss  
536 National Science Foundation (No 31003A.1464125 to M. Kéry and M. Schaub). BJTM was  
537 supported by a Leverhulme Emeritus fellowship.

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