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Abstract

Venn diagrams and Euler circles have long been used to express constraints on sets and their relationships with other sets. However, these notations can get very cluttered when we consider many closed curves or contours. In order to reduce this clutter, and to focus attention within the diagram appropriately, the notion of a projected contour, or projection, is introduced. Informally, a projected contour is a contour that describes a set of elements limited to a certain context. Through a series of examples, we develop a formal semantics of projections and discuss the issues involved in introducing these.

Keywords Visual formalisms, diagrammatic notations

1. Introduction

Diagrammatic notations involving circles and other closed curves, which we will call contours, have been in use for the representation of classical syllogisms since at least the Middle Ages [11]. In the middle of the 18th century, the Swiss mathematician Leonhard Euler introduced the notation we now call Euler circles (or Euler diagrams) [1] to illustrate relations between sets. This notation uses the topological properties of enclosure, exclusion and intersection to represent the set-theoretic notions of containment, disjointness, and intersection, respectively. The 19th century logician John Venn [16] modified this notation to represent logical propositions. In Venn diagrams all contours must intersect. Moreover, for each non-empty subset of the contours, there must be a single connected region of the diagram, such that the contours in this subset intersect at exactly that region. Shading is then used to show that a particular region represents the empty set.

An indication of the popularity and intuitiveness of Venn and Euler diagrams is the fact that they are used in elementary schools for teaching set theory as an introduction to mathematics. However, as we will see next, both notations have their limitations.

Venn diagrams are expressive as a visual notation for writing constraints on sets and their relationships with other sets, but difficult to draw because all possible intersections have to be drawn and then some regions shaded. Although it may first seem impossible to draw a Venn diagram of more than three contours, there are in fact many ways of doing so. Venn himself developed a scheme for drawing such a diagram for any number of diagrams. Yet another such scheme is due to More [12]. Since then, there was a large body of research on the drawing of Venn diagrams, their topological properties, etc. The interested reader is referred to e.g., [5, 6] for more information on the topic, which involves some beautiful mathematics, which results in some very aesthetically pleasing drawing. For example, Figure 1 shows a symmetrical Venn diagram of four contours, while Figure 2 is the only simple symmetric Venn diagram of five contours.

Figure 1 - A simple and symmetrical Venn diagram of four contours

Figure 2 - The simple symmetrical Venn diagram of five contours

Examining these two figures, it is clear why it is so rare to see Venn diagrams of four or more contours used in visual formalisms. Most regions require a bit of pondering before it is clear which are the contours that contain it. As shown in Figure 3, the situation worsens
with the increase in the number of curves.

Figure 3 - Adelaide, a symmetrical Venn diagram of seven contours

On the other hand, Euler circles are intuitive and easier to draw, but are not as expressive as Venn diagrams because they lack provisions for shading. It is therefore the case that an informal hybrid of the two notations that is used for teaching purposes. We use the term Venn-Euler diagrams for the notation obtained by a relaxation of the demand that all curves in Venn-diagrams must intersect or conversely, by introducing shading into Euler diagrams. Gil, Howse and Kent [2] provided formalism for Venn-Euler diagrams as part of the more general spider diagrams notation.

Rather informally, we use the following terminology:

A contour is a simple closed plane curve. A boundary contour is not contained in and does not intersect with any other contour. A district (or basic region) is the set of points in the plane enclosed by a contour. A region is defined as follows: any district is a region; if \( r_1 \) and \( r_2 \) are regions, then the union, intersection, or difference, of \( r_1 \) and \( r_2 \) (defined as sets of points of the plane) are regions provided these are non-empty. A zone (or minimal region) is a region having no other region contained within it. Contours and regions denote sets.

Every region is a union of zones. A region is shaded if each of its component zones is shaded. A shaded region denotes the empty set.

Figure 4 - A Venn-Euler diagram

The Venn-Euler diagram \( D \) in Figure 4 has four non-boundary contours \( A, B, C, D \) and the boundary is omitted. Its interpretation includes \( D \subseteq (C - B) - A \) and \( A \cap B \cap C = \emptyset \).

