Three Optimisations for Sharing

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Abstract
In order to improve precision and efficiency sharing analysis should track both freeness and linearity. The abstract unification algorithms for these combined domains are suboptimal, hence there is scope for improving precision. This paper proposes three optimisations for tracing sharing in combination with freeness and linearity. A novel connection between equations and sharing abstractions is used to establish correctness of these optimisations even in the presence of rational trees. A method for pruning intermediate sharing abstractions to improve efficiency is also proposed. The optimisations are lightweight and therefore some, if not all, of these optimisations will be of interest to the implementor.

Keywords: Abstract interpretation, sharing analysis, freeness, linearity and rational trees.

1 Introduction
A set-sharing analyser will usually also track freeness and linearity. This is because freeness and linearity are cheap to maintain and result in more accurate, that is smaller, sharing abstractions which in turn improve the efficiency of the sharing component of abstract unification. However, current abstract unification algorithms for sharing, freeness and linearity are suboptimal. This paper considers how to improve the precision of sharing with freeness and linearity by considering the interaction of these components. These refinements do not incur a significant computational overhead. To this end three optimisations are given, along with examples of where precision is gained. Their cost is discussed and correctness proved.

The first optimisation follows from the observation that the algorithms for pair-sharing with linearity can sometimes outperform set-sharing with linearity (in terms of which pairs of variables may share). This is because of an independence check which pervades the set-sharing literature (from early work (Langen, 1991) to the most recent and comprehensive (Bagnara et al., 2000)). This check is in fact redundant. By removing this, the precision of abstract unification is improved, since linearity can be exploited more frequently.

Filé (Filé, 1994) observed that freeness can be used to decompose a sharing
abstraction into a set of sharing abstractions. For each component of the decomposition, the sharing groups of that component do not (definitely) arise from different computational paths. Abstract unification can then be applied to each component and the resulting abstractions merged. This tactic has not been included in analysers owing to its prohibitive cost. The second optimisation is a lightweight refinement of abstract unification inspired by the decomposition. Though not as precise as the full decomposition, it does achieve the necessary balance between cost and benefit.

Thirdly, an optimisation for pruning sharing groups is presented. This tactic demonstrates that sharing in combination with freeness can improve groundness which, in turn, can improve sharing (even in the presence of rational trees). Put another way, it means that any optimal algorithm for sharing, freeness and linearity will have to consider subtle interactions between sharing, freeness and groundness.

One principle of set-sharing is that the number of sharing groups should be minimised. As well as increasing precision, this can improve efficiency and possibly avoid widening. A fourth technique is proposed which can prune the size of inputs to the abstract unification algorithm by considering the grounding behaviour of sets of equations. Reducing the size of the inputs (and intermediate abstractions) simplifies abstract unification and can thereby improve performance. Whilst the technique will not theoretically improve the precision of the overall result, in practice, a precision gain might be achieved if widening is avoided within the unification algorithm.

Correctness is expressed in terms of a novel concretisation map which characterises equations as their idempotent most general unifiers. This simplifies the correctness arguments and in particular enables the abstract unification algorithms to be proved correct for rational tree constraint solving (as adopted by SICStus Prolog and Prolog-III). To the best of the authors’ knowledge, this is the first proof of correctness for a sharing, freeness and linearity analysis in the presence of rational trees. (Previous work for rational tree unification has either focused on pair-sharing (King, 2000) or set-sharing without freeness and linearity (Hill et al., 2002)).

In summary, this paper provides the implementor with a number of low-cost techniques for improving the precision and efficiency of sharing analyses.

2 Preliminaries

2.1 Trees and terms

Let ε denote the empty sequence, . denote sequence concatenation, and |α| denote the length of a sequence α ∈ N*. A tree (or term) over an alphabet of symbols F is a partial map t : N* → F such that t(ε) = t if α = ε, otherwise t(α) = t(β) where α = αβ and t = f(t_1, ..., t_n). Let T(F) and T∞(F) denote the set of finite and possibly infinite trees over F. Let U denote a (denumerable) universe of variables such that F ∩ U = ∅, and let var(t) = {u ∈ U | ∃α ∈ N*.t(α) = u} where t ∈ T∞(F ∪ U). Finally, |S| denotes the cardinality of the set S.
2.2 Substitutions and equations

A substitution is a (total) map \( \theta : U \rightarrow T^\infty(F \cup U) \) such that \( \text{dom}(\theta) = \{u \in U \mid \theta(u) \neq u\} \) is finite. A substitution \( \theta \) can be represented as a finite set \( \{x \mapsto \theta(x) \mid x \in \text{dom}(\theta)\} \). Let \( \text{rng}(\theta) = \cup\{\text{var}(\theta(u)) \mid u \in \text{dom}(\theta)\} \) and let \( \text{Sub} \) denote the set of substitutions. If \( \theta = \{x_i \mapsto t_i\}_{i=1}^n \) then \( \theta(t) \) denotes the tree obtained by simultaneously replacing each occurrence of \( x_i \) in \( t \) with \( t_i \). For brevity, let \( \theta(x, \alpha) = t(\alpha) \) where \( \theta(x) = t \). An equation \( e \) is a pair \( (s, t) \in T^\infty(F \cup U) \). A finite set of equations is denoted \( E \) and \( \text{Eqn} \) denotes the set of finite sets of equations. Also define \( \theta(E) = \{\theta(s) = \theta(t) \mid (s = t) \in E\} \). The map \( \text{eqn} : \text{Sub} \rightarrow \text{Eqn} \) is defined \( \text{eqn}(\theta) = \{x = t \mid (x \mapsto t) \in \theta\} \). Where \( Y \subseteq U \), projection out and projection onto are respectively defined \( \exists Y \theta = \{x \mapsto t \in \theta \mid x \notin Y\} \) and \( \forall Y \theta = \exists(U \setminus Y)\theta \). Composition \( \theta \circ \psi \) of two substitutions is defined so that \( (\theta \circ \psi)(u) = \theta(\psi(u)) \) for all \( u \in U \). Composition induces the (more general than) relation \( \leq \) defined by \( \theta \leq \psi \) iff there exists \( \delta \in \text{Sub} \) such that \( \psi = \delta \circ \theta \). A renaming is a substitution \( \rho \in \text{Sub} \) that has an inverse, that is, there exists \( \rho^{-1} \in \text{Sub} \) such that \( \rho^{-1} \circ \rho = \text{id} \). The set of renamings is denoted \( \text{Rename} \). A substitution \( \theta \) is idempotent iff \( \theta \circ \theta = \theta \), or equivalently, iff \( \text{dom}(\theta) \cap \text{rng}(\theta) = \emptyset \).

2.3 Solved forms and most general unifiers

A substitution is in rational solved form if it has no subset \( \{x_1 \mapsto x_2, \ldots, x_n \mapsto x_1\} \) where \( n \geq 2 \). The subset of \( \text{Sub} \) in rational solved form is denoted \( \text{RSub} \). The set of unifiers of \( E \) is defined by: \( \text{unify}(E) = \{\theta \in \text{Sub} \mid \forall (s = t) \in E, \theta(s) = \theta(t)\} \). The set of most general unifiers (mgu's) and the set of idempotent mgu's (imgu's) are defined: \( \text{mgu}(E) = \{\theta \in \text{unify}(E) \mid \forall \psi \in \text{unify}(E), \theta \leq \psi\} \) and \( \text{imgu}(E) = \{\theta \in \text{mgu}(E) \mid \text{dom}(\theta) \cap \text{rng}(\theta) = \emptyset\} \). Note that \( \text{imgu}(E) \neq \emptyset \) iff \( \text{mgu}(E) \neq \emptyset \) (Lassz et al., 1988). An mgu can be renamed to obtain any other (as can an imgu).

Lemma 2.1 (Proposition 11 from Lassz et al., 1988)

Let \( \theta \in \text{imgu}(E) \). Then \( \phi \in \text{imgu}(E) \) iff there exists \( \{x_i \mapsto y_i\}_{i=1}^n \subseteq \theta \) such that \( \phi = \{x_i \mapsto y_i, y_i \mapsto x_j\}_{j=1}^m \circ \theta \).

One way to obtain an imgu is by considering limits of substitutions.