However, even Venn-Euler diagrams can get very cluttered when many contours are involved. The issue of clutter becomes even more crucial when such diagrams are used as foundation for other, more advanced visual formalism. A case in point is the constraint diagrams notation [3, 10] which uses arrows and other diagrammatic elements to model constraints not only on simple sets, but also on mathematical relations. Constraint diagrams can be used in conjunction with the Unified Modeling Language (UML) [14], which has become the Object Management Group’s (OMG) standard for object-oriented modelling notations, and the Object Constraint Language (OCL) [17], a textual notation for expressing constraints that is part of UML.

In order to reduce this clutter, and to focus attention within the diagram appropriately, the notion of a projected contour, or projection, can be used as an addition to the Venn-Euler based notation. In Figure 5 for example, the set Women is projected into the set of employees. The projected contour represents the set of women employees; it doesn’t say that all women are employees.

Figure 5 - Example projection

As a slightly more interesting example, consider the constraint diagram in Figure 6. This diagram states (among other things) that the sets Kings and Queens are disjoint, that the set Kings has an element named Henry VIII, that all women that Henry VIII married were queens and that there was at least one queen he married who was executed. The dotted contour is a projection of the set Executed; it is the set of all executed people projected into the set of people married to Henry VIII, that is, it gives all the queens who were married to Henry VIII and executed.

Figure 6 - A constraint diagram with projection

Thus, a projection, denoted by a dotted contour can be thought of as a notation for intersection. In the example, the inner most circle labelled "Executed" denotes the intersection of the set Executed with the set of women who were married to Henry VIII. The notation is intuitive.
and more concise than the alternative, which would have been drawing a large ellipse that intersects the Queens contour. As shown in Figure 7, this ellipse must also intersect with the Kings contour, or otherwise the diagram would imply that no kings were ever executed.

Figure 7 - The constraint diagram of Figure 6 redrawn without projections.

Moreover, Figure 6 does not specify whether Henry VIII was executed or not. Eliminating the projections from the figure requires delving into a history book and explicitly specifying this point as shown in Figure 7. Alternatively, one could use what is known as a spider to refrain from stating whether or not Henry VIII was executed. As shown in Figure 8, this alternative is even more cumbersome, and will probably draw the attention of the reader to an irrelevant point.

Figure 8 - Using a spider notation to preserve the semantics of Figure 6 while eliminating projections from it.

There are non-trivial issues in dealing with this seemingly neat idea. For example, the notation must have a well-defined semantics when a projection intersects with a contour, and not only when it is disjoint to it, or contained in it. A diagram may contain more than one projection that may interact in subtle ways. Moreover, the same set may be projected several times into the same diagrams, and these projections might interact as well.

The projection concept was first suggested as part of the constraint diagram language. However, these complicating matters were not dealt with. Instead, there was a tacit understanding that only “simple” use of projections, which avoided these issues, was allowed. The work reported in here represents the first attempt to systematically deal with the semantics of projections.

The discourse of the presentation is structured as follows: Section 2 briefly sketches the formal semantics of Venn-Euler diagrams. Section 3 gives an informal definition of projections. The formal semantics is given in Section 4. In Section 5 we consider interacting projections and give a further syntactic constraint to the notation. Finally, Section 6 gives a conclusion and discusses related work.

2. Semantics of Venn-Euler Diagrams

In this section we sketch the main definitions used in giving semantics to a Venn-Euler diagram. A Venn-Euler diagram is a finite collection of contours and a list of shaded zones, where each zone is a non-empty subset of the contours. Exactly one of the contours must be denoted as boundary contour. (We frequently omit the boundary contour from drawings.) For any diagram $D$, we use $C = C(D)$, $R = R(D)$, $Z = Z(D)$, and $Z^* = Z^*(D)$ to denote the sets of contours, regions, zones, and shaded zones of $D$, respectively.

The semantics of a Venn-Euler diagram $D$ is given in terms of the semantic function $\Psi : C \to \mathcal{P}U$, where $U$ is a given universal set of $D$ and $\mathcal{P}U$ denotes the power set of $U$. Contours are interpreted as subsets of $U$, and the boundary contour is interpreted as $U$.