Definition 2.1

Let \( \{t_n \mid n \in \mathbb{N}\} \subseteq T^\infty(F \cup U) \). Then \( t = \lim_{n \rightarrow \infty} t_n \) iff for all \( k \in \mathbb{N} \) there exists \( l \in \mathbb{N} \) such that for all \( m \geq l \) and \( ||\alpha|| \leq k \), \( t(\alpha) = t_m(\alpha) \). Furthermore, if \( \{\theta_n \mid n \in \mathbb{N}\} \subseteq \text{Sub} \) then \( \lim_{n \rightarrow \infty} \theta_n = \lambda x.\lim_{n \rightarrow \infty} \theta_n(x) \).

Note that \( \lim_{n \rightarrow \infty} \theta^n \) exists iff \( \theta \in \text{RSub} \) (King, 2000). Henceforth \( \theta^n \) abbreviates \( \lim_{n \rightarrow \infty} \theta^n \). If \( \theta \in \text{RSub} \) then \( \theta^n \) is idempotent whereas if \( \theta \) is idempotent then \( \theta^n = \theta \). The following lemmas detail how limits of substitutions and composition of substitutions relate to an mgu.

Lemma 2.2 (Lemmas 2.2, 4.3 and 4.4 from King, 2000)

1. \( \theta^n \in \text{mgu}(<\text{eqn}(\theta)) \) iff \( \theta \in \text{RSub} \).
2. \( \delta \circ \theta^n \in \text{mgu}(E \cup \text{eqn}(\theta)) \) iff \( \delta \in \text{mgu}(\theta^n(E)) \).
3. \( \exists \text{dom}(\theta) \setminus \text{rng}(\theta)) \delta \in \text{mgu}(\theta(E)) \) iff \( \delta \circ \theta \in \text{mgu}(E) \).
2.4 Linearity

Variable multiplicity is defined in order to formalise linearity. The significance of linearity is that unification of linear terms enables sharing to be described by more precise sharing abstractions (even in the presence of rational trees).

Definition 2.2

The variable multiplicity map $\chi : T^\infty(F \cup U) \rightarrow \{0,1,2\}$ is defined: $\chi(t) = \max(\{\chi(x,t) \mid x \in U\})$ where $\chi(x,t) = \min(2, |\{\alpha \mid t(\alpha) = x\}|)$.

If $\chi(t) = 0$, $t$ is ground; if $\chi(t) = 1$, $t$ is linear; and if $\chi(t) = 2$, $t$ is non-linear. The next lemma details the forms of sharing barred by the unification of linear terms.

Lemma 2.3 (Proposition 3.1 from (King, 2000))

If $\theta \in mgu(\{s = t\})$, $x \neq y$ and $\var(\theta(x)) \cap \var(\theta(y)) \neq \emptyset$ then either: $x \in \var(s)$ and $y \in \var(t)$; or $x,y \in \var(t)$ and $\chi(s) = 2$; or $x \in \var(t)$ and $y \in \var(s)$; or $x,y \in \var(s)$ and $\chi(t) = 2$.

The correctness arguments for abstract unification require lemma 2.3 to be augmented with a new result - lemma 2.4. The proof of this lemma is analogous to that of lemma 2.3 detailed in (King, 2000).

Lemma 2.4

If $\theta \in mgu(\{s = t\})$ and $\chi(\theta(x)) = 2$ then either: $x \in \var(s) \cap \var(t)$; or $x \in \var(t)$ and $\chi(s) = 2$; or $x \in \var(s)$ and $\chi(t) = 2$.

2.5 Groundness and sharing abstractions

The abstract domains of interest in this paper are represented either as Boolean functions, or as sets or as sets of sets. Let $X$ denote a finite subset of $U$. The set of propositional formulae over $X$ is denoted by $\text{Bool}_X$ and abbreviates the formula $\land \forall X$. The (bijective) map $\text{model}_X : \text{Bool}_X \rightarrow \var(\var(X))$ is defined by $\text{model}_X(f) = \{M \subseteq X \mid \psi_X(M) \models f\}$ where $\psi_X(M) = M \land \neg \{y \mid y \in X \setminus M\}$. The groundness, sharing, freeness and linearity domains over $X$ are defined as follows:

Definition 2.3

$\text{Pos}_X = \{f \in \text{Bool}_X \mid X \models f\}$, $\text{Sh}_X = \{S \subseteq \var(X) \mid \emptyset \in S\}$, $\text{Fr}_X = \var(X)$ and $\text{Lin}_X = \var(X)$.

If $S \in \text{Sh}_X$, then each $G \in S$ is referred to as a sharing group.

These domains are connected to the concrete domain of sets of equations by Galois connections induced by the concretisation maps. This approach leads to succinct statements of correctness. To obtain well defined concretisations, maps abstracting substitutions are introduced. It is then observed that the abstractions for equivalent idempotent substitutions are the same.

Definition 2.4

The abstraction maps $\alpha^{\text{Pos}} : \text{Sub} \rightarrow \text{Pos}_U$ and $\alpha^{\text{Sh}}_X : \text{Sub} \rightarrow \text{Sh}_X$ are defined: $\alpha^{\text{Pos}}(\theta) = \land \{x \leftrightarrow \var(t) \mid x \leftrightarrow t \in \theta\}$, $\alpha^{\text{Sh}}_X(\theta) = \{\text{occ}(\theta,u) \cap X \mid u \in U\}$ and $\text{occ}(\theta,y) = \{u \in U \mid y \in \var(\theta(u))\}$.
Lemma 2.5
Let $\theta, \phi \in \text{imgu}(E)$. Then $\alpha^{\text{Pos}}(\theta) = \alpha^{\text{Pos}}(\phi)$, $\alpha^{\text{Sh}}_X(\theta) = \alpha^{\text{Sh}}_X(\phi)$, $\theta(x) \in U$ iff $\phi(x) \in U$ and $\chi(\theta(x)) \leq 1$ iff $\chi(\phi(x)) \leq 1$.

Proof
By lemma 2.1 there exists $\{x_i \mapsto y_i\}_{i=1}^n \subseteq \theta$ such that $\phi = \rho \circ \theta$ where $\rho = \{x_i \mapsto y_i, y_i \mapsto x_i\}_{i=1}^n$.

1. Let $x \mapsto t \in \theta$. Observe that $\{x \mapsto \rho(t), y_1 \mapsto x_1, \ldots, y_n \mapsto x_n\} \subseteq \rho \circ \theta$ and $y_i \in \text{var}(t)$ iff $x_i \in \text{var}(\rho(t))$, thus $\alpha^{\text{Pos}}(\phi) \models x \leftrightarrow \text{var}(\rho(t)) \wedge (\wedge_{i=1}^n y_i \leftrightarrow x_i) \models x \leftrightarrow \text{var}(t)$. Hence $\alpha^{\text{Pos}}(\phi) \models \alpha^{\text{Pos}}(\theta)$. The other direction is similar.

2. Observe that $\text{occ}(\rho \circ \theta, y_i) = \text{occ}(\theta, x_i)$, $\text{occ}(\rho \circ \theta, x_i) = \text{occ}(\theta, y_i)$ and $\text{occ}(\rho \circ \theta, u) = \text{occ}(\theta, u)$ for all $u \not\in \text{dom}(\rho) \cup \text{rng}(\rho)$. Hence $\alpha^{\text{Sh}}_X(\theta) = \alpha^{\text{Sh}}_X(\phi)$.

3. and 4. Immediate.

\[ \square \]

Instead of defining concretisation in terms of a particular imgu (the limit of a rational solved form (King, 2000)), an arbitrary imgu is used. This new approach simplifies correctness proofs.

Definition 2.5
The concretisation maps $\gamma^{\text{Pos}}_X : \text{Pos}_X \rightarrow \varphi(Eqn)$, $\gamma^{\text{Sh}}_X : \text{Sh}_X \rightarrow \varphi(Eqn)$, $\gamma^{\text{Fr}}_X : \text{Fr}_X \rightarrow \varphi(Eqn)$ and $\gamma^{\text{Lin}}_X : \text{Lin}_X \rightarrow \varphi(Eqn)$ are respectively defined by:

\[
\begin{align*}
\gamma^{\text{Pos}}_X(f) &= \{ E \in \text{Eqn} \mid \exists \theta \in \text{imgu}(E) \alpha^{\text{Pos}}(\theta) \models f \} \\
\gamma^{\text{Sh}}_X(S) &= \{ E \in \text{Eqn} \mid \exists \theta \in \text{imgu}(E) \alpha^{\text{Sh}}_X(\theta) \models S \} \\
\gamma^{\text{Fr}}_X(F) &= \{ E \in \text{Eqn} \mid \exists \theta \in \text{imgu}(E) \forall x \in F, \theta(x) \in U \} \\
\gamma^{\text{Lin}}_X(L) &= \{ E \in \text{Eqn} \mid \exists \theta \in \text{imgu}(E) \forall x \in L, \theta(x) \in 1 \}
\end{align*}
\]

Each free variable is linear so that $\gamma^{\text{Fr}}_X(F) \cap \gamma^{\text{Lin}}_X(L) = \gamma^{\text{Fr}}_X(F) \cap \gamma^{\text{Lin}}_X(L \cup F)$. This paper is concerned with combined domains and the following combined concretisation maps will be useful: $\gamma^{\text{Sh}}_X(s, F) = \gamma^{\text{Sh}}_X(S) \cap \gamma^{\text{Fr}}_X(F)$ and $\gamma^{\text{ShF}}_X(s, F, L) = \gamma^{\text{Sh}}_X(s, F) \cap \gamma^{\text{Lin}}_X(L)$.

A connection is established in (Codish et al., 1999) which sheds light on the relationship between sharing and Boolean functions. The corollary (also observed in the long version of (Bagnara et al., 2000)) explains how this can be used to improve precision of combined domains.

Lemma 2.6 (Observation 4.1 and lemma 5.1 from (Codish et al., 1999))

\[ \{ X \setminus G \mid G \in \alpha^{\text{Sh}}_X(\theta) \} \subseteq \text{model}_X(\alpha^{\text{Pos}}(\theta)) \text{ where } \theta \text{ is idempotent.} \]

Corollary 2.1

\[ \gamma^{\text{Pos}}_X(f) \cap \gamma^{\text{Sh}}_X(S) = \gamma^{\text{Pos}}_X(f) \cap \gamma^{\text{Sh}}_X(\text{trim}_X(f, S)) \text{ where } \text{trim}_X(f, S) = \{ G \in S \mid X \setminus G \in \text{model}_X(f) \}. \]

Finally, the following auxiliary operations will be used throughout the paper. Let $S, S_1 \in \text{Sh}_X$. The relevance map is defined $\text{red}(t, S) = \{ G \in S \mid \text{var}(t) \cap G \neq \emptyset \}$; closure is defined $S^* = \bigcap \{ S' \mid S \subseteq S' \wedge \forall G_1, G_2 \in S', G_1 \cup G_2 \in S' \}$; and pairwise union is defined $S_1 \sqcup S_2 = \{ G_1 \cup G_2 \mid G_1 \in S_1 \wedge G_2 \in S_2 \}$. Observe that if
\( \text{var}(\text{rel}(s, S)) \cap \text{var}(\text{rel}(t, S)) = \emptyset \) then \( \text{var}(\theta(s)) \cap \text{var}(\theta(t)) = \emptyset \) for all \( \theta \in \text{mgu}(E) \)
and \( E \in \gamma_{X}^{SH}(S) \). Thus the independence check \( \text{var}(\text{rel}(s, S)) \cap \text{var}(\text{rel}(t, S)) = \emptyset \)
can verify that two terms \( s \) and \( t \) do not share under \( \theta \) (or equivalently \( E \)).

3 Independence check in set-sharing

The following example demonstrates that pair-sharing can sometimes detect independence when standard set-sharing unification algorithms cannot.

**Example 3.1**

Let \( X = \{u, v, w, x, y, z\} \) and consider \( E \in \gamma_{X}^{SF}((S, F, L)) \) where \( S = \{\emptyset, \{u, w\}, \{v, w\}, \{x, y\}, \{x, z\}, \{w, x\}\} \), \( F = \emptyset \) and \( L = X \). Let \( \theta' \in \text{mgu}(E) \cup \{w = x\} \). The set-sharing unification algorithms of (Langen, 1991; Degano et al., 1997) give the following abstraction \( S' = \emptyset \cup (\text{S}_{w}^{\emptyset}) \cup (\text{S}_{x}^{\emptyset}) \) for \( \theta' \) where \( \text{S}_{w} = \{\{u, w\}, \{v, w\}, \{w, x\}\} \) and \( \text{S}_{x} = \{\{x, y\}, \{x, z\}, \{w, x\}\} \). Observe that \( \{u, v, w\} \in \text{S}_{w}^{r} \) and \( \{x, y, z\} \in \text{S}_{x}^{r} \) and therefore \( S' \) does not assert the independence of \( u \) and \( v \) (similarly \( y \) and \( z \)). However, if \( S \) is interpreted as a set of pairs, then the pair-sharing abstract unification algorithms of (Codish et al., 1993; King, 2000) both give the abstraction \( S \cup \{\{w\}, \{x\}, \{u, x\}, \{u, y\}, \{u, z\}, \{v, x\}, \{v, y\}, \{v, z\}, \{w, y\}, \{w, z\}\} \) which states the independence of \( u \) and \( v \) (similarly \( y \) and \( z \)). Note that this different does not stem from a difference in the set-sharing and pair-sharing domains, but derives from the way in which linearity is exploited in the abstract unification algorithms.

The crucial difference between pair-sharing and set-sharing algorithms is that the former does not require the terms in the equation to be independent to exploit linearity. Put another way, to apply linearity the latter requires that \( \text{var}(\text{rel}(s, S)) \cap \text{var}(\text{rel}(t, S)) = \emptyset \) when solving the equation \( s = t \) in the context of the sharing abstraction \( S \). Lemmas 2.3 and 2.4 detail the forms of sharing that can arise in \( \text{mgu}(\{s' = t'\}) \) rational (and finite) tree unification where \( s' \) and \( t' \) are arbitrary terms. Observe that \( s' \) and \( t' \) are not required to be independent. Abstract unification algorithms with the independence check are safe. However, this check is not fundamental to combining sharing with linearity. By observing how to exploit linearity more fully, a more precise abstract unification algorithm can be obtained. This algorithm also explains why algorithms with the independence check are safe.

The following abstract operator is used to approximate the multiplicity map in abstract unification. Lemma 3.1 asserts its correctness.

**Definition 3.1**

\[
\chi(t, S, L) = \begin{cases} 
2 & \text{if } \exists x \in \text{var}(S) x \in \text{var}(t) \setminus L \\
2 & \text{if } \exists x \in \text{var}(S) x \notin \text{var}(t) \setminus L \\
1 & \text{otherwise} 
\end{cases}
\]

**Lemma 3.1**

If \( E \in \gamma_{X}^{SH}(S) \cap \gamma_{X}^{Lin}(L) \) and \( \theta \in \text{mgu}(E) \) then \( \chi(\theta(t)) \leq \chi(t, S, L) \).
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Proof
Suppose \( \chi(\theta(t)) = 2 \). One of the following holds:

- There exists \( x \in \text{var}(t) \) such that \( \chi(x, t) = 2 \) and \( \text{var}(\theta(x)) \neq \emptyset \). Then \( x \in \text{var}(S) \) so that \( \chi(t, S, L) = 2 \).
- There exists \( x \in \text{var}(t) \) such that \( \chi(\theta(x)) = 2 \). Then \( x \in \text{var}(S) \) and \( x \in \text{var}(t) \setminus L \) so that \( \chi(t, S, L) = 2 \).
- There exist \( x, y \in \text{var}(t) \) such that \( x \neq y \) and \( \text{var}(\theta(x)) \cap \text{var}(\theta(y)) \neq \emptyset \). Then there exists \( G \in S \) such that \( x, y \in G \) so that \( \chi(t, S, L) = 2 \).

\( \square \)

The revised abstract unification algorithm (with the independence check removed) is detailed in definition 3.2, and theorem 3.1 establishes its correctness.