A zone is uniquely defined by the contours containing it and the contours not containing it; its interpretation is the intersection of the sets denoted by the contours containing it and the complements of the sets denoted by those contours not containing it. We extend the domain of $\Psi$ to interpret regions as subsets of $U$. First define $\Psi : Z \to \mathcal{P}U$ by

$$\Psi(z) = \bigcap_{c \in C^+(z)} \Psi(c) \cap \bigcap_{c \in C^-(z)} \overline{\Psi(c)}$$

where $C^+(z)$ is the set of contours containing the zone $z$, $C^-(z)$ is the set of contours not containing $z$ and $\overline{\Psi(c)} = U - \Psi(c)$, the complement of $\Psi(c)$. Since any region is a union of zones, we may define $\Psi : R \to \mathcal{P}U$ by

$$\Psi(r) = \bigcup_{z \in Z(r)} \Psi(z)$$

where, for any region $r$, $Z(r)$ is the set of zones contained in $r$.

The semantics of a diagram $D$ is the conjunction of the following conditions.

**Plane Tiling Condition:** All elements fall within sets denoted by zones:

$$\bigcup_{z \in Z} \Psi(z) = U$$
Shading Condition: The set denoted by a shaded zone is empty

\[ \bigwedge_{z \in Z} \Psi(z) = \emptyset \]

3. Projections

Sometimes it is necessary to show a set in a certain context. Intersection can be used for just this purpose: an intersection of \( A \) and \( B \) shows the set \( A \) in the context of \( B \) and vice-versa. However, intersections also introduce regions that may not be of interest. Projections are equivalent to taking the intersection of sets, except that they introduce fewer regions, with the effect that regions which are not the focus of attention are not shown, resulting in less cluttered diagrams.

A projection is a contour, which is used to denote an intersection of a set with a "context". By convention, we use dashed iconic representation to make the distinction between projections and other contours.

A determining label, denoted by \( \lambda(p) \), must be associated with any projection \( p \). This label is used to denote the set which is being projected. The convention is that determining labels are rendered within parenthesis when drawn in a diagram. A projection can also have a contour label.

Definition 1 The context of a projection \( p \), denoted \( \kappa(p) \), is the smallest region, defined in terms of non-projected contours, that contains the district of \( p \).

The set denoted by the context of a projection is calculated from the sets denoted by non-projected contours. A projection \( p \) denotes the set obtained by intersecting the set denoted by its determining label \( \lambda(p) \) with the set denoted by its context \( \kappa(p) \).

Figure 9 shows a simple example. The dashed contour labelled \( X \) denotes the set obtained by "projecting" the set \( A \) onto the context \( D - B \), i.e., \( X = A \cap (D - B) \).

Figure 9 - Simple projection

The same semantics could have been obtained by using More's algorithm [12] to draw the Venn diagram with four contours, as in Figure 10, in which \( X = X_1 \cup X_2 = A \cap (D - B) \), where \( X_1 \) and \( X_2 \) denote the zones in which the labels appear. The simplicity of Figure 3, when compared to that of Figure 4, is self-evident.

Figure 10 - Semantics of Figure 9

Thus, a projection gives another way of showing the intersection of sets. This gives a clue to its value, given the notorious difficulty of showing the intersection of more than three sets on a Venn diagram: Figure 11 shows how all the regions obtained by intersecting six sets can be obtained using projections. This is an extreme case. More often than not, one is only interested in some of the intersections and not the others: projections provide the freedom to show only those intersections of interest.

Figure 11 - Six sets

4. Semantics of Projections

Let \( P \) be the set of all projections and \( L \) be the set of all determining labels. We extend the domain of the semantic function \( \Psi \) to interpret projections and determining labels as subsets of \( U \):

\[ \Psi : P \rightarrow \mathcal{P}U, \Psi : L \rightarrow \mathcal{P}U. \]

Let \( p \) be a projection with determining label \( \lambda(p) \) and context \( \kappa(p) \). Then we have:

\[ \Psi(p) = \Psi(\lambda(p)) \cap \Psi(\kappa(p)). \]

Also, we must update the Plane Tiling Condition so that projections are included with ordinary contours in defining zones. Let \( P(D) \) be the set of all projections in diagram \( D \). Then the semantics of a diagram \( D \) is the conjunction of the (updated) Plane Tiling Condition, the Shading Condition and the Projection Condition.
Projection Condition: The set denoted by a projection is the intersection of the set denoted by its determining label and the set denoted by its context:

\[ \bigwedge_{p \in P(D)} \Psi(p) = \Psi(\lambda(p)) \cap \Psi(\kappa(p)) \, . \]

5. Interacting Projections

In this section we consider examples of interacting projections and highlight some problems. The solution of these problems requires a syntactic constraint on projections. There are two main cases to consider: disjoint projections and intersecting projections. The case of projections contained in each other is similar to that of intersection projections.