Definition 3.2 (Abstract unification 1)
Abstract unification \( \text{amgu}_1((S, F, L), s, t) = (S', F', L') \) is defined:

\[
S_s = \text{rel}(s, S) \quad S_t = \text{rel}(t, S) \quad S' = (S \setminus (S_s \cup S_t)) \cup S'' \quad G' = X \setminus \text{var}(S')
\]

\[
S'' = \begin{cases} 
S_s \cup S_t & \text{if } s \in F \land t \in F \\
(S_s \uplus S_t) \cap (S_s \uplus S_t^*) & \text{if } \chi(s, S, L) = \chi(t, S, L) = 1 \\
S_s \uplus S_t^* & \text{if } \chi(s, S, L) = 1 \\
S_s \uplus S_t^* & \text{if } \chi(t, S, L) = 1 \\
S_s^* \uplus S_t & \text{otherwise}
\end{cases}
\]

\[
F' = \begin{cases} 
F & \text{if } s \in F \land t \in F \\
F \setminus \text{var}(S_s) & \text{if } s \in F \\
F \setminus \text{var}(S_t) & \text{if } t \in F \\
F \setminus \text{var}(S_s \cup S_t) & \text{otherwise}
\end{cases}
\]

\[
L' = F' \cup G' \cup \begin{cases} 
L \setminus (\text{var}(S_s) \cup \text{var}(S_t)) & \text{if } \chi(s, S, L) = 1 \land \chi(t, S, L) = 1 \\
L \setminus \text{var}(S_s) & \text{if } \chi(s, S, L) = 1 \\
L \setminus \text{var}(S_t) & \text{if } \chi(t, S, L) = 1 \\
L \setminus \text{var}(S_s \cup S_t) & \text{otherwise}
\end{cases}
\]

A precision gain over previous algorithms follows since a closure is avoided if \( s \) is linear but not \( t \) (or vice versa) and \( s \) and \( t \) are not independent. When both \( s \) and \( t \) are linear, but not independent, two closures are required (as previously), but the resulting sharing abstraction may contain fewer elements owing to the pruning effect of intersection. When the independence check is satisfied, that is \( S_s \cap S_t = \emptyset \), it follows that \( (S_s^* \uplus S_t) \cap (S_s \uplus S_t^*) = S_s \uplus S_t^* \). This explains why algorithms with the independence check are safe. Note that if \( s \) and \( t \) are both linear, but not independent, an implementor might trade precision for efficiency by computing \( S_s^* \uplus S_t \) if \( |S_s| \leq |S_t| \) and \( S_s \uplus S_t^* \) otherwise.

Theorem 3.1 (Correctness of abstract unification 1)
Let \( E \in \gamma_{SFL}(\langle S, F, L \rangle), \text{var}(s) \cup \text{var}(t) \subseteq X \) and \( \text{amgu}_1((S, F, L), s, t) = (S', F', L') \).
Then \( E \cup \{ s = t \} \in \gamma_{SFL}(\langle S', F', L' \rangle) \).
Proof
Put \( E' = \{ s = t \} \). Let \( \theta \in \text{img}u(E) \) and \( \theta' \in \text{img}u(E \cup E') \). Observe that 
\[
\text{unify}(\theta(E')) = \text{unify}(\theta'(E') \cup \text{eqn}(\theta)) = \text{unify}(\theta'(E) \cup \text{eqn}(\theta)) = \text{unify}(E \cup E') \neq 0.
\]

Thus let \( \delta \in \text{img}u(\theta'(E')) \). By part 2 of lemma 2.2, \( \delta \circ \theta^\infty \in \text{img}u(\text{eqn}(\theta) \cup E') = \text{img}u(E \cup E') \). Since \( \text{dom}(\theta) \cap \text{rng}(\delta) = \emptyset \), \( \delta \circ \theta^\infty = \delta \circ \theta \in \text{img}u(E \cup E') \).

1. To show \( \alpha_X^{\text{fp}}(\delta \circ \theta) \subseteq S' \), let \( y \in U \) and consider \( \text{occ}(\delta \circ \theta, y) \).

   (a) Suppose \( y \notin \text{rng}(\delta \circ \theta) \).

      i Suppose \( y \notin \text{dom}(\delta \circ \theta) \), that is, \( \delta \circ \theta(y) = y' \) and \( \delta(y') = y \). Suppose \( y \neq y' \). Then \( y \in \text{dom}(\theta) \), thus \( y \notin \text{rng}(\delta) \) which is a contradiction. Therefore \( y = y' \), giving \( \theta(y) = y \) and \( \delta(y) = y \).

      A Suppose \( y \notin \text{var}(\theta(s)) \) and \( y \notin \text{var}(\theta(t)) \). Hence \( y \notin \text{dom}(\delta) \) and \( y \notin \text{rng}(\delta) \), so that \( \text{occ}(\delta \circ \theta, y) \cap X = \text{occ}(\theta, y) \cap X \subseteq S \). But \( \text{var}(\delta) \cap \text{occ}(\theta, y) = \emptyset \) and similarly \( \text{var}(\theta, y) \cap \text{occ}(\theta, y) = \emptyset \), so that \( \text{occ}(\delta \circ \theta, y) \cap X \subseteq S' \).

      B Suppose \( y \notin \text{var}(\theta(s)) \) and \( y \notin \text{var}(\theta(t)) \). Since \( \delta(y) = y \), it follows that \( y \in \text{var}(\delta \circ \theta(s)) = \text{var}(\delta \circ \theta(t)) \). Suppose \( y \in \text{rng}(\delta) \), then \( y \notin \text{dom}(\theta) \), hence \( y \notin \text{rng}(\delta \circ \theta) \) which is a contradiction. Therefore \( y \notin \text{rng}(\delta) \), thus \( y \in \text{var}(\theta(t)) \) which is a contradiction.

   C Suppose \( y \notin \text{var}(\theta(s)) \) and \( y \in \text{var}(\theta(t)) \). Analogous to the previous case.

   D Suppose \( y \in \text{var}(\theta(s)) \) and \( y \in \text{var}(\theta(t)) \). Since \( \delta(y) = y \) and \( y \notin \text{rng}(\delta \circ \theta) \), \( y \in \text{rng}(\theta) \). Thus \( y \in \text{var}(\delta) \) and \( y \in \text{var}(\theta) \). Since \( y \notin \text{rng}(\delta) \), it follows that \( y \notin \text{dom}(\theta) \), therefore \( y \notin \text{rng}(\delta) \). Thus, \( \text{occ}(\delta \circ \theta, y) = \text{occ}(\theta, y) \). Therefore \( \text{occ}(\delta \circ \theta, y) \subseteq X \subseteq S \) since \( \text{var}(s) \subseteq X \) and \( \text{occ}(\delta \circ \theta, y) \cap X \subseteq S \) since \( \text{var}(t) \subseteq X \). Thus \( \text{occ}(\delta \circ \theta, y) \subseteq S' \).

   ii Suppose \( y \in \text{dom}(\delta \circ \theta) \). Since \( y \notin \text{rng}(\delta \circ \theta) \), \( \text{occ}(\delta \circ \theta, y) \cap X = \emptyset \subseteq S' \).

   (b) Suppose \( y \in \text{rng}(\delta \circ \theta) \setminus \text{var}(\theta(E')) \). Then \( y \notin \text{dom}(\delta) \) and \( y \notin \text{rng}(\delta) \) so that \( \text{occ}(\delta \circ \theta, y) = \text{occ}(\theta, y) \). Moreover, since \( y \notin \text{var}(\theta(E')) \) it follows that \( \text{occ}(\delta \circ \theta, y) \cap X \subseteq S \setminus (S_s \cup S_t) \subseteq S' \).

   (c) Suppose \( y \in \text{rng}(\delta \circ \theta) \setminus \text{var}(\theta(E')) \). Since \( \text{occ}(\delta, y) \subseteq \text{var}(\theta(s)) \setminus \text{var}(\theta(t)) \), \( \text{occ}(\delta \circ \theta, y) \cap X \subseteq \{ \text{occ}(\theta, u) \cap X \mid u \in \text{occ}(\delta, y) \} = \{ \text{occ}(\theta, v) \cap X \mid v \in \text{var}(\theta(s)) \cap \text{occ}(\delta, y) \} = \{ \text{occ}(\theta, w) \cap X \mid w \in \text{var}(\theta(t)) \cap \text{occ}(\delta, y) \} \). If \( R_s = \emptyset \), then \( y \notin \text{var}(\delta \circ \theta(s)) = \text{var}(\delta \circ \theta(t)) \), hence \( R_t = \emptyset \) and \( \text{occ}(\delta \circ \theta, y) \cap X = \emptyset \subseteq S' \). Likewise \( \text{occ}(\delta \circ \theta, y) \cap X = \emptyset \subseteq S' \) if \( R_t = \emptyset \). Thus suppose \( R_s \neq \emptyset \) and \( R_t \neq \emptyset \). Since \( \text{var}(s) \subseteq X \), \( R_s \subseteq S_s \) and \( \text{var}(t) \subseteq X \), \( R_t \subseteq S_t \).

   i Suppose \( s \in F \). Thus \( \theta(s) \in U \), hence \( |R_s| = |	ext{var}(\theta(s))| = 1 \). Moreover \( \chi(\theta(s)) \leq 1 \). Suppose \( |R_t \setminus R_s| > 1 \). Thus there exists \( u \neq v \) such that \( u, v \in \text{var}(\theta(t)) \setminus \text{var}(\theta(s)) \) and \( \text{var}(\delta(u)) \cap \text{var}(\delta(v)) \neq \emptyset \). This contradicts lemma 2.3, hence \( |R_t \setminus R_s| \leq 1 \). Thus \( \text{occ}(\delta \circ \theta, y) \cap X \subseteq S_s \cup S_t \).
iii Suppose \( \chi(s, S, L) = 1 \). Thus \( \chi(\theta(s)) \leq 1 \). As with case 1(c), it follows that \( |R_0 \setminus R'_0| \leq 1 \). Thus \( \operatorname{occ}(\delta \circ \theta, y) \cap X \in S'_0 \cup S_r \).

iv Suppose \( \chi(t, S, L) = 1 \). Analogous to the previous case.

v Otherwise \( \operatorname{occ}(\delta \circ \theta, y) \cap X \in S'_0 \cup S'_r \).

2. It is straightforward to show \( \delta \circ \theta(x) \in U \) for all \( x \in F' \).

3. To show \( \chi(\delta \circ \theta(x)) \leq 1 \) for all \( x \in L' \). Observe \( \chi(\delta \circ \theta(x)) = 0 \) if \( x \in C' \) and \( \chi(\delta \circ \theta(x)) = 1 \) if \( x \in F' \). Hence, let \( x \in L \subseteq X \) and suppose \( \chi(\delta \circ \theta(x)) = 2 \).

(a) Suppose \( \chi(s, S, L) = 1 \). By lemma 3.1, \( \chi(\theta(s)) \leq 1 \).

i Suppose there exist \( u, v \in \operatorname{var}(\theta(x)) \), \( u \neq v \) such that \( \operatorname{var}(\delta(u)) \cap \operatorname{var}(\delta(v)) \neq \emptyset \). By lemma 2.3 either:

A \( u \in \operatorname{var}(\theta(s)) \) and \( v \in \operatorname{var}(\theta(t)) \), hence \( x \in \operatorname{occ}(\theta, u) \cap X \in S_s \), and therefore \( x \notin L' \).

B \( u \in \operatorname{var}(\theta(t)) \) and \( v \in \operatorname{var}(\theta(s)) \), hence \( x \in \operatorname{occ}(\theta, v) \cap X \in S_s \), and therefore \( x \notin L' \).

C \( u, v \in \operatorname{var}(\theta(s)) \). Hence \( x \in \operatorname{occ}(\theta, u) \cap X \in S_s \), and thus \( x \notin L' \).

ii Suppose there exists \( u \in \operatorname{var}(\theta(x)) \) such that \( \chi(\delta(u)) = 2 \). By lemma 2.4, \( u \in \operatorname{var}(\theta(s)) \), thus \( x \in \operatorname{occ}(\theta, u) \cap X \in S_s \) and therefore \( x \notin L' \).

(b) Suppose \( \chi(t, S, L) = 1 \). Analogous to the previous case.

(c) Otherwise observe that either:

i There exist \( u, v \in \operatorname{var}(\theta(x)) \), \( u \neq v \) such that \( \operatorname{var}(\delta(u)) \cap \operatorname{var}(\delta(v)) = \emptyset \).

Thus \( u \in \operatorname{var}(\theta(E')) \) and \( x \in \operatorname{occ}(\theta, u) \cap X \in S_s \cup S_r \). Hence \( x \notin L' \).

ii There exists \( u \in \operatorname{var}(\theta(x)) \) such that \( \chi(\delta(u)) = 2 \). Thus \( u \in \operatorname{var}(\theta(E')) \) and \( x \in \operatorname{occ}(\theta, u) \cap X \in S_s \cup S_r \). Hence \( x \notin L' \).

□

Example 3.2
Consider again example 3.1. Observe that \( \text{amgu}_1((S, F, L), w, x) = \langle S', F', L' \rangle \) where \( S' = \{ \emptyset \} \cup (S'_w \cup S_r) \cap (S'_w \cup S'_r) = \{ \emptyset, \{ w, x \}, \{ w, x, y \}, \{ u, w, x, z \}, \{ v, w, x, y \}, \{ v, w, x, z \}, \{ w, x \}, \{ w, x, y \}, \{ w, x, z \} \} \), \( F' = \emptyset \) and \( L' = \emptyset \). This asserts the independence of \( u \) and \( v \) (similarly \( y \) and \( z \)), as required.

The following example, adapted from (Langen, 1991), illustrates that closure can be required to abstract the unification of linear terms.

Example 3.3
Let \( X = \{ w, x, y, z \} \) and observe \( E \in \gamma_X^{SFL}(S, F, L) \) where \( E = \{ w = f(x, y, z) \}, \quad S = \{ \emptyset, \{ w, x \}, \{ w, y \}, \{ w, z \} \} \), \( F = \emptyset \) and \( L = \{ w, x, y, z \} \). Let \( E' = \{ w = f(z, x, y) \} \) and note that \( \theta' \in \text{imgu}(E \cup E') \) where \( \theta' = \{ w \mapsto f(z, x, y), x \mapsto z, y \mapsto z \} \). Thus \( E \cup E' \in \gamma_X^{SFL}(S', F', L') \) where \( S' = \{ \emptyset, \{ w, x, y, z \} \} \), \( F' = \emptyset \) and \( L' = \{ x, y, z \} \). Indeed, if \( S_x = \text{rel}(w, S) = \{ \{ w, x \}, \{ w, y \}, \{ w, z \} \} \) and \( S_t = \text{rel}(f(z, x, y), S) = \{ \{ w, x \}, \{ w, y \}, \{ w, z \} \} \) then \( (S'_w \cup S_t) \cap (S'_w \cup S'_r) = \{ \{ w, x \}, \{ w, y \}, \{ w, z \}, \{ w, x, y, z \} \} \), thus \( \text{amgu}_1((S, F, L), \)}
$w, f(z, x, y)$ yields a safe, though conservative, abstraction. Closure is required to construct the $\{w, x, y, z\}$ sharing group.

4 Decomposition of set-sharing

Filé (Filé, 1994) observes that different sharing and freeness abstractions can represent the same equations, that is, $\gamma_X(S_1, F) = \gamma_X(S_2, F)$ does not imply that $S_1 = S_2$. Therefore the relationship between $Sh \times Fr$ and the concrete domain is a Galois connection rather than an insertion. An insertion is constructed by using $F$ to decompose $S$ into a set of sharing abstractions $K_F(S)$ such that each $B \in K_F(S)$ does not include sharing groups that definitely arise from different computational paths. The following definition and lemma from (Filé, 1994) formalises this decomposition, henceforth referred to as the Filé decomposition.

**Definition 4.1**

The map $K_F(S) : Sh \to \wp(Sh)$ is defined by:

$$K_F(S) = \left\{ B \bigg| \forall B \subseteq S \land F \subseteq \text{var}(B) \land \forall G_1, G_2 \in B, (G_1 \neq G_2 \rightarrow G_1 \cap G_2 \cap F = \emptyset) \right\}$$

**Lemma 4.1**

$$\gamma_X(S, F) = \cup \{ \gamma_X(B, F) \mid B \in K_F(S) \}.$$

Using the above, abstract unification can be refined to $\cup \{\text{amgu}((B, F, L), s, t) \mid B \in K_F(S)\}$. Abstract unification computed in this way does not merge sharing groups arising from different computational paths, and thereby improves precision. Calculating $K_F(S)$ is expensive and the number of calls to $\text{amgu}$ is $|K_F(S)|$ (which is potentially exponential in $|S|$). However, this tactic suggests lightweight refinements to closure ($\ast$) and pair-wise union ($\uplus$) that recover some precision at little cost. Since two distinct sharing groups which contain a common free variable must arise from different computational paths, they cannot describe the same equation and therefore need not be combined. Definition 4.2 details the refined abstract unification algorithm and theorem 4.1 builds on lemma 4.2 to establish correctness.