5.1 Disjoint Projections

The intuitive interpretation of the diagram in Figure 12 is that \( X = A \cap B \) and \( Y = A \cap C \) and that \( A \cap B \) and \( A \cap C \) are disjoint.

![Figure 12 - Disjoint projections](image)

We will interpret \( \Psi(A) \) as \( A \), etc., for simplicity (and, of course, this will almost always be the intention of the producer of the diagram).

Now, \( \kappa(X) = A \) and \( \kappa(Y) = A \). The Projection Condition gives \( X = A \cap B \) and \( Y = A \cap C \) and the Plane Tiling Condition says that \( X \) and \( Y \) are disjoint, which is the intuitive interpretation. Note that this specifies that \( A \cap B \) and \( A \cap C \) are disjoint, so even though we are not explicitly showing the contours \( B \) and \( C \), we can still constrain the sets that they represent.

![Figure 13 - An illegal diagram](image)

Now, consider the diagram in Figure 13. We have \( \kappa(X) = A \) and \( \kappa(Y) = A \). The Projection Condition gives \( X = A \cap B \) and \( Y = A \cap B \) and the Plane Tiling Condition says that \( X \) and \( Y \) are disjoint. So, we have \( A \cap B = \emptyset \). We could have said the same thing by shading a single projection of \( B \) in \( A \) as in Figure 14.

![Figure 14 - Empty projection](image)

There are various extensions of Venn-Euler diagrams in which elements of sets can be shown diagrammatically; these include Peirce diagrams [7, 13, 15], spider diagrams [2, 8, 9] and constraint diagrams [3, 10]. If a diagram such as that in Figure 13 occurred in such a system, then the diagram could be made inconsistent by placing an element icon in one of the projections; the set represented by the projection would have at least one element by the presence of the icon, but would be empty by the above argument, a contradiction. In spider diagrams, for instance, all well-formed diagrams are consistent. Because of this and other similar problems, this situation is not allowed. We have the following syntactic constraint on projections:

*if two projections have the same context, then they must have different determining labels.*

More formally, the requirement is that for any two projections \( p_1 \) and \( p_2 \)

\[ \kappa(p_1) = \kappa(p_2) \Rightarrow \lambda(p_1) \neq \lambda(p_2) \, . \]

![Figure 15 - Another illegal diagram](image)

The diagram in Figure 15 is illegal because \( Y \) and \( Z \) have the same context and the same determining label.

![Figure 16 - Yet another illegal diagram](image)

In fact, this syntactic constraint is not strong enough. Consider the diagram in Figure 16. The context of \( X \) is \( A \), the context of \( Y \) is \( B \). The Projection Condition gives \( X = A \cap C \) and \( Y = B \cap C \) and the Plane Tiling Condition says that \( X \) and \( Y \) are disjoint. Hence, we have
\( A \cap B \cap C = \emptyset \), which, again, is problematic and could lead to inconsistent diagrams in some systems. The complete (syntactic) constraint that prevents these situations is the following:

**Projection Label Constraint:** if two projections have the same determining label, then they must have disjoint contexts.

Formally: let \( p_1 \) and \( p_2 \) be projections, then

\[ \lambda(p_1) = \lambda(p_2) \Rightarrow \kappa(p_1) \cap \kappa(p_2) = \emptyset. \]

**Theorem 1** Imposing the Projection Label Constraint does not limit expressiveness.

**Proof** Suppose that projections \( p_1 \) and \( p_2 \) do not satisfy the constraint:

\[ \lambda(p_1) = \lambda(p_2) = \lambda \quad \text{and} \quad \kappa(p_1) \cap \kappa(p_2) = \kappa \neq \emptyset \]

as illustrated in Figure 17.