**Definition 4.2 (Abstract unification 2)**

Abstract unification $\text{amgu}_2((S, F, L), s, t) = (S', F', L')$ is defined:

$$S'' = \left\{ (S''_a \uplus_F S'_a) \cap (S''_s \uplus_F S'_s) \right\}$$

if $\chi(s, S, L) = \chi(t, S, L) = 1$

if $\chi(s, S, L) = 1$

if $\chi(t, S, L) = 1$

otherwise

$$S_1 \uplus_F S_2 = \bigcup \{ G_1 \cup G_2 \mid G_1 \in S_1 \land G_2 \in S_2 \land G_1 \neq G_2 \rightarrow G_1 \cap G_2 \cap F = \emptyset \}$$

$$S^{*r} = \bigcap \{ S' \mid S \subseteq S' \land \forall G_1, G_2 \in S', G_1 \cap G_2 \cap F = \emptyset \rightarrow G_1 \cup G_2 \in S' \}$$

where $S', S_s, S_1, F'$ and $L'$ are defined as in definition 3.2.

Notice that the use of freeness is completely absorbed into $*_F$ and $\uplus_F$. The following lemma demonstrates that $\uplus_F$ and $*_F$ coincide with $\uplus$ and $\ast$ for each element of the
FILE decomposition. The correctness of abstract unification (AMGU) follows from this result.

**Lemma 4.2**

1. If \( B \in K_F(S) \) and \( R \subseteq B \), then \( R^* = R^* F \).
2. If \( B \in K_F(S) \) and \( R_1, R_2 \subseteq B \), then \( R_1 \cup R_2 = R_1 \cup F R_2, R_1^* \cup R_2 = R_1^* \cup F R_2, R_1 \cup R_2^* = R_1 \cup F R_2^* \) and \( R_1^* \cup R_2^* = R_1^* \cup F R_2^* \).

**Proof**

1. Proof by induction.
   
   (a) Suppose \( R = \emptyset \). Then \( R^* = \emptyset = R^* F \).
   
   (b) Suppose \( R = \{G\} \cup R' \). By the hypothesis, \( R^* = R^* F \). Since \( R \subseteq B \), then for all \( G' \in R' \), \( G' \cap G \cap F = \emptyset \). Hence \( R^* = R^* F \).

2. (a) To show \( R_1 \cup R_2 = R_1 \cup F R_2 \). Let \( G_1 \in R_1 \). If \( G_1 \cap G_2 \cap F \neq \emptyset \) then \( G_1 = G_2 \). Hence \( G_1 \cup G_2 \in R_1 \cup F R_2 \).

   (b) To show \( R_1^* \cup R_2 = R_1^* \cup F R_2 \). Let \( G_1 \in R_1^* \) and \( G_2 \in R_2 \). Then \( G_1 = \cup Q_1 \) for some \( Q_1 \subseteq R_1 \). Put \( Y = G_1 \cap G_2 \cap F, Q_1' = \{G \in Q_1 \mid G \cap Y = \emptyset \} \) and \( Q_1'' = Q_1 \setminus Q_1' \). Observe that \( |Q_1'| \leq 1 \) and \( |Q_1''| \subseteq \{G_2\} \). Thus \( G_1 \cup G_2 = (\cup Q_1') \cup G_2 \). Since \( (\cup Q_1') \cap G_2 \cap F = \emptyset \) it follows that \( G_1 \cup G_2 \in R_1^* \cup F R_2 \).

   (c) To show \( R_1 \cup R_2^* = R_1 \cup F R_2^* \). Analogous to the previous case.

   (d) To show \( R_1^* \cup R_2 = R_1^* \cup F R_2 \). Let \( G_1 \in R_1^* \) and \( G_2 \in R_2^* \). Then \( G_i = \cup Q_i \) for some \( Q_i \subseteq R_i \). Put \( Y = G_1 \cap G_2 \cap F, Q_i' = \{G \in Q_i \mid G \cap Y = \emptyset \} \) and \( Q_i'' = Q_i \setminus Q_i' \). Observe that \( |Q_i'| \leq 1 \).

   i. Suppose \( |Q_i'| = 0 \) or \( |Q_i''| = 0 \). Then \( G_1 \cap G_2 \cap F = \emptyset \), hence \( G_1 \cup G_2 \in R_1^* \cup F R_2^* \).

   ii. Suppose \( |Q_i'| = |Q_i''| = 1 \). Hence \( Q_i' = G_2 \), thus \( G_1 \cup G_2 = G_1 \cup (\cup Q_2) \).

   Since \( G_1 \cap (\cup Q_2) \cap F = \emptyset \) it follows that \( G_1 \cup G_2 \in R_1^* \cup F R_2^* \).

\( \square \)

**Theorem 4.1 (Correctness of abstract unification 2)**

Let \( E \in \gamma_X^{FL}(\langle S, F, L \rangle), \text{var}(s) \cap \text{var}(t) \subseteq X \) and \( \text{AMGU}_2(\langle S, F, L \rangle, s, t) = \langle S', F', L' \rangle \).

Then \( E \cup \{s = t\} \in \gamma_X^{FL}(\langle S', F', L' \rangle) \).

**Proof**

Observe \( E \in \gamma_X^{FL}(\langle S, F \rangle) \) and \( E \in \gamma_X^L(L) \). By lemma 4.1, there exists \( B \in K_F(S) \) such that \( E \in \gamma_X^{FL}(\langle B, F \rangle) \), hence \( E \in \gamma_X^{FL}(\langle B, F, L \rangle) \). Observe that if \( s \in F \) then \( S^* = S \) (and likewise for \( t \in F \)) and hence by lemma 4.2, \( \text{AMGU}_1(\langle B, F, L \rangle, s, t) = \text{AMGU}_2(\langle B, F, L \rangle, s, t) \). By theorem 3.1, \( E \cup \{s = t\} \in \gamma_X^{FL}(\text{AMGU}_2(\langle B, F, L \rangle, s, t)) = \gamma_X^{FL}(\text{AMGU}_2(\langle B, F, L \rangle, s, t)) \), thus \( E \cup \{s = t\} \in \gamma_X^{FL}(\text{AMGU}_2(\langle S, F, L \rangle, s, t)) \).

\( \square \)

The proof explains why the standard freeness tactic is a specialised version of the FILE decomposition.

This refinement is only worthwhile if redundant sharing groups are introduced in analysis. Although it can be shown that projection and join do not introduce redundancy, the following example indicates that redundant sharing groups can arise in abstract unification (AMGU) and that the refined abstract unification (AMGU) can avoid some of these redundant sharing groups.
Example 4.1
Let $X = \{x, y, z\}$, $S = \{\emptyset, \{x, y\}, \{y, z\}\}$, $F = \{y\}$ and $L = \{y\}$. Suppose $s = x$ and $t = z$. Then $S_s = \{\{x, y\}\}$ and $S_t = \{\{x, z\}\}$ so that $amu_1(\langle S, F, L, x, z \rangle) = \langle \emptyset, \{x, y\}, \emptyset, \emptyset, \emptyset \rangle$. However $S_s^{\star_F} = \{\{x, y\}\}$ and $S_t^{\star_F} = \{\{x, z\}\}$ and in particular $S_s^{\star_F} \cup_F S_t^{\star_F} = \emptyset$ so that $amu_2(\langle S, F, L, x, z \rangle) = \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$.

The following example demonstrates that $amu_2$ is not as precise as the full Fileé decomposition.

Example 4.2
Let $X = \{x, y, z\}$, $S = \{\emptyset, \{x\}, \{z\}, \{x, y\}, \{y, z\}\}$, $F = \{x, y, z\}$ and $L = \{x, y, z\}$. Suppose $s = x$ and $t = z$. Then $S_s = \{\{x\}, \{x, y\}\}$ and $S_t = \{\{z\}, \{y, z\}\}$, hence $S_s^{\star_F} = S_s$ and $S_t^{\star_F} = S_t$. Thus $S_s^{\star_F} \cup_F S_t^{\star_F} = \{\emptyset, \{x\}, \{x, y\}, \{x, z\}\}$. It follows that $amu_2(\langle S, F, L, x, z \rangle) = \langle \emptyset, \emptyset, \emptyset, \emptyset, \emptyset \rangle$. However, the Fileé decomposition gives $K_F(S) = \{S_1, S_2, S_3, S_4\}$ where $S_1 = \{\{x\}, \{x, y\}\}$, $S_2 = \emptyset, \{x\}, \{y, z\}\}$, $S_3 = \{\{x, y\}, \{x, z\}\}$ and $S_4 = \emptyset, \{x, z\}, \{y, z\}\}$. Moreover, $amu_1(\langle S, F, L, x, z \rangle) = \langle \emptyset, \{x, y\}, \{x, z\}\}, \emptyset, \emptyset \rangle$. Since $S_1 \subseteq S_2$ and $S_3 \subseteq S_1$, the Fileé leads to the sharing abstraction $\emptyset, \emptyset, \emptyset, \emptyset, \emptyset\}$, which is more precise.

5 Pruning of set-sharing

Pruning sharing groups is advantageous for efficiency and precision. By reducing the size of an abstraction, abstract unification works on smaller objects and is therefore faster, even if no precision is gained. Of course, the benefit of pruning for efficiency needs to outweigh its cost.

5.1 Pruning with freeness via groundness

Surprisingly, combined sharing and freeness information can improve groundness propagation and sharing even for rational tree unification. For example, the equation $x = f(y, z)$ can be abstracted by $(x \leftrightarrow z) \land (x \leftrightarrow y)$ if $x$ and $y$ are free variables that share. This is because, in this circumstance, finite tree unification fails for $x = f(y, z)$ whereas rational tree unification binds $x$ and $y$ to $f(f(\ldots, z), z)$. Abstract unification can use the freeness of variables in the equation to extract hidden groundness information (for distinct computational paths) and thereby prune sharing groups and improve precision. The proof of theorem 5.1 again uses the Fileé decomposition.

Definition 5.1 (Abstract unification 3)
Abstract unification $amu_3(\langle S, F, L, s, t \rangle) = \langle S', F', L' \rangle$ is defined:

$$S' = (S \setminus (S_s \cup S_t)) \cup \begin{cases} \bigcup_{G \in S_s} trim_X(s \leftrightarrow Y, \{G\} \cup F S_t) & \text{if } s \in F \land t \notin U \\ \bigcup_{G \in S_t} trim_X(Z \leftrightarrow t, S_s \cup F \{G\}) & \text{if } t \notin F \land s \notin U \\ S'' & \text{otherwise} \end{cases}$$

where $Y = \text{var}(t) \setminus (G \cap F)$, $Z = \text{var}(s) \setminus (G \cap F)$, $S_s, S_t, S''$, $F'$ and $L'$ are defined as in definition 4.2.
Three Optimisations for Sharing

Theorem 5.1 (Correctness of abstract unification 3)

Let \( E \in \gamma_X^{SF}(⟨S,F,L⟩) \), \( \text{var}(s) \cup \text{var}(t) \subseteq X \) and \( \text{amgu}_3(⟨S,F,L⟩, s, t) = ⟨S', F', L'⟩ \). Then \( E \cup \{s = t\} \in \gamma_X^{SF}(⟨S', F', L'⟩) \).

Proof

Suppose \( s \in F \). By lemma 4.1, there exists \( B \in K_F(S) \) such that \( E \in \gamma_X^{FL}(⟨B,F⟩) \) and by theorem 4.1, \( E \cup \{s = t\} \in \gamma_X^{h}(B') \) where \( B' = (B \setminus (B_s \cup B_t)) \cup (B_t \cup F \setminus B_t) \), \( B_s = \text{rel}(s,B) \) and \( B_t = \text{rel}(t,B) \). Let \( \theta \in \text{mgu}(E) \). Since \( s \in F \), \( \theta(s) = x \) for some \( x \in U \). Furthermore, \( s \in G \) for all \( G \in S_s \). Since \( s \in F \), \( B_s = \{G\} \) where \( G = \text{occ}(\theta,x) \). Observe that \( \theta(y) = x \) for all \( y \in G \cap F \). Since \( t \not\in U \), \( \theta(t) \not\in U \), hence \( \alpha_X^{\text{pos}}(\{\theta(s) = \theta(t)\}) \models s \leftrightarrow Y \). Moreover, \( \text{mgu}(E \cup \{s = t\}) = \text{mgu}(\text{eqn}(\theta) \cup \{s = t\}) = \text{mgu}(\text{eqn}(\theta) \cup \{\theta(s) = \theta(t)\}) \). Thus \( \alpha_X^{\text{pos}}(E \cup \{s = t\}) \models \alpha_X^{\text{pos}}(\{\theta(s) = \theta(t)\}) \) \models s \leftrightarrow Y \). The result follows by corollary 2.1. The \( t \in F \) case is analogous and the otherwise case follows immediately from theorem 4.1. \( \Box \)

The following example illustrates the gain of precision. Note that even the Filé decomposition cannot match this level of precision.

Example 5.1

Let \( X = \{x,y,z\} \), \( S = \{\emptyset, \{x,y\}, \{y\}, \{z\}\} \), \( F = \{x,y\} \) and \( L = \{x,y\} \). Suppose \( s = x \) and \( t = f(y,z) \). Consider the Filé decomposition, that is, \( K_F(S) = \{S_1, S_2, S_3, S_4\} \) where \( S_1 = \{\{x,y\}\} \), \( S_2 = \{\emptyset, \{x,y\}\} \), \( S_3 = \{\{x,y\}, \{z\}\} \), \( S_4 = \{\emptyset, \{x,y\}, \{x,y,z\}\} \). Then \( \text{amgu}_3(⟨S_1,F,L⟩, x, f(y,z)) = ⟨S', \emptyset, \emptyset⟩ \) where \( S' = \{\emptyset, \{x,y,z\}\} \). Since \( S_i \subseteq S_4 \) for all \( i \in \{1,2,3\} \), the decomposition results in the sharing abstraction \( S' \). Moreover, \( \text{amgu}_3(⟨S,F,L⟩, x, f(y,z)) = ⟨S', \emptyset, \emptyset⟩ \). However, \( \text{amgu}_3(⟨S,F,L⟩, x, f(y,z)) = ⟨\text{trim}_X(x \leftrightarrow z, S'), \emptyset, \emptyset⟩ = ⟨\emptyset, \{x,y,z\}, \emptyset, \emptyset⟩ \) which is more precise.

Example 5.2

Let \( X = \{x,y,z\} \), \( S = \{\emptyset, \{x,y\}, \{y,z\}\} \), \( F = \{y\} \) and \( L = \{y\} \). Suppose \( s = x \) and \( t = z \). Since \( x, z \in U \), \( \text{amgu}_3(⟨S,F,L⟩, x, z) = \text{amgu}_2(⟨S,F,L⟩, x, z) = ⟨\emptyset, \{x,y,z\}, \emptyset, \emptyset⟩ \) whereas the Filé decomposition produces \( ⟨\emptyset, \emptyset, \{x,y,z\}⟩ \) (see example 4.1).

Example 5.2 shows that \( \text{amgu}_3 \) is not uniformly more precise than the Filé decomposition, hence is sub-optimal. Nevertheless, this pruning tactic suggests that any optimal abstract unification algorithm for sharing, freeness and linearity, in the presence of groundness, will have to consider subtle interactions between the components.