![Figure 17 - Intersecting contexts](image)

Suppose that \( p_1 \) and \( p_2 \) are disjoint (if not, \( p_1 \) and \( p_2 \) should be replaced by a single projection). Then, the Plane Tiling Condition gives

\[ \Psi(p_1) \cap \Psi(p_2) = \emptyset \]

The Projection Condition gives

\[ \Psi(p_1) = \Psi(\lambda(p_1)) \cap \Psi(\kappa(p_1)) \]
\[ \Psi(p_2) = \Psi(\lambda(p_2)) \cap \Psi(\kappa(p_2)) \]

Therefore,

\[ \Psi(\lambda(p_1)) \cap \Psi(\kappa(p_1)) \cap \Psi(\lambda(p_2)) \cap \Psi(\kappa(p_2)) = \emptyset \]

hence,

\[ \Psi(\lambda) \cap \Psi(\kappa(p_1)) \cap \Psi(\kappa(p_2)) = \emptyset \]

i.e.,

\[ \Psi(\lambda) \cap \Psi(\kappa) = \emptyset. \]

So, \( p_1 \) and \( p_2 \) can be replaced by a single projection \( p \) whose intersection with \( \kappa \) is shaded. This is expressed by the legal diagram in Figure 18.

![Figure 18 - Legal version of Figure 17](image)

### 5.2 Containing and Intersecting Projections

Consider the diagram in Figure 19. The intuitive interpretation is that \( A \cap C \subseteq A \cap B \), or, in the context of \( A, C \) is a subset of \( B \).

![Figure 19 - A containing projection](image)

By the projection condition \( X = A \cap B \) and \( Y = A \cap C \). By the plane tiling condition \( Y \subseteq X \). So, \( A \cap C \subseteq A \cap B \), the intuitive interpretation. Note, again, that the sets \( B \) and \( C \) have been constrained. In fact, we can obtain precise expressions for \( X \) and \( Y \): \( X = A \cap B \) and \( Y = A \cap B \cap C \), because \( A \cap B \cap C = \emptyset \).

![Figure 20 - Intersecting projections](image)

In Figure 20, the two projections intersect in the same context. In this case there are no constraints on the sets \( B \) or \( C \) (or \( A \)).
In Figure 21 there is a more complicated intersection of projections. The context of both projections $X$ and $Y$ is $C \cup D$. So $X = (C \cup D) \cap A$ and $Y = (C \cup D) \cap B$. But in this case $X$ and $Y$ are constrained: $X \subseteq C \cup Y$ and $Y \subseteq D \cup X$. Putting all this together, we have

$$X \subseteq C \cup Y = C \cup (C \cup D) \cap B = C \cup D \cap B.$$ 

So,

$$X = (C \cup D) \cap A \cap (C \cup D \cap B) = A \cap (C \cup D \cap B)$$

and further,

$$(C \cup D) \cap A \cap C \cap D \cap B = \emptyset$$

hence,

$$A \cap D \cap \overline{C} \cap \overline{B} = \emptyset.$$ 

We can obtain similar expressions for $Y$ by symmetry. So we have precise expressions for $X$ and $Y$:

$$X = A \cap (C \cup B \cap D) \quad \text{and} \quad Y = B \cap (D \cup A \cap C)$$

with

$$A \cap D \cap \overline{C} \cap \overline{B} = \emptyset \quad \text{and} \quad B \cap C \cap \overline{D} \cap \overline{A} = \emptyset.$$ 

After much investigation of interacting projections, we conjecture that the only problematic cases occur when disjoint projections with the same determining label have intersecting contexts. This is the situation explicitly excluded by the Projection Label Constraint. We do not have a formal proof of this conjecture. In the case of spider diagrams, if this conjecture holds, then any spider diagram involving projections has a compliant model.

6. Conclusion and Related Work

We have introduced the concept of projections into Venn-Euler and related diagrammatic systems and have given them simple formal and intuitive semantics. Projections form an integral part of spider diagrams and constraint diagrams. Constraint diagrams have been used, in conjunction with UML, in the modelling of telecommunications systems for industry and projections have proved invaluable in allowing complicated invariants to be expressed with clarity. Formal semantics have been given for spider diagrams [2] and are currently being produced for constraint diagrams. Diagrammatic reasoning rules have been developed for spider diagrams [9] and these have been proved sound and complete for a large subset of the notation [8]. Reasoning rules involving projections are currently being developed.

There is an alternative possibility for the semantics of projections, which is to include projections in the context of a projection. This interpretation of interacting projections involves the solution of simultaneous set equations. In general, these equations have many solutions, but there is usually a “minimal” solution. This minimal solution frequently agrees with the intuitive interpretation. However, there are some cases in which the solution might give counter-intuitive semantics. In [4], this alternative semantics is developed; it is a more direct semantics than that given in this paper and there are fascinating mathematical intricacies in this alternative approach to the semantics.

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8. References