5.2 Early pruning with groundness

Sharing abstractions can always be pruned by removing sharing groups which contain ground variables. Common practice is to schedule the solving of equations so as to first apply abstract unification to equations on ground terms (Langen, 1991). Moreover, (Muthukumar & Hermenegildo, 1992) details a queueing/dequeueing mechanism for maximally propagating groundness among systems of equations.
This can involve repeated searching. This section proposes a revision of this tactic that applies groundness to the complete set of equations (without repeated searching) and then uses the resulting groundness information to prune sharing before abstract unification is applied. The gain is that searching and scheduling are no longer required (the mechanism is single pass) and that the disjoint groundness information captured by Pos can be exploited so that abstract unification can potentially operate on smaller abstractions. Observe that groundness information will normally be tracked by Pos anyway, thus the computational overhead is negligible. To formulate this strategy, abstract unification is lifted to sets of equations as follows:

**Definition 5.2**

The map \( \text{amgu}(T, E) = \{ T' \mid \langle T, E \rangle \leadsto^* \langle T', \emptyset \rangle \} \) is defined by the least relation \( \leadsto \subseteq (\text{Share}_X \times F_{\text{fr}} \times \text{Lin}_X)^2 \) such that \( \langle T, \{ s = t \} \cup E \rangle \leadsto \langle \text{amgu}(T, s, t), E \rangle \).

The following theorem states correctness of the early pruning using groundness for \( \text{amgu}_1, \text{amgu}_2 \) and \( \text{amgu}_3 \).

**Theorem 5.2**

Let \( E \in \gamma^{\text{Pos}}_X (f) \cap \gamma^F (S, F, L) \), \( E \cup E' \in \gamma^{\text{Pos}}_X (f') \), \( Y = \{ y \in X \mid f' \vdash y \} \), \( S' = \text{trim}_X (f \wedge Y, S) \), \( f' = F \setminus \text{var}(\text{rel}(Y, S)) \), \( L' = L \cup Y \), \( \text{var}(E) \subseteq X \) and \( T' \in \text{amgu}_3 (S', F', L', E) \). Then \( E \cup E' \in \gamma^{\text{FL}}_X (T') \).

**Proof**

Let \( \theta \in \text{imgu}(E) \) and \( \theta' \in \text{imgu}(E \cup E') \). Since \( \theta \in \text{unify}(E) \), \( \theta \leq \theta' \) and there exists \( \zeta \in \text{Sub} \) such that \( \zeta \circ \theta = \theta' \). Since \( \theta' \in \text{unify}(E') \), \( \zeta \in \text{unify}(E'(E')) \) so that \( \text{mgu}(\theta(E')) \neq \emptyset \). Let \( \delta \in \text{imgu}(\theta(E')) = \text{imgu}(\theta^\infty(E')) \). By part 2 of lemma 2.2, \( \delta \circ \theta = \delta \circ \theta^\infty \in \text{mgu}(\text{eqn}(\theta) \cup E') = \text{mgu}(E \cup E') \). Thus there exists \( \rho \in \text{Rename} \) such that \( \rho \circ \delta \circ \theta = \theta' \). Now \( \text{var}(\theta'(y)) = \emptyset \) for all \( y \in Y \), hence \( \text{var}(\delta \circ \theta(y)) = \emptyset \) for all \( y \in Y \). Put \( Z = \{ \text{var}(\theta'(y)) \mid y \in Y \}, \phi = \exists Z \delta \) and \( \psi = \exists Z \delta \). Let \( z \in Z \). Then there exists \( y \in Y \) such that \( z \in \text{var}(\theta'(y)) \). But \( \text{var}(\delta \circ \theta(y)) = \emptyset \), hence \( \text{rng}(\delta) = \emptyset \) and \( \delta = \psi \circ \phi \). Thus \( \psi \circ \phi \in \text{mgu}(E'(E')) \) and by lemma 2.2 part 3, \( \exists (\text{dom} \circ \phi \setminus \text{rng}(\phi)), \psi \in \text{mgu}(\phi \circ \theta(E')) \). Furthermore, \( \exists (\text{dom} \circ \phi \setminus \text{rng}(\phi)), \psi = \psi \) hence \( \psi \in \text{mgu}(\phi \circ \theta(E')) \). Since \( \phi \circ \theta \) is idempotent, \( \psi \in \text{mgu}(\phi \circ \theta(E')) \).

To show \( \text{eqn}(\phi \circ \theta) \in \gamma^\infty_X (\text{trim}(f \wedge Y, S)) \), let \( u \in U \). If \( \text{occ}(\phi \circ \theta, u) = \emptyset \) then \( \text{occ}(\phi \circ \theta, u) \cap X \in S \) trivially. If \( \text{occ}(\phi \circ \theta, u) \neq \emptyset \) then \( \text{occ}(\phi \circ \theta, u) = \text{occ}(\theta, u) \) since \( \text{rng}(\phi) = \emptyset \). Thus \( \text{occ}(\phi \circ \theta) \cap X \in S \). Therefore \( \text{eqn}(\phi \circ \theta) \in \gamma^\infty_X (S) \). By lemma 2.2, part 2, \( \delta \circ \theta \in \text{mgu}(E \cup \text{eqn}(\theta)) \). But \( \theta' \in \text{mgu}(E \cup \text{eqn}(\theta)) \) and therefore there exists \( \rho \in \text{Rename} \) such that \( \rho \circ \delta \circ \theta = \theta' \). Thus \( \text{eqn}(\phi \circ \theta) \in \gamma^\infty_X (S) \). By corollary 2.1, \( \text{eqn}(\phi \circ \theta) \in \gamma^\infty_X (\text{trim}(f \wedge Y, S)) \).

To show \( \phi \circ \theta(x) \in U \) for all \( x \in F' \). Let \( x \in F \) and \( x \notin \text{var}(\text{rel}(Y, S)) \). Since \( x \notin \text{var}(\text{rel}(Y, S)) \), \( x \notin \text{occ}(\theta, u) \cap X \) or \( y \notin \text{occ}(\theta, u) \cap X \) for all \( u \in U \) and \( y \in Y \).
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Since \( x \in X \) and \( Y \subseteq X \), \( \text{var}(\theta(x)) \cap \text{var}(\theta(y)) = \emptyset \) for all \( y \in Y \). Hence \( \theta(x) \notin Z \), thus \( \theta(x) \notin \text{dom}(\phi) \), therefore \( \phi \circ \theta(x) \in U \). Thus \( \text{eqn}(\phi \circ \theta) \in \gamma_X^F(F') \).

To show \( \chi(\phi \circ \theta(x)) \leq 1 \) for all \( x \in L' \). Since \( \text{rng}(\phi) = \emptyset \), \( \chi(\phi \circ \theta(x)) \leq 1 \) for all \( x \in L \). Moreover, \( \alpha_{\text{Pos}}(\phi \circ \theta) \models Y \) and therefore \( \chi(\phi \circ \theta(x)) \leq 1 \) for all \( x \in Y \). Thus \( \text{eqn}(\phi \circ \theta) \in \gamma_X^\text{Pos}\{L', L'\} \). The result then follows by induction on \( E' \) and theorems 3.1, 4.1 and 5.1. □

The following example illustrates the computational advantages of early pruning.

Example 5.3
Let \( X = \{u, v, x, y\} \), \( S = \{\emptyset, \{x\}, \{y\}, \{u\}, \{v\}\} \), \( F = \emptyset \), \( L = \emptyset \) and \( f = x \lor y \). Let \( E' = \{x = f(u, v), x = y\} \) so that \( f' = (x \lor y) \land (x \leftrightarrow (u \lor v)) \land (x \leftrightarrow y) = x \land y \land u \land v \). Then \( Y = \{x, y, u, v\} \) so that \( f \land Y = x \land y \land u \land v \) and \( S' = \text{trim}_X(f \land Y, S) = \{\emptyset\} \). Hence \( \text{amgu}_3((S, F, L), E') \) reduces to \( \text{amgu}_3((S', F, L), E') = \langle \{0\}, 0, 0 \rangle \). Without this tactic, no equation of \( E' \) will possess a ground argument and both calls to \( \text{amgu}_3 \) will involve non-trivial sharing group manipulation.

6 Conclusion

This paper has given correctness proofs for sharing analysis with freeness and linearity which hold in the presence of rational trees. The abstract unification algorithms are themselves novel – incorporating optimisations for both precision and efficiency. Specifically, the independence check which can prevent linearity from being exploited has been removed. In addition, refined closure and pair-wise union operations have been derived from the Filé decomposition. A further precision optimisation has been presented which exploits an interaction between sharing, freeness and groundness, which shows the subtlety that an optimal algorithm will need to address. These optimisations have been chosen to balance precision against efficiency whilst not changing the underlying representation of the abstract domains. They are ordered according to their anticipated degree of usefulness. This work provides the implementor with a suite of new optimisations for abstract unification algorithms for sharing, freeness and linearity.

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References


